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Volumetric imaging of fish locomotion

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Fish locomotion involves the coordinated use of multiple flexible fins, which can be manipulated to move fluid and maintain stability in a complex fluid environment. The use of traditional imaging techniques, such as planar Doppler velocimetry, has been limited due to the two-dimensional nature of these methods. The goal of this study is to develop a novel volumetric velocimetry system to capture three-dimensional instantaneous views of wake structures produced by freely swimming fishes.

Fishes use multiple flexible fins in order to move and maintain stability in a complex fluid environment. The development of a new volumetric velocimetry imaging system allows for the first time the instantaneous three-dimensional visualization of the vortex wake pattern produced by the symmetrical homocercal caudal fin of steadily swimming teleost fishes. This new technology provides a quantitative understanding of the motion of the fins, which is necessary for the development of more accurate models of fish locomotion.

**2. MATERIAL AND METHODS**

Four bluegill sunfish (Lepomis macrochirus; mean total length (TL) = 15.5 cm) and one cichlid fish (Pseudotropheus greshakei; TL = 12 cm) were used in this study. Each fish was placed into a 160 l recirculating flow tank with an 80 × 20 × 20 cm working area, trained to swim in the central flow, and illuminated by a 120 mJ dual-head pulse laser pulsed at a frequency of 7.25 Hz. The fluid downstream of the swimming bluegill was illuminated by a 120 mJ dual-head pulse laser pulsed at a frequency of 7.25 Hz. The fluid downstream of the swimming bluegill was illuminated by a 120 mJ dual-head pulse laser pulsed at a frequency of 7.25 Hz.

**3. RESULTS**

Fishes swam steadily at 1.1 body lengths per second (L s⁻¹; Re = 28 600 ± 316, St = 0.50 ± 0.04) and 1.5 L s⁻¹ (Re = 38 300 ± 1350, St = 0.39 ± 0.02) with the tail and dorsal and anal fins inside the laser volume, as well as upstream, for a minimum of 2 s, during which time 15 volumes were captured in any one sequence and 41 sequences captured in total. The homocercal tail of steadily swimming teleost fishes produced a series of linked ring vortices (figure 1). Vortices were also shed from the dorsal and ventral trailing edges of the caudal fin (figure 2). The caudal fin of bluegill and the cichlid produced a jet with a mean angle of 65.91 ± 1.38° relative to the downstream flow, with no significant difference between the two swim speeds (p < 0.0001). The mean maximum vorticity of rings produced by fishes swimming at 1.1 L s⁻¹ was 9.38 ± 0.84 s⁻¹ and 16.25 ± 1.26 s⁻¹ by fishes swimming at 1.5 L s⁻¹.

Dorsal fin wake properties were highly variable; jet angle ranged from 17.8 to 92.6° (mean = 65.32 ± 13.7°) relative to downstream flow with lower jet angles being correlated with higher swim speeds, and mean maximum vorticity ranged from 5.6 to 22.3 s⁻¹ (mean = 12.9 ± 3.02 s⁻¹). Conversely, anal fins produced a more consistent jet angle of 90.32 ± 0.32° with a mean maximum vorticity of 6.33 ± 1.53 s⁻¹. In some cases, the wake produced by the dorsal or anal fin could be seen clearly anterior to the location of the caudal fin (figure 2c,e). Downstream of the caudal fin, vortices produced by the dorsal or anal fin assimilated with the most recent fully formed caudal vortex; once a second vortex ring had been produced by the caudal fin, the dorsal or anal fin vortex was needed in order to understand fully the fluid interactions between fishes and their environment, and among the different fins used for propulsion [16,17].

The goal of this paper is to use a novel volumetric velocimetry system to test for the vortex wake structures hypothesized, using two-dimensional techniques in fishes swimming with an externally symmetrical (homocercal) caudal fin [11,12], and to examine the interaction between the dorsal and anal fin wake and the tail fin, which has been technically difficult to do with traditional imaging approaches [16].
nearly completely entrained by its corresponding caudal fin vortex (figure 2c,d). The vorticity magnitude produced by the dorsal and anal fins was not significantly different from the vorticity magnitude produced by the caudal fin during associated tail beats ($p < 0.01$).

4. DISCUSSION
The results presented here represent the first application of instantaneous volumetric PIV, or V3V, to be used in the study of swimming hydrodynamics of teleost fishes. Previous attempts to understand wake hydrodynamics produced by a homocercal tail...
employed repeated two-dimensional PIV techniques or stereo-PIV [15], to attempt to infer the three-dimensional wake structure produced by swimming fishes, or computational fluid dynamics (CFD) modelling techniques [20]. The ability to capture experimentally a three-dimensional snapshot of the wake structure created by a single individual removes the problem of aligning two-dimensional slices collected at different times. In addition, the three-dimensional structure of the wake shed by the dorsal and anal fins, and how this vorticity interacts with tail vortices, has not been directly visualized previously.

Two teleost fishes, cichlid and bluegill sunfish, both possessing homocercal (externally symmetrical) tails,
produced single vortex ring structures with each lateral pass of the tail, and volumetric imaging produces wake flow patterns that closely match current models based on two-dimensional analyses in most respects (figure 1a–d; [11,12]). As expected, continuous tail beats resulted in the formation of a linked chain of vortex rings. This same structure was also hypothesized for the mackerel, which possesses a more forked homocercal tail, using both planar PIV and three-dimensional CFD techniques [14,20].

Using multiple two-dimensional PIV slices in the transverse plane, Tytell [16] inferred that the dorsal and anal fin wakes would interact with the caudal fin and the wake it produced, but the duration and extent of median fin wake interaction was not known due to the inability to image the area of interaction above and below the tail in three dimensions. It is now evident that the dorsal and anal fin wakes are rapidly entrained by the caudal fin wake, approximately within the timeframe of a subsequent tail beat (figure 2). Volumetric images revealed a great deal more variability of the dorsal fin jet angle and mean maximum vorticity when compared with the relatively consistent anal fin wake. While the mean angle of the jet produced by the dorsal fin here (65.3 ± 13.7°) was similar to the 62.4 ± 1.8° jet angle discovered by Drucker & Lauder [9], the extent to which dorsal fin jet angle varied was not found in previous research. The dorsal fin produced a jet at lower angles to the direction of motion when the fish swam at higher speeds, suggesting that a greater portion of the jet contributed thrust and added momentum to the caudal fin vortex than compared with swimming at lower speeds.

Volumetric imaging of flows produced by moving animals is a long-sought goal in comparative biomechanics and allows previously hypothesized fluid motion resulting from fin and body movements to be quantified in three dimensions, without the assumptions inherent in reconstructing flow patterns from two-dimensional slices. These results show that volumetric imaging of biologically generated flow patterns can reveal new features of locomotor dynamics, and provides an avenue for future investigations of the diversity of fish swimming patterns and their hydrodynamic consequences.

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