The Limited Macroeconomic Effects of Unemployment Benefit Extensions*

Gabriel Chodorow-Reich
Harvard University and NBER

Loukas Karabarbounis
University of Minnesota, FRB Minneapolis, and NBER

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Abstract

By how much does an extension of unemployment benefits affect macroeconomic outcomes such as unemployment? Answering this question is challenging because U.S. law extends benefits for states experiencing high unemployment. We use data revisions to decompose the variation in the duration of benefits into the part coming from actual differences in economic conditions and the part coming from measurement error in the real-time data used to determine benefit extensions. Using only the variation coming from measurement error, we find that benefit extensions have a limited influence on state-level macroeconomic outcomes. We use our estimates to quantify the effects of the increase in the duration of benefits during the Great Recession and find that they increased the unemployment rate by at most 0.3 percentage point.

JEL-Codes: E24, E62, J64, J65.

Keywords: Unemployment Insurance, Measurement Error, Unemployment.

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1 Introduction

Responding to the increase in unemployment during the Great Recession, the potential duration of unemployment insurance (UI) benefits in the United States increased from 26 weeks to up to 99 weeks. Recent studies have found mixed effects of these benefit extensions on individual outcomes (Rothstein, 2011; Farber and Valletta, 2015; Johnston and Mas, 2015). The effect on macroeconomic outcomes has been even more controversial. According to one view, by making unemployment relatively more attractive to the jobless, the extension of benefits contributed substantially to the slow recovery of the labor market (Barro, 2010; Hagedorn, Karahan, Manovskii, and Mitman, 2015). Others have emphasized the potential stimulus effects of increasing transfers to unemployed individuals (Summers, 2010; Congressional Budget Office, 2012). Distinguishing between these possibilities has important implications for the design of UI policy and for economists’ understanding of labor markets.

Quantifying the effects of UI benefit extensions on macroeconomic outcomes is challenging. Federal law links actual benefit extensions in a state directly to state-level macroeconomic conditions. This policy rule mechanically generates a positive correlation between unemployment and benefit extensions, complicating the identification of any direct effect that benefit extensions may have on macroeconomic outcomes.

We combine a novel empirical research design with a standard labor market model augmented with extensions of UI benefits to shed light on this policy debate. Our results are inconsistent with large effects of benefit extensions on state-level macroeconomic aggregates including unemployment, employment, vacancies, and worker earnings. Instead, we find that the extension of benefits has only a limited influence on macroeconomic outcomes.

Our empirical approach starts from the observation that, at the state level, the duration of UI benefits depends on the unemployment rate as estimated in real time. However, real-time data provide a noisy signal of the true economic fundamentals. It follows that two states differ in the duration of their UI benefits because of differences in fundamentals or because of measurement error. We use subsequent revisions of the unemployment rate to separate the
fundamentals from the measurement error. We then use the measurement error component of UI benefit extensions to identify the effects of benefit extensions on state-level macroeconomic aggregates. Effectively, our strategy exploits the randomness in the duration of benefits with respect to economic fundamentals caused by measurement error in the fundamentals.

Table 1 uses the example of Louisiana and Wisconsin in April 2013 to illustrate our strategy. Under the 2008 emergency compensation program, the duration of benefits in a state increased by 14 additional weeks if a moving average of the state’s unemployment rate exceeded 6 percent. The unemployment rate measured in real time in Louisiana was 5.9 percent while that in Wisconsin was 6.9 percent, resulting in an additional 14 weeks of potential benefits in Wisconsin relative to Louisiana. However, data revised as of 2015 show that both states actually had the same unemployment rate of 6.9 percent. According to the revised data, both states should have qualified for the additional 14 weeks. We refer to the 14 weeks that Louisiana did not receive as a “UI error.” This error reflects mismeasurement of the economic fundamentals rather than differences in fundamentals between the two states and, therefore, provides variation to identify the effects of UI benefit extensions on state aggregates. In the event, the actual unemployment rate (from the revised data as of 2015) evolved very similarly following the UI error, declining
by roughly 0.2 percentage point between April and June 2013 in both states. Our empirical exercise amounts to asking whether this apparent limited influence of extending benefits on unemployment generalizes to a larger sample.

We begin our analysis in Section 2 by discussing relevant institutional details of the UI system, the measurement of real-time and revised state unemployment rates, and the UI errors that arise because of differences between real-time and revised data. The Bureau of Labor Statistics (BLS) constructs state unemployment rates by combining a number of state-level data sources using a state space model. Revisions occur due to revisions to the input data, the use of the full time series of available data in the state space estimation at the time of the revision, and the introduction of technical improvements in the statistical model itself. Of these, the technical improvements account for the largest share of the variation in the measurement error in the unemployment rate. The unemployment rate measurement error gives rise to more than 600 state-month cases between 1996 and 2015 in which, as in the example of Louisiana and Wisconsin in April 2013, the duration of benefits using the revised data differs from the actual duration of benefits. Almost all of these UI errors occur during the Great Recession. This concentration reflects both the additional tiers of benefits duration created by the 2008 emergency compensation program and the fact that most states experienced unemployment rates high enough for measurement errors to affect their eligibility for extended benefits.

Once a UI error occurs, it takes on average nearly 4 months to revert to zero. Thus, workers and firms can adjust their behavior in response to past and current unexpected changes in the UI error and to expectations about the future evolution of the error. We model the UI error as a flexible Markov process and identify its unexpected component, which we call the “UI error innovation.” Unlike the error itself, the innovation displays essentially zero serial correlation.

In Section 3 we estimate the impulse response of state-level variables to an unexpected UI error innovation. Innovations in the UI error have negligible effects on state-level unemployment, employment, vacancies, and worker earnings. In our baseline specification, a one-month positive innovation in the UI error generates at most a 0.02 percentage point increase in the
state unemployment rate. Crucially, a positive UI error innovation raises the fraction of the unemployed who receive UI benefits by a statistically significant and an economically reasonable magnitude, with the additional recipients being in the tiers affected by the error. Therefore, our results do not reflect the fact that more unemployed do not receive benefits in response to a UI error. They simply reflect the small macroeconomic effects of an increase in UI eligibility and receipt.

We validate our results along various dimensions. First, the incorporation of the full time series of data in the revision process makes the unemployment rate revision in month $t$ partly dependent on realizations of variables after month $t$. To make sure this aspect of the revision process does not bias our results, we add to our regression controls for linear and non-linear functions of the unemployment rate measurement error. The responses of labor market variables to a UI error innovation remain similar to our baseline estimates, reflecting the fact that this aspect of the revision process contributes very little to the variation in the unemployment rate measurement error. Second, we show the robustness of our results to the inclusion of a number of controls into the baseline specification and to alternative specifications. Third, we demonstrate that our results are similar under two alternative ways of extracting innovations in the UI error. Fourth, our exercise depends on the information content of the unemployment rate revisions. We derive a bound for the consistency of our estimator so long as the revised data measure true economic conditions at least as well as the real-time data. We provide empirical support for this condition from horse-race regressions in which measures of consumer spending and survey attitudes and beliefs load on the revised but not on the real-time unemployment rate, indicating that the revised data better align with agents’ decisions and perceptions of economic conditions.

Our empirical exercise provides a direct answer to the question of what would happen if a state increased the duration of unemployment benefits around the neighborhood of a typical UI error, or by about 3 months after a state has already extended benefits by nearly one year. The policy debate following the Great Recession has focused on the different, but related, question of the macroeconomic effects of extending benefits all the way from 26 to as many as 99 weeks.
Extrapolating linearly the upper bound of our estimates, we find that extending benefits from 26 to 99 weeks increased the unemployment rate by at most 0.3 percentage point.

In Section 4 we use a standard DMP model (Diamond, 1982; Mortensen and Pissarides, 1994) augmented with a UI policy to further illustrate the informativeness of our empirical results for the effects of extending benefits on macroeconomic outcomes. Relative to the direct calculation in the data, the model allows for potential non-linearities in the response of the unemployment rate to benefit extensions and anticipation effects by workers and firms. The effect of UI policy on macroeconomic outcomes depends crucially on the level of the opportunity cost of employment. We denote by $z = \xi + b$ the opportunity cost of employment, where $\xi$ is the value of non-market work and $b$ is the value of benefits for the average unemployed. We consider an economy with a high average level of $z = \xi + b = 0.81 + 0.15 = 0.96$ relative to a marginal product of one, as advocated by Hagedorn and Manovskii (2008). We also consider an economy with a lower average level of $z = \xi + b = 0.81 + 0.06 = 0.87$. The value of $b = 0.06$ accords with the estimates of Chodorow-Reich and Karabarbounis (2016) who show that benefits comprise a small fraction of the average opportunity cost mainly because many unemployed do not receive these benefits.

We begin our theoretical analysis by comparing the model’s responses to a one-month UI error innovation to the ones we estimated in the data. In the high $b$ economy, the unemployment rate increases by roughly 0.14 percentage point, while in the low $b$ economy the unemployment rate increases by less than 0.02 percentage point. The increase in unemployment in both economies reflects the fact that benefit extensions raise the opportunity cost of working for the average unemployed which puts upward pressure on wages, lowers firm profits, and dampens vacancy creation. The difference in magnitude occurs because in the high $b$ economy average firm profits are smaller and, therefore, the increase in the opportunity cost decreases firms profits by more in percent terms. We conclude that the low $b$ model comes much closer than the high $b$ model in matching the empirical response of the unemployment rate to a one-month UI error innovation (less than 0.02 percentage point).
In the final step of our analysis, we subject both economies to a sequence of large negative shocks that increase unemployment from below 6 percent to roughly 10 percent. Similar to what happened during the Great Recession, the increase in unemployment triggers benefit extensions in the model from 6 months to 20 months. To estimate the influence of benefit extensions on the path of unemployment, we then subject the two economies to the same sequence of shocks but without the benefit extensions. Removing benefit extensions in the high $b$ model reduces the average unemployment rate over a three-year horizon by 3.1 percentage points. The corresponding number in the low $b$ model is less than 0.3 percentage point. Because the low $b$ model matches the response of unemployment to a UI error innovation, we conclude that benefit extensions play a limited role in increasing unemployment during a recession.\footnote{Our conclusion differs from the results of Mitman and Rabinovich (2014) who argue that benefit extensions explain jobless recoveries. Benefit extensions generate significant movements in unemployment only under very high values of opportunity costs $b$ and $z$. The small response of unemployment to a UI error innovation implies that $b$ is much lower than the values generated by the Mitman and Rabinovich (2014) model.}

Related Literature. The economic literature on the effects of benefit extensions has followed two related lines of inquiry. Motivated in part by a partial equilibrium optimal taxation result linking the optimal provision of UI to individual search behavior (Baily, 1978; Chetty, 2006), a microeconomic literature has studied how various aspects of UI policy affects individual labor supply (see for a survey Krueger and Meyer, 2002). Studies which find a small effect of benefit extensions following the Great Recession on individual job finding rates and unemployment duration include Rothstein (2011) and Farber and Valletta (2015), while Johnston and Mas (2015) find somewhat larger effects.\footnote{Schmieder, von Wachter, and Bender (2012) and Kroft and Notowidigdo (2015) show that the effect of UI benefit extensions on unemployment duration becomes smaller during recessions.}

The macroeconomic effects of UI benefits concern their effect on aggregate unemployment.\footnote{Our estimates of the macroeconomics effects are particularly informative for general equilibrium models with UI policy. See Hansen and Imrohoroglu (1992), Krusell, Mukoyama, and Sahin (2010), and Nakajima (2012) for earlier general equilibrium analyses of unemployment insurance policy. Landais, Michaillat, and Saez (2015) and Kekre (2016) extend the Baily-Chetty partial equilibrium optimal UI formula to a general equilibrium setting and show how it depends on the macroeconomic effects of benefit extensions.}

Economic theory does not provide a one-to-one mapping between the magnitude of the microeconomic and macroeconomic effects. For example, in a standard DMP model with exogenous
job search effort and Nash bargaining, an increase in UI benefits raises workers’ outside options, putting an upward pressure on wages and depressing firm vacancy creation. Exogenous search effort implies a zero microeconomic effect, but the decline in total vacancies generates a rise in total unemployment, i.e. a non-zero macroeconomic effect (Hagedorn, Karahan, Manovskii, and Mitman, 2015). Alternatively, in models with job rationing, large microeconomic effects could be consistent with small macroeconomic effects if the job finding rate of UI recipients falls but that of non recipients rises (Levine, 1993; Landais, Michaillat, and Saez, 2015; Lalive, Landais, and Zweimüller, 2015).

Hagedorn, Karahan, Manovskii, and Mitman (2015) and Hagedorn, Manovskii, and Mitman (2015) use a county border discontinuity design to estimate a large positive effect of UI benefit extensions on unemployment. Hall (2013) challenges aspects of their research design and Amaral and Ice (2014), Coglianese (2015), Dieterle, Bartalotti, and Brummet (2016), and Boone, Dube, Goodman, and Kaplan (2016) report that the results are sensitive to changes in the data sources and the specification. Johnston and Mas (2015) use a sudden change in benefits in Missouri to estimate both the microeconomic and macroeconomic effects. They estimate macroeconomic effects of similar magnitude to the microeconomic effects, but their estimate of the macroeconomic effect depends on a difference-in-difference research design with Missouri the only treated observation. Consistent with our findings, Marinescu (2015) documents a small effect of benefit duration on vacancies. In work closest in approach to our own, Coglianese (2015) also recognizes that measurement error in the unemployment rate may help to identify the macroeconomic effects of duration extensions. Our approach differs from his in using the data revisions to isolate the measurement error in the duration of UI benefits, in explicitly modeling a stochastic process for the measurement error that allows us to tackle the issue of expectations, and in our interpretation of the informativeness of our empirical estimates for key policy experiments through the lens of the DMP model.\footnote{In a different context, Suárez Serrato and Wingender (2014) use data revisions to population estimates to identify the effects of government spending on local outcomes.}
2 Empirical Design

We begin this section by discussing relevant institutional details of the UI system and the measurement of real-time and revised unemployment rates. We then define the UI errors that arise because of differences between real-time and revised data and discuss how we use these errors to estimate the effects of UI benefit extensions on state-level aggregate outcomes.

2.1 Unemployment Insurance Laws

The maximum number of weeks of UI benefits available in the United States varies across states and over time. Regular benefits in most states provide 26 weeks of compensation, with a range between 13 and 30 weeks. The existence of regular UI benefits does not depend on economic conditions in the state. Extended benefits (EB) and emergency compensation provide additional weeks of benefits during periods of high unemployment in a state. The EB program has operated since 1970 and is 50 percent federally funded except for the period 2009-2013 when it became fully federally funded. Emergency compensation programs are authorized and financed on an ad hoc basis by the federal government. Our sample contains the Temporary Emergency Unemployment Compensation (TEUC) program between March 2002 and December 2003 and the Emergency Unemployment Compensation (EUC) program between July 2008 and December 2013. We refer to the combination of EB and emergency compensation as UI benefit extensions.

Qualification for benefit extensions in a state typically depends on the unemployment rate exceeding some threshold. Two measures of unemployment arise in the laws governing these extensions. The insured unemployment rate (IUR) is the ratio of recipients of regular benefits to employees covered by the UI system. The total unemployment rate (TUR) is the ratio of the total number of individuals satisfying the official definition of not working and on layoff or actively searching for work to the total labor force. To avoid very high frequency movements in the available benefit extensions, both the IUR and the TUR enter into the trigger formulas determining extensions as three-month moving averages. A trigger may also contain a lookback
provision which requires that the indicator exceed its value during the same set of months in prior years. In Appendix A.1 we list the full set of benefit extension programs, tiers, and triggers in operation during our sample.\(^5\)

### 2.2 Measurement of State Unemployment and Data Revisions

Whether a state extends its duration of benefits or not depends on state-level estimates of the IUR and TUR as estimated in real time. The real-time IUR uses as inputs administrative data on UI payments and covered employment and, therefore, contains little measurement error. The Local Area Unemployment Statistics (LAUS) program at the Bureau of Labor Statistics (BLS) produces the state-level estimates of the TUR. Unlike the national unemployment rate, which derives directly from counts from the Current Population Survey (CPS) of households, the state unemployment rates incorporate auxiliary information to overcome the problem of small sample sizes at the state level (roughly 1,000 labor force participants for the median state). Better source data and improved statistical methodology imply substantial revisions in the estimated TUR over time.

We give here a brief description of BLS’s procedure to estimate state unemployment rates and present more details in Appendix A.2. The real-time unemployment rate, which we denote by \(u_{s,t}^*\) for state \(s\) in month \(t\), equals the ratio of real-time unemployment to real-time unemployment plus employment. The BLS uses a state space filter to estimate separately real-time total unemployment and total employment. For unemployment the observed variables are the CPS count of unemployed individuals in the state and the number of insured unemployed. For employment the observed variables are the CPS count of employed individuals and the level of payroll employment in the state from the Current Employment Statistics (CES) program. From 2005 to 2014, the procedure also included a real-time benchmarking constraint that allocated

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\(^5\)Not every unemployed individual qualifies for regular benefits in a state, with eligibility determined by reason for separation from previous employer, earnings over the previous year, and search effort. Individuals who qualify for and then exhaust their regular benefits are eligible for benefits under EB or an emergency program. Individuals who have exhausted their eligibility under other tiers are eligible to receive benefits when their state triggers onto a tier. Conversely, as soon as a state triggers off a tier all individuals lose eligibility immediately regardless of whether they had begun to collect benefits on that tier.
pro rata the residual between the sum of filter-based levels across states and the total at the Census division or national level. Finally, in 2010 the BLS began applying a one-sided moving average filter to the state space filtered and benchmarked data.

The BLS publishes revisions of its estimates of the state unemployment rates. We denote the unemployment rate as reported in the revised data by \( u_{s,t} \) and the measurement error in the (real-time) unemployment rate by \( \hat{u}_{s,t} = u^*_{s,t} - u_{s,t} \). The revised rates \( u_{s,t} \) do not determine eligibility into the various extended benefits programs.

Revisions in the unemployment rate occur for three reasons. First, the auxiliary data used in the estimation – insured unemployment and payroll employment – are updated with administrative data not available in real time. Second, the BLS incorporates the entire time series available at the time of the revision into its model, replacing the state space filter with a state space smoother and the one-sided moving-average filter with a symmetric filter. Third, the BLS periodically updates its estimation procedure to reflect methodological improvements. Most recently, in 2015 the BLS discontinued the external real-time benchmarking constraint and incorporated a benchmarking constraint within the state space model to reduce the spillover of state-specific outliers in the CPS across states. In Appendix A.2 we investigate the importance of different components of the revision process by regressing \( \hat{u}_{s,t} \) on the components. The 2015 methodological update and the treatment of outliers account for the largest amount of the variation in \( \hat{u}_{s,t} \). Importantly, the incorporation of the full time series at the time of revision explains very little of the variation in \( \hat{u}_{s,t} \).

2.3 The UI Errors

Let \( f_{s,t}(\cdot) \) be the UI law which maps a history of unemployment rates in a state \( s \) into the maximum duration of UI benefit extensions in the state. We use a time subscript \( t \) on the function because the mapping can change due to temporary legislation such as an emergency compensation program. We define the actual maximum duration of UI benefit extensions based on the real-time unemployment rates as \( T^*_s \) and the hypothetical duration of benefit extensions
Based on the revised data as $T_{s,t}$:

$$T_{s,t}^* = f_{s,t}(u_{s,t-1}^*)$$ \hspace{1cm} (1)
$$T_{s,t} = f_{s,t}(u_{s,t-1}).$$ \hspace{1cm} (2)

Importantly, the same function $f_{s,t}(.)$ appears in both equations (1) and (2).\(^6\)

We define the UI error $\hat{T}_{s,t}$ as:

$$T_{s,t}^* = T_{s,t} + \hat{T}_{s,t}.$$ \hspace{1cm} (3)

Variation in the actual duration of benefit extensions $T_{s,t}^*$ comes from the component $T_{s,t}$ which depends on the true economic fundamentals and from the component $\hat{T}_{s,t}$ which reflects measurement error in the state unemployment rate. The key idea of our approach is to use variation induced only from the UI error $\hat{T}_{s,t}$ to identify the effects of benefit extensions on state-level outcomes.

To separate $T_{s,t}^*$ into the component $T_{s,t}$ that corresponds to the fundamentals and the UI error $\hat{T}_{s,t}$, we start with the weekly trigger notices produced by the Department of Labor (DOL). The DOL produces each week a trigger notice that contains for each state the most recent available moving averages of IUR and TUR, the ratios of IUR and TUR relative to previous years, and information on whether a state has any weeks of EB available and whether it has adopted optional triggers for EB status. During periods with emergency compensation programs, the DOL also produces separate trigger notices with the relevant input data and status determination for the emergency programs. We scraped data for EB notices from 2003-2015 and for the EUC 2008 programs from the DOL’s online repository.\(^7\) The TEUC notices

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\(^6\)We simplify a few details in writing monthly UI duration in equations (1) and (2) as a function of the previous month’s unemployment rate. The actual determination of UI benefit extensions eligibility occurs weekly and is based on unemployment rate data available at the start of the week. The BLS typically releases the real-time state unemployment rate data for month $t-1$ around the 20th day of month $t$. Therefore, for the first weeks of month $t$ the most recent real-time unemployment rate which enters into the eligibility determination is for month $t-2$ while for the last weeks the most recent unemployment rate affecting eligibility is for month $t-1$. We aggregate in the text to a monthly frequency and capture the reporting lag for the real-time data by writing UI benefits in month $t$ as a function of the unemployment rate in month $t-1$. Next, as we discuss in Appendix A.1, benefit duration typically depends on a three month moving average of unemployment rates and may also depend on a “lookback” to the unemployment rate 12 and 24 months before, so that further lags of the unemployment rates also enter into the eligibility determination. While we appropriately take into account these details in our implementation, they do not affect the general econometric approach so we omit them in the main text for clarity.

\(^7\)The address is http://www.oui.doleta.gov/unemploy/claims_arch.asp.
Table 2: Accuracy of Our Algorithm for Calculating UI Benefit Extensions

<table>
<thead>
<tr>
<th></th>
<th>EB</th>
<th>TEUC02</th>
<th>EUC08</th>
<th>Total</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Original Trigger Notices</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Same as our algorithm</td>
<td>45456</td>
<td>3982</td>
<td>14291</td>
<td>63729</td>
</tr>
<tr>
<td>Different from our algorithm</td>
<td>44</td>
<td>18</td>
<td>9</td>
<td>71</td>
</tr>
<tr>
<td><strong>Corrected Trigger Notices</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Same as our algorithm</td>
<td>45494</td>
<td>3999</td>
<td>14300</td>
<td>63793</td>
</tr>
<tr>
<td>Different from our algorithm</td>
<td>6</td>
<td>1</td>
<td>0</td>
<td>7</td>
</tr>
</tbody>
</table>

Notes: The table reports the number of state-weeks where our algorithm gives the same UI benefit tier eligibility as the published DOL trigger notices. The period is 1996-2015. The top panel compares our algorithm to the raw trigger notices. In the bottom panel, we have corrected the information in the raw trigger notices when we find conflicting accounts in either contemporary media sources or in the text of state legislation.

We augment these data with monthly real-time unemployment rates by digitizing archived releases of the monthly state and local unemployment reports from the BLS.

We use the revised unemployment data as of 2015 as inputs into the trigger formulas described in Appendix Table A.1 to calculate $T_{s,t}$. The UI error then equals $\hat{T}_{s,t} = T_{s,t}^* - T_{s,t}$. To verify the accuracy of our algorithm for constructing $T_{s,t}$, we apply the same algorithm using the
Figure 1: Extended Benefits and Unemployment in Vermont

Notes: The figure plots the actual duration of benefits $T_{s,t}^*$ and the duration based on the revised data $T_{s,t}$ (left axis) together with the real-time $u_{s,t}^*$ and revised unemployment rates $u_{s,t}$ (right axis).

We use the EB program in the state of Vermont to illustrate our measurement of the two components. Figure 1 plots four lines. The blue solid step function shows the additional weeks of benefits available to unemployed in Vermont in each calendar week, $T_{VT,t}^*$. This series depends on the most recently reported three month moving-average real-time unemployment rate, plotted by the dashed blue line. The red dashed step function shows $T_{VT,t}$, the additional weeks of benefits that would have been available in Vermont using the revised unemployment rate series plotted by the dashed red line.

Vermont extended its benefits by an additional 13 weeks in the beginning of 2009. Because

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10Our algorithm does better than the trigger notices, in the sense that it identifies more than 50 instances where the trigger notices report an incorrect duration or aspect of UI law which we subsequently correct using contemporary local media sources or by referencing the actual text of state legislation. We suspect but cannot confirm that the remaining discrepancies also reflect mistakes in the trigger notices. A number of previous papers have relied on information contained in the trigger notices (Rothstein, 2011; Hagedorn, Karahan, Manovskii, and Mitman, 2015; Hagedorn, Manovskii, and Mitman, 2015; Marinescu, 2015; Coglianese, 2015). Our investigation reveals that, while small in number, uncorrected mistakes in the trigger notices could induce some attenuation bias.
the real-time and the revised unemployment rates move closely together in this period, Vermont would have triggered an EB extension using either the real-time or the revised data as an input in the trigger formula. The unemployment rate peaks at the end of 2009. As the unemployment rate starts to decline, a UI error occurs. In the beginning of 2010, the real-time unemployment rate temporarily increases by a small amount whereas the revised rate continues to decline steadily. Under the revised data, EB should have been discontinued at the beginning of 2010. However, under the real-time data, EB remained in place until roughly the middle of 2010. The UI error $\hat{T}_{VT,t}$, which is the difference between the blue and red step functions, takes the value of 13 weeks during the first part of 2010. In Appendix A.2 we show that Vermont’s UI error is entirely accounted for by the 2015 methodological improvement in the LAUS statistical model.

### 2.4 Innovations in UI Errors

The UI error $\hat{T}_{s,t}$ exhibits serial correlation, as shown for example in the Vermont case in Figure 1.\(^{11}\) This implies that firms and workers can respond to past and current unexpected changes in the UI error and to expectations about the future evolution of the error. Our analysis, therefore, traces impulse response functions with respect to a UI error innovation $\epsilon_{s,t}$, defined as the current period unexpected component of the UI error:

$$\epsilon_{s,t} = \hat{T}_{s,t} - \mathbb{E}_{t-1}\hat{T}_{s,t}, \quad (4)$$

where $\mathbb{E}_{t-1}\hat{T}_{s,t}$ denotes the expectation of $\hat{T}_{s,t}$ using information available until period $t - 1$.\(^{12}\)

To identify the unexpected component in the UI error $\epsilon_{s,t}$, we need to estimate the expectation of the future value of the UI error. Inspection of the time series of the UI errors, as for example in Vermont in Figure 1, reveals a stochastic process better described by occasional

\(^{11}\)The serial correlation reflects both the UI law (once triggered onto a tier a state must remain on for at least 13 weeks) and serial correlation in $\hat{u}_{s,t}$. To give a sense of the latter, the first 8 autocorrelation coefficients of $\hat{u}_{s,t}$ are 0.78, 0.63, 0.52, 0.45, 0.40, 0.35, 0.32, 0.29.

\(^{12}\)When an outcome variable $y_{s,t}$ depends on leads or lags of a persistent right-hand side variable $\{\hat{T}_{s,t+j}\}_{j=1}^{h_{s,t}}$, a regression of $y_{s,t}$ only on the contemporaneous $\hat{T}_{s,t}$ suffers from a standard omitted variable bias. This problem is distinct from the endogeneity of benefit extensions $T_{s,t}$ with respect to the underlying macroeconomic conditions. The standard solution to the problem of persistent right-hand side variables is to use innovations to the right-hand side variables. Our approach follows closely the macroeconomics convention of plotting impulse responses with respect to structural innovations, as summarized in Ramey (2016).
discrete jumps than by a smoothly evolving diffusion. Therefore, rather than obtaining $\epsilon_{s,t}$ as the residual from a smooth autoregressive process, our baseline estimates use a more general first-order discrete Markov chain for $\hat{T}_{s,t}$.

We assume the UI error $\hat{T}_{s,t}$ follows a first-order discrete Markov chain with probabilities given by $\pi_T \left( \hat{T}_{s,t+1} = x_j \mid \hat{T}_{s,t} = x_i; u_{s,t}, t \right)$ that $\hat{T}$ transitions from a value $x_i$ to a value $x_j$. We allow the probabilities to depend on the unemployment rate and calendar time because the mapping from a measurement error in the unemployment rate to a UI error depends on whether the measurement error occurs in a region of the unemployment rate space sufficiently close to a trigger threshold. For example, measurement error in the mid-2000s does not cause a UI error for Vermont in Figure 1 because the unemployment rate is far below the threshold for triggering an extension of benefits. Conditioning on calendar time reflects the time variation in UI laws and triggers, for example due to the enactment of an emergency compensation program. In practice, we aggregate $\hat{T}_{s,t}$ up to a monthly frequency and estimate each probability $\pi_T \left( \hat{T}_{s,t+1} = x_j \mid \hat{T}_{s,t} = x_i; u_{s,t}, t \right)$ as the fraction of transitions of the UI error from $x_i$ to $x_j$ for observations in the same unemployment rate and calendar time bin. We form a vector of discrete possible values of $x$ from one-half standard deviation wide bins of $\hat{T}_{s,t}$. Finally, once we have estimated the transition probabilities of the Markov process, we calculate the expectation $E_{t-1} \hat{T}_{s,t}$ and form the UI error innovation $\epsilon_{s,t}$ using equation (4).

We explore the sensitivity of our results to the assumed $\hat{T}_{s,t}$ process by considering two alternatives in robustness exercises. First, we obtain the innovations by simply first-differencing the UI error, $\epsilon_{s,t} = \hat{T}_{s,t} - \hat{T}_{s,t-1}$. This transformation is less general than our baseline first-order discrete Markov chain, but has the virtue of simplicity. Second, we obtain the innovations from a VAR(12) of the UI error $\hat{T}_{s,t}$ and the unemployment rate $u_{s,t}$. This approach is conceptually

\footnote{A trade-off exists between finer partitioning of the state space and retaining sufficient observations to make the exercise non-trivial. We estimate separate transition matrices for each of the following sequential groupings, motivated by the divisions shown in Table A.1: December 2008 – May 2012 and $5.5 \leq u_{s,t} < 7$; December 2008 – May 2012 and $7 \leq u_{s,t} < 8.5$; December 2008 – May 2012 and $u_{s,t} \geq 8.5$; June 2012 – December 2013 and $5.5 \leq u_{s,t} < 7$; June 2012 – December 2013 and $7 \leq u_{s,t} < 9$; June 2012 – December 2013 and $u_{s,t} \geq 9$; January 2002 – December 2003 and $u_{s,t} \geq 5.5$; $u_{s,t} \geq 5.5$; $u_{s,t} < 5.5$. We have experimented with coarser groupings and larger bins of $\hat{T}_{s,t}$ with little effect on our results.
similar to a Jordà (2005) local projection. Our results do not change significantly when using these alternative assumptions for the data generating process of the UI errors.

2.5 Summary Statistics

We draw on a number of sources for state-level outcome variables. From the BLS, along with the revised unemployment rate, we use monthly employment growth from the Current Employment Statistics program and monthly labor force participation from the LAUS program. We obtain data on the number of UI payments across all programs by state and month from the DOL ETA 539 and ETA 5159 activity reports and from special tabulations for the July 2008 to December 2013 period.\footnote{These are found at http://www.ows.doleta.gov/unemploy/DataDownloads.asp and http://workforcesecurity.doleta.gov/unemploy/euc.asp respectively, last accessed February 10, 2016. The data report the total number of UI payments each month. To express as a share of the total unemployed, we divide by the number of unemployed in the (revised) LAUS data and multiply by the ratio $7/\text{[days in month]}$ because the number of unemployed are a stock measure as of the CPS survey reference week.} We obtain monthly data on vacancies from the Conference Board Help Wanted Print Advertising Index and the Conference Board Help Wanted Online Index. We use the first for the years 1996-2003 and aggregate local areas up to the state level. We use the online index for 2007-2015. The print index continues until June 2008 and the online index begins in 2005. However, the two indexes exhibit conflicting trends between 2004 and 2006 as vacancy posting gradually transitioned from print to online and we exclude this period from our analysis of vacancies.\footnote{The loss of these years has little effect for our results because these years contain very few UI errors. See Sahin, Song, Topa, and Violante (2014) for a description of the vacancy data and a comparison to JOLTS.} Our measure of worker wages, available at quarterly frequency, is the earnings of all and of new workers from the Census Bureau Quarterly Workforce Indicators.

Table 3 reports summary statistics. Our sample covers the period between 1996 and 2015 for the 50 U.S. states.\footnote{We exclude months in which a benefit extension program had temporarily lapsed for at least half the month (June 2010, July 2010, and December 2010) and the months immediately following (August 2010 and January 2011).} The average error in the real-time state total unemployment rate, $\hat{u}_{s,t}$, is close to zero, with a standard deviation of 0.37 percentage point. Measurement error in the unemployment rate is spread across states and months as its standard deviation changes little after controlling for state and month fixed effects.\footnote{In contrast to the total unemployment rate, the insured unemployment rate contains almost no revisions. The}
Table 3: Summary Statistics of Selected Variables

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Unemployment Rate Error</td>
<td>( \hat{u}_{s,t} )</td>
<td>-0.08</td>
<td>0.37</td>
<td>0.32</td>
<td>-0.29</td>
<td>0.13</td>
<td>11700</td>
</tr>
<tr>
<td>Actual Duration of Benefit Extensions</td>
<td>( T^*_s,t )</td>
<td>3.32</td>
<td>5.46</td>
<td>1.44</td>
<td>0.00</td>
<td>3.50</td>
<td>11700</td>
</tr>
<tr>
<td>UI Error</td>
<td>( \hat{T}_{s,t} )</td>
<td>0.02</td>
<td>0.53</td>
<td>0.51</td>
<td>0.00</td>
<td>0.00</td>
<td>11700</td>
</tr>
<tr>
<td>UI Error Innovation</td>
<td>( \epsilon_{s,t} )</td>
<td>-0.00</td>
<td>0.34</td>
<td>0.33</td>
<td>-0.00</td>
<td>0.00</td>
<td>11700</td>
</tr>
<tr>
<td>Unemployment Rate (Revised 2015)</td>
<td>( u_{s,t} )</td>
<td>5.55</td>
<td>1.93</td>
<td>0.82</td>
<td>4.20</td>
<td>6.60</td>
<td>11700</td>
</tr>
<tr>
<td>Fraction Unemployed Receiving UI</td>
<td>( \phi_{s,t} )</td>
<td>36.47</td>
<td>16.59</td>
<td>6.71</td>
<td>23.86</td>
<td>45.94</td>
<td>1500</td>
</tr>
<tr>
<td>Log Vacancies (Detrended)</td>
<td>( \log v_{s,t} )</td>
<td>0.04</td>
<td>0.27</td>
<td>0.16</td>
<td>-0.15</td>
<td>0.24</td>
<td>7656</td>
</tr>
<tr>
<td>Log Payroll Employment (Detrended)</td>
<td>( \log E_{s,t} )</td>
<td>0.00</td>
<td>0.03</td>
<td>0.02</td>
<td>-0.02</td>
<td>0.02</td>
<td>11700</td>
</tr>
<tr>
<td>Log Earnings of All Workers (Detrended)</td>
<td>( \log w_{s,t} )</td>
<td>0.00</td>
<td>0.03</td>
<td>0.03</td>
<td>-0.02</td>
<td>0.02</td>
<td>3204</td>
</tr>
<tr>
<td>Log Earnings of New Hires (Detrended)</td>
<td>( \log w_{s,t} )</td>
<td>0.00</td>
<td>0.05</td>
<td>0.04</td>
<td>-0.03</td>
<td>0.03</td>
<td>3066</td>
</tr>
</tbody>
</table>

Memo:

- Duration of Benefit Extensions (\( \hat{T}_{s,t} \neq 0 \))
  - \( T^*_s,t \) | 11.84 | 4.53 | 8.69 | 16.31 | 618
- UI Error (\( \hat{T}_{s,t} \neq 0 \))
  - \( \hat{T}_{s,t} \) | 0.47 | 2.27 | -1.50 | 2.25 | 618
- UI Error Innovation (\( \Delta \hat{T}_{s,t} \neq 0 \))
  - \( \epsilon_{s,t} \) | 0.02 | 1.44 | -1.02 | 1.04 | 573
- Length of Episode
  - 3.86 | 3.13 | 2.00 | 4.00 | 161

Notes: All variables except for Log Earnings are measured at monthly frequency. Denoted variables have been detrended with a state-specific linear time trend. Within S.D. is the standard deviation of the variable’s residual from a regression of the variable on state and month fixed effects.

A potential concern with our empirical approach is that there are too few or too small errors to identify significant effects of benefit extensions on macroeconomic outcomes. Table 3 shows that this is not true. There are 618 cases in which a state would have had a different duration of extensions using the revised data. Conditional on a UI error occurring, that is \( \hat{T}_{s,t} \neq 0 \), the standard deviation of the UI error is larger than 2 months. The interquartile range is roughly 4 months. The fact that there is enough variation in the UI error relative to outcome variables such as the unemployment rate explains the small standard errors of our estimates below.

The average episode of non-zero UI error lasts nearly 4 months and occurs when benefit extensions already provide an additional year of UI eligibility. Most of these episodes occur during the Great Recession. As already discussed in Section 2.4, measurement error in the unemployment rate translates into a UI error only if the state’s unemployment rate is sufficiently standard deviation of the error in the insured unemployment rate is only 0.02 percentage point.
near a trigger threshold. This fact explains why we examine errors in the number of weeks available \( \hat{T} \) directly rather than measurement error in the unemployment rate. It also explains why the UI errors occur mostly in the Great Recession, a period when both the EUC program created additional trigger thresholds and most states had unemployment rates high enough for a measurement error in the unemployment rate to translate into a UI error.

3 Empirical Results

In this section we present our empirical results. The impulse responses that we estimate give model-free evidence for the labor market effects of UI benefit extensions triggered purely by measurement error. In Section 4, we use a DMP model to show the informativeness of these impulse responses for the labor market effects of the large extensions observed after the Great Recession and which are triggered by to shocks to fundamentals rather than measurement error.

We summarize our approach for overcoming the endogeneity of UI benefit extensions to macroeconomic conditions as follows. We use data revisions to isolate the component of benefit extensions arising from mismeasurement of state unemployment rates in real time, which we denote by \( \hat{T}_{s,t} \), and construct the unexpected and serially uncorrelated component of the UI error, \( \epsilon_{s,t} \). Motivated by our investigation of the sources of unemployment rate revisions, we begin our analysis in Section 3.1 under the assumption that the measurement error in the unemployment rate underlying \( \epsilon_{s,t} \) is random.\(^{18}\) In Section 3.2, we implement an identification strategy which relaxes this assumption. Section 3.3 presents additional sensitivity analyses of our baseline specifications. Finally, in Section 3.4 we provide auxiliary evidence that the revised unemployment rate actually measures better true economic conditions than the real-time unemployment rate.

---

\(^{18}\)Our strategy differs from a linear IV design in which measurement error in unemployment \( \hat{u}_{s,t} \) instruments for actual benefit extensions \( T^*_{s,t} \) (or the innovation in \( T^*_{s,t} \)) because the linear IV disregards our knowledge of the exact nonlinear mapping from \( \hat{u}_{s,t} \) to the UI errors \( \hat{T}_{s,t} \). Our procedure makes full use of this information and produces much tighter confidence intervals. Our strategy also resembles a Regression Discontinuity (RD) framework, but with the crucial difference being that UI errors reflect larger and more persistent variation than the variation RD uses around a trigger threshold. Using the model of Section 4 we find that, when shocks are very persistent, a pure RD framework could fail to detect significant effects of benefit extensions on unemployment despite the existence of such effects. See Appendix C for more details.
3.1 Baseline Results

Identification. In this section we measure the response of labor market variables to a one-month UI error innovation \( \epsilon_{s,t} \) using the specification:

\[
y_{s,t+h} = \beta(h)\epsilon_{s,t} + \Gamma(h)X_{s,t} + \nu_{s,t+h}, \tag{5}
\]

where \( y_{s,t+h} \) is an outcome variable in state \( s \) and period \( t + h \), \( \epsilon_{s,t} \) is the UI error innovation in state \( s \) and period \( t \), and \( X_{s,t} \) is a vector of covariates. The coefficients \( \beta(h) \) for \( h = 0, 1, 2, ... \) trace out the impulse response function of \( y \) with respect to a one-month unexpected change in the UI error. The vector \( X_{s,t} \) contains a state fixed effect \( d_s \), a month fixed effect \( d_t \), and twelve lags of the unemployment rate \( \{u_{s,t-j}\}_{j=1}^{12} \). We include state and month fixed effects because, as seen in Table 3, they absorb substantial variation in our main outcome variables and, therefore, increase precision. The lags of the unemployment rate approximate the experiment of comparing two states on similar unemployment paths until one receives an unexpected UI error. The identification assumption that \( \epsilon_{s,t} \) is orthogonal to \( \nu_{s,t+h} \), \( \mathbb{E}[\epsilon_{s,t} \times \nu_{s,t+h} | X_{s,t}] = 0 \), is valid if the underlying measurement error in the unemployment rate \( \hat{u}_{s,t} \) that gives rise to \( \epsilon_{s,t} \) is random.\(^{19}\)

Results. Figure 2 shows impulse responses of the innovation \( \epsilon \) and the UI error \( \hat{T} \) to a one-month innovation \( \epsilon \). As expected, the innovation exhibits essentially no serial correlation. The lack of serial correlation provides support for our choice of modeling \( \hat{T} \) as a first-order Markov process.\(^{20}\) The UI error \( \hat{T} \) rises one-for-one with \( \epsilon \) on impact and then decays over the next few months with a half-life of roughly 2 months. In all impulses, dashed lines report the 90 percent confidence interval based on standard errors two-way clustered by state and by month.

Figure 3 illustrates the main empirical result of the paper. The left panel shows the responses

\(^{19}\)Indeed, this identification argument applies without controls in \( X_{s,t} \) and we report results from the bivariate specification in Section 3.3. The twelve lags of the unemployment rate also directly control for the small increment to the \( R^2 \) from including lags of the unemployment rate in Table A.2. When we plot impulse responses of \( u_{s,t+h} \) we continue to include both the fixed effect and the lagged values of \( u_{s,t} \) in an OLS framework since the large time series (more than 200 monthly observations) exceeds the cross-sectional component (Alvarez and Arellano, 2003).

\(^{20}\)Time aggregation from weekly to monthly frequency could explain the small correlation between months \( t \) and \( t + 1 \), as an increase in \( \hat{T} \) in week 3 or 4 of month \( t \) would produce a positive innovation in both \( t \) and \( t + 1 \).
Figure 2: Serial Correlation

Notes: The figure plots the coefficients on $\epsilon_{s,t}$ from the regression $y_{s,t+h} = \beta(h)\epsilon_{s,t} + \sum_{j=1}^{12} \gamma_j(h)u_{s,t-j} + d_s(h) + d_t(h) + \nu_{s,t+h}$, where $y_{s,t+h} = \epsilon_{s,t+h}$ is the UI error innovation (left panel) or $y_{s,t+h} = \hat{T}_{s,t+h}$ is the UI error (right panel). The dashed lines denote the 90 percent confidence interval based on two-way clustered standard errors.

from equation (5) when the left-hand side variable is the (revised) unemployment rate. The unemployment rate barely responds to the increase in the duration of benefits. Our point estimate for the response is essentially zero. The upper bound is roughly 0.02 percentage point. The data do not reject a zero response of the unemployment rate at any horizon.\(^\text{21}\) To get a sense of the magnitude of the responses, in the same figure we plot a dashed line at 0.14 percentage point. This is the response required for the model of Section 4 to conclude that unemployment in the Great Recession remained persistently high because of an extension of benefits from 6 to 20 months. Our baseline point estimate is more than 6 standard errors below this level.

The right panel of Figure 3 reports the response of vacancy creation. The macroeconomic effect of benefit extensions on unemployment may exceed the microeconomic effect because of a general equilibrium mechanism intermediated by vacancies. The mechanism posits that, following the extension of benefits, firms bargain with unemployed who have higher opportunity

\(^{21}\)The small standard errors reflect the substantial variation in the right-hand side variable $\epsilon$ relative to the outcome variable $u$ shown in Table 3. To get a back-of-the-envelope estimate of the standard error without controlling for lags of $u$, consider a bivariate regression with a zero coefficient and no clustering. The standard error of the coefficient would be $\frac{1}{\sqrt{N}} \frac{\sigma_{\epsilon}}{\sigma_u} = \frac{1}{\sqrt{11,550}} \frac{0.82}{0.33} \approx 0.023$. The two-way clustered standard error differs only slightly from this back-of-the-envelope estimate.
cost of working. The result is higher wages and lower firm profits from hiring, discouraging vacancy creation. However, Figure 3 shows that vacancies are unresponsive to a UI error innovation. The dashed line plotted at $-0.045$ denotes the response of log vacancies required to conclude that the extension of benefits from 6 to 20 months caused unemployment in the Great Recession to remain persistently high.

We next show in Figure 4 that the absence of a response of unemployment and vacancies occurs despite a higher fraction of the unemployed receiving UI benefits following a UI error innovation. The left panel shows that upon impact, the fraction of unemployed receiving UI benefits increases by 0.5 percentage point. The fraction remains high for the next two months and then declines to zero. The innovations in the UI error take place when benefits have, on average, already been extended for roughly 12 months. Using CPS data we estimate that between 0.5 and 1 percent of unemployed would be affected by such an extension, implying a take-up rate in the range of estimates documented by Blank and Card (1991). The right panel of Figure 4 splits the increase in UI receipt into recipients on tiers without a UI error (dashed red line with triangles) and recipients on tiers affected by the UI error (solid blue line with triangles).
Response of total $\phi$

Response of $\phi$ by tier

Figure 4: Impulse Response of Fraction Receiving UI

Notes: The figure plots the coefficients on $\epsilon_{s,t}$ from the regression $\phi_{s,t+h} = \beta(h)\epsilon_{s,t} + \sum_{j=1}^{12} \gamma_j(h)u_{s,t-j} + d_s(h) + d_h + v_{s,t+h}$. In the left panel, $\phi_{s,t+h}$ includes UI recipients in all tiers. The right panel plots separate impulse response functions for UI recipients in tiers with a UI error (solid blue line) and in tiers without a UI error (dashed red line). In the right panel the sample starts in 2008. The dashed lines denote the 90 percent confidence interval based on two-way clustered standard errors.

Reassuringly, all of the additional take-up of UI benefits occurs among individuals on tiers directly affected by the UI error.

Finally, Table 4 summarizes the responses of a number of labor market variables. The table reports the point estimates and standard errors at horizons 1 and 4 for the variables already plotted along with employment, labor force participation, and worker earnings. The right panel displays results for a slight modification of equation (5) in which we replace the dependent variable with its difference relative to before the UI error innovation occurs.\textsuperscript{23} Across

\textsuperscript{22}We do not have UI receipt by tier for the EB or TEUC02 programs. Therefore, the sample in the right panel of Figure 4 starts in 2008 and the sum of the two lines in the right panel does not equal the impulse response in the left panel which is based on the full sample.

\textsuperscript{23}For $u_{s,t}$, the lags of the unemployment rate make differencing with respect to $u_{s,t-1}$ redundant, but for the other variables we do not impose a zero effect in $t-1$ in the left panel. If UI error innovations are uncorrelated with lagged outcome variables, then it would not matter for the point estimates which specification we used. We prefer the levels specification because of a time-aggregation issue. An increase in $\hat{T}$ in week 4 of month $t-1$ that persists through month $t$ would be associated with an increase in $\epsilon_{s,t}$ and may also be correlated with variables in $t-1$. Indeed, we have already noted the small serial correlation of $\epsilon_{s,t}$ due to this time aggregation issue. The attenuation from differencing with respect to $t-1$ is likely quite small for variables based on the CPS (the unemployment rate and labor force participation rate) or the CES (payroll employment) which use as a reference period the week or pay period containing the 12th day of the month. Likewise, the reference period for the vacancy measure for month $t$ is from mid month in $t-1$ to mid month in month $t$. However, the problem is larger for the fraction of unemployed who receive UI, which counts all UI payments during the month, and for the wage measures which include total earnings over the month. We account for this issue in Table 4 by taking a difference of these variables with respect to their $t-2$ value.
Table 4: Response of Variables to UI Error Innovation

<table>
<thead>
<tr>
<th>Horizon:</th>
<th>Levels</th>
<th>Differences</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>1</td>
<td>4</td>
</tr>
<tr>
<td>1. Unemployment rate</td>
<td>0.003</td>
<td>−0.003</td>
</tr>
<tr>
<td></td>
<td>(0.008)</td>
<td>(0.014)</td>
</tr>
<tr>
<td>2. Fraction Receiving UI</td>
<td>0.694**</td>
<td>−0.036</td>
</tr>
<tr>
<td></td>
<td>(0.234)</td>
<td>(0.246)</td>
</tr>
<tr>
<td>3. Log Vacancies</td>
<td>0.002</td>
<td>0.003</td>
</tr>
<tr>
<td></td>
<td>(0.004)</td>
<td>(0.005)</td>
</tr>
<tr>
<td>4. Log Payroll Employment</td>
<td>0.000</td>
<td>0.000</td>
</tr>
<tr>
<td></td>
<td>(0.000)</td>
<td>(0.000)</td>
</tr>
<tr>
<td>5. Labor Force Participation Rate</td>
<td>0.001</td>
<td>0.001</td>
</tr>
<tr>
<td></td>
<td>(0.017)</td>
<td>(0.020)</td>
</tr>
<tr>
<td>6. Log Earnings (All Workers)</td>
<td>0.001</td>
<td>−0.001</td>
</tr>
<tr>
<td></td>
<td>(0.002)</td>
<td>(0.002)</td>
</tr>
<tr>
<td>7. Log Earnings (New Hires)</td>
<td>−0.000</td>
<td>0.003</td>
</tr>
<tr>
<td></td>
<td>(0.003)</td>
<td>(0.004)</td>
</tr>
</tbody>
</table>

Notes: Each cell reports the result from a separate regression of the dependent variable indicated in the left column on the innovation in the UI error $\epsilon_{s,t}$, controlling for state and period fixed effects and 12 monthly or 4 quarterly lags of $u_{s,t}$. In the panel headlined “Levels” the dependent variable enters in levels. In the panel headlined “Differences” the dependent variable enters with a difference relative to its value in $t-1$ (rows 1, 3, 4, 5) or $t-2$ (rows 2, 6, 7). Standard errors clustered by state and time period are shown in parentheses. ** denotes significance at the 1% level.

Collectively, these results provide direct evidence of the limited macroeconomic effects of increasing the duration of unemployment benefits around the neighborhood of a typical UI error, or by about 3 months after a state has already extended benefits by nearly one year. Extrapolating linearly the upper bound of a 0.02 percentage point increase in the unemployment rate with respect to a one-month UI error innovation, we obtain that moving from 26 to 99 weeks of benefits would increase the unemployment rate by roughly $0.02 \times 17 \approx 0.3$ percentage points.\footnote{Our estimates are also informative for potential stimulus effects of benefit extensions. Applying an average lower bound of $-0.03$ percentage point, we obtain that the extension of benefits from 26 to 99 weeks decreased the unemployment rate by at most 0.5 percentage point. This bound encompasses the estimates of Di Maggio and Kermani (2015) who find a UI output multiplier of 1.9. Total EB and EUC payments between 2009 and 2013 were $50.5$ billion, $79.2$ billion, $58.7$ billion, $39.7$ billion, and $22.0$ billion. Applying a multiplier of 1.9 to the peak amount of $79.2$ billion in 2010 gives an increase in output in 2010 of 1.0% of GDP. An application of Okun’s law...}
However, this calculation neglects potential non-linear effects of the extension length and the lower persistence of a UI error relative to a policy that increases maximum benefits to 99 weeks as in the Great Recession. In Section 4 we account for these effects within a DMP model and obtain similar results.\footnote{Non-linearities may arise, for example, because the fraction of unemployed affected by the extension of the duration of benefits declines in the duration of benefits. We have estimated regressions interacting the UI error innovation with bins of the duration of benefits ($T^* < 8$, $8 \leq T^* < 12$, $12 \leq T^* < 16$, and $T^* \geq 16$). As expected, the effect of a UI error innovation on the fraction of unemployed receiving UI is declining in $T^*$. However, we find little variation in the effect of a UI error innovation on the unemployment rate, with a maximum point estimate below 0.01.}

### 3.2 Robustness to Controlling for $\hat{u}_{s,t}$

**Identification.** In Section 2.2, we distinguished three sources of revisions to the state unemployment rate. One of these, the use of a state space smoother in the revision process, makes the revised unemployment rate in each month dependent on the full available time series of the input variables at the point of revision. This dependence raises a concern that the unemployment rate revision in month $t$ partly depends on realizations of variables after month $t$. Importantly for our empirical design, we found that this source of revisions contributes little to the variation in $\hat{u}_{s,t}$ and hence $\epsilon_{s,t}$. Nonetheless, we now implement an identification strategy which remains valid even if the revisions process induces a correlation between $\hat{u}_{s,t}$ and the future path of variables.

We augment our baseline specification to:

$$y_{s,t+h} = \beta(h)\epsilon_{s,t} + g(\{\hat{u}_{s,t}\}) + \sum_{j=1}^{12} \gamma_j(h)u_{s,t-j} + d_s(h) + d_t(h) + \nu_{s,t+h},$$

where the flexible function $g(\cdot)$ may allow for leads, lags, and non-linear transformations of the measurement error in the unemployment rate $\hat{u}_{s,t}$. Specification (6) controls directly for any correlation between functions of $\hat{u}_{s,t}$ and the future path of $y_{s,t+h}$ which may arise from the revision process.

To build intuition for specification (6), it helps to start with the case where $y_{s,t+h} = u_{s,t+h}$ and $g(\cdot) = \rho(h)\hat{u}_{s,t-1}$. Recalling that $\epsilon_{s,t}$ depends on data in period $t - 1$ due to reporting yields a 0.3-0.5 percentage point decline in the unemployment rate in that year. The 0.5 percentage point bound is smaller than the effect found in Kekre (2016) based on a calibrated model.
lags, $\hat{u}_{s,t-1}$ controls for the measurement error in the unemployment rate during the same month as the data which determines $\epsilon_{s,t}$. The term $\rho(h)\hat{u}_{s,t-1}$, therefore, partials out any “normal” covariation between $\hat{u}_{s,t-1}$ and $u_{s,t+h}$ which might result from the revision process. The identification exploits the fact that the mapping between $\hat{u}_{s,t-1}$ and $\hat{T}_{s,t}$ is not strictly monotonic; there are many instances of measurement error in the unemployment rate which do not give rise to a UI error, as illustrated in Figure 1 in the case of Vermont. Formally, the identification assumption becomes $\mathbb{E}[\epsilon_{s,t} \times \nu_{s,t+h}|X_{s,t}, \hat{u}_{s,t-1}] = 0$. A sufficient condition for this to hold is that any correlation between the unemployment rate measurement error $\hat{u}_{s,t-1}$ and the future path of unemployment does not change if $\hat{u}_{s,t-1}$ causes a UI error, except through the direct response of future variables to the UI error. That is, $\mathbb{E}[u_{s,t+h}|X_{s,t}, \hat{u}_{s,t-1}, \epsilon_{s,t} = \epsilon] = \mathbb{E}[u_{s,t+h}|X_{s,t}, \hat{u}_{s,t-1}, \epsilon_{s,t} = 0] + \beta(h)\epsilon = \Gamma(h)X_{s,t} + \rho(h)\hat{u}_{s,t-1} + \beta(h)\epsilon$. Including leads, lags, or non-linear transformations of $\hat{u}_{s,t-1}$ in the function $g(\cdot)$ allows for the baseline correlation of $\hat{u}_{s,t-1}$ and $u_{s,t+h}$ to vary with the level or path of $\hat{u}_{s,t}$.

**Results.** We begin in Figure 5 by reporting the impulse response functions for the unemployment rate $u_{s,t}$ and the total fraction receiving benefits $\phi_{s,t}$ based on specification (6) with only $\hat{u}_{s,t-1}$ added to the regression. Both impulse response functions appear nearly identical to those without the measurement error in the unemployment rate control. Specifically, the response of unemployment to a positive one-month UI error innovation is essentially zero while the fraction of unemployed receiving UI increases by roughly 0.5 percentage point.

We next allow for more flexible functions of the measurement error in the unemployment rate to enter into the specification. Table 5 reports the one and four month responses of the unemployment rate, the fraction of unemployed receiving UI, and log vacancies. Each cell of the table reports the coefficient or standard error on the UI error innovation $\epsilon_{s,t}$ from a separate regression of the dependent variables in the columns on the UI error innovation, the baseline controls of twelve lags of the unemployment rate and state and month fixed effects, and the additional controls for the measurement error in the unemployment rate shown in the rows. Row 1 reports coefficients when controlling only for $\hat{u}_{s,t-1}$. Row 2 adds 12 leads and lags of $\hat{u}_{s,t}$. Row
Figure 5: Impulse Responses Controlling for Measurement Error $\hat{u}_{s,t}$

Notes: The figure plots the coefficients on $\epsilon_{s,t}$ from the regression $y_{s,t+h} = \beta(h)\epsilon_{s,t} + \rho(h)\hat{u}_{s,t-1} + \sum_{j=1}^{12} \gamma_j(h)u_{s,t-j} + d_s(h) + d_t(h) + \nu_{s,t+h}$, where $y_{s,t+h} = u_{s,t+h}$ is the unemployment rate (left panel) or $y_{s,t+h} = \phi_{s,t+h}$ is the fraction of unemployed receiving UI on all tiers (right panel). The dashed lines denote the 90 percent confidence interval based on two-way clustered standard errors.

Table 5: Sensitivity of Impulse Responses to Controlling for Measurement Error $\hat{u}_{s,t}$

<table>
<thead>
<tr>
<th>Additional controls</th>
<th>Unemployment Rate</th>
<th>Fraction Receiving</th>
<th>Log Vacancies</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Horizon: 1 4</td>
<td>1 4</td>
<td>1 4</td>
</tr>
<tr>
<td>1. $\hat{u}_{s,t-1}$</td>
<td>0.010 (0.008)</td>
<td>0.010 (0.014)</td>
<td>0.596** (0.214)</td>
</tr>
<tr>
<td>2. ${\hat{u}<em>{s,t+j}}</em>{j=-12}^{12}$</td>
<td>0.012 (0.009)</td>
<td>0.013 (0.014)</td>
<td>0.585** (0.214)</td>
</tr>
<tr>
<td>3. $\hat{u}<em>{s,t-1}, \hat{u}</em>{s,t-1}, \hat{u}_{s,t-1}$</td>
<td>0.010 (0.008)</td>
<td>0.009 (0.014)</td>
<td>0.604** (0.225)</td>
</tr>
<tr>
<td>4. $\hat{u}<em>{s,t-1}, \hat{u}</em>{s,t-1} * \mathbb{I}{\hat{u}_{s,t-1} \geq 0}$</td>
<td>0.010 (0.008)</td>
<td>0.010 (0.014)</td>
<td>0.601** (0.219)</td>
</tr>
<tr>
<td>5. $\hat{u}_{s,t-1} * \mathbb{I}{t \in \text{year}}$</td>
<td>0.007 (0.009)</td>
<td>0.004 (0.014)</td>
<td>0.554** (0.184)</td>
</tr>
</tbody>
</table>

Notes: Each cell reports the coefficient from a separate regression of the dependent variable indicated in the table header on the UI error innovation $\epsilon_{s,t}$, controlling for the baseline control variables, $\sum_{j=1}^{12} \gamma_j u_{s,t-j}$, $d_s$, and $d_t$, and the additional control variables indicated in the leftmost column of the row. Standard errors are clustered by state and time period and are reported in parentheses. ** denotes significance at the 1% level.

3 incorporates a cubic in $\hat{u}_{s,t-1}$ as a control. Row 4 allows the coefficient on $\hat{u}_{s,t-1}$ to depend on the sign of the unemployment rate measurement error. Row 5 allows the coefficient on $\hat{u}_{s,t-1}$
to vary by year so that $\rho(h)$ could change with the introduction of real-time benchmarking in 2005 or the higher average unemployment during the Great Recession.

Our results do not change significantly in any of these specifications. In particular, the responses of unemployment and vacancies to a UI error innovation are always close to zero and never statistically significantly different from zero, whereas we always detect an increase in the fraction of the unemployed receiving benefits. The stability of the point estimates across specifications and the close similarity to the baseline results shown above reinforces our baseline identifying assumption in Section 3.1.

### 3.3 Further Robustness

In this section we investigate the robustness of our main findings along various other dimensions. Table 6 compares the one and four month responses of the unemployment rate, the fraction of unemployed receiving UI, and log vacancies in the baseline specification to the responses in various alternative specifications. The first row of the table repeats the baseline results from Section 3.1.

Row 2 removes the lags of the unemployment rate from the specification. We obtain very similar results to the baseline. Row 3 removes the lags of the unemployment rate and the state $d_s$ and month $d_t$ fixed effects from the specification (so there are no controls). We again find similar point estimates. However, the standard errors more than double in row 3 with no controls because fixed effects absorb a large fraction of the variation in outcome variables unrelated to the UI error innovation.

Next, we assess the robustness of our results to the assumed process for the UI errors used in extracting the innovations. In Section 2.4 we imposed a first-order Markov process that generalizes the autoregressive persistence usually imposed on macroeconomic data to account for the sparsity and non-linearity of the UI error process. In row 4, we instead simply first difference the UI error and replace $\epsilon_{s,t}$ in equation (5) with $\Delta \hat{T}_{s,t} = \hat{T}_{s,t} - \hat{T}_{s,t-1}$. Under this transformation, we again obtain very similar results to the baseline results.

In row 5, we report the coefficient on the level of $\hat{T}_{s,t}$ but controlling for twelve lags of $\hat{T}_{s,t}$. 

27
Table 6: Additional Sensitivity Checks of Impulse Responses

<table>
<thead>
<tr>
<th>Coefficient</th>
<th>Controls</th>
<th>Unemployment Rate</th>
<th>Fraction Receiving Vacancies</th>
<th>Log Rate Receiving Vacancies</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. $\epsilon_{s,t}$</td>
<td>${u_{s,t-j}}_{j=1}^{12}, d_s, d_t$</td>
<td>0.003</td>
<td>-0.003</td>
<td>0.694**</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(0.008)</td>
<td>(0.014)</td>
<td>(0.234)</td>
</tr>
<tr>
<td>2. $\epsilon_{s,t}$</td>
<td>$d_s, d_t$</td>
<td>-0.013</td>
<td>-0.022</td>
<td>0.632**</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(0.023)</td>
<td>(0.024)</td>
<td>(0.217)</td>
</tr>
<tr>
<td>3. $\epsilon_{s,t}$</td>
<td>None</td>
<td>-0.002</td>
<td>-0.026</td>
<td>0.507</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(0.072)</td>
<td>(0.072)</td>
<td>(0.614)</td>
</tr>
<tr>
<td>4. $\Delta \hat{T}_{s,t}$</td>
<td>${u_{s,t-j}}_{j=1}^{12}, d_s, d_t$</td>
<td>0.003</td>
<td>0.004</td>
<td>0.514**</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(0.007)</td>
<td>(0.011)</td>
<td>(0.123)</td>
</tr>
<tr>
<td>5. $\hat{T}_{s,t}$</td>
<td>${\hat{T}<em>{s,t-j}}</em>{j=1}^{12}, {u_{s,t-j}}_{j=1}^{12}, d_s, d_t$</td>
<td>0.002</td>
<td>-0.002</td>
<td>0.841**</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(0.007)</td>
<td>(0.013)</td>
<td>(0.246)</td>
</tr>
</tbody>
</table>

Notes: Each cell reports the coefficient from a separate regression of the dependent variable indicated in the table header on the right-hand side variable indicated in the leftmost column of the row, controlling for the variables indicated in the second column of the row. Standard errors are clustered by state and time period and are reported in parentheses. **, + denote significance at the 1% and 10% level.

This specification is conceptually similar to defining the UI error innovation as the structural residual from a VAR(12) in $\hat{T}_{s,t}$ and $u_{s,t}$ with $\hat{T}_{s,t}$ first in a Cholesky ordering. Comparing row 5 to the previous results, we see that the limited response of unemployment and vacancies and the significantly positive response of the fraction receiving UI remain robust to this way of defining the innovations.

### 3.4 Are Revisions Informative About Fundamentals?

The information content of the revised data matters for our results. If revisions contained little new economic information, then the error component of the benefit duration would be relatively

---

26Formally, after demeaning with respect to the state and month fixed effects, the specification is a Jordà (2005) local projection based on a bivariate system in $u_{s,t}$ and $\hat{T}_{s,t}$ with twelve lags and $\hat{T}_{s,t}$ being first in the Cholesky ordering. The Cholesky identification assumption is that the forecast error in $\hat{T}_{s,t}$ does not respond to the contemporaneous structural innovation to the unemployment rate. As a justification for the ordering, recall that due to reporting lags UI benefits in month $t$ are only a function of unemployment rates for month $t - 1$ and earlier.
uninformative for estimating the effects of benefit extensions on labor market outcomes. Additionally, even if the revised data better reflect the economy’s fundamentals, whether firms and workers respond to these fundamentals or to the data published in real time matters for the interpretation of our results.

We have already presented two types of evidence consistent with the data revisions containing new information. First, we described the new source data and methodological improvements incorporated in the revisions process. Second, we would not have obtained the economically significant response of the fraction of unemployed receiving benefits to innovations in the UI error if the revised data added only noise to the real-time estimates. We now show that the data revisions contain information for economic choices and beliefs in real time. These results further substantiate the information content of the revisions and provide direct evidence that agents base their decisions on the true economic fundamentals rather than data published in real time.

Our first result pertains to whether the revised or real-time unemployment rate better correlates with actual consumer spending. We estimate a horse-race specification:

\[
y_{s,t} = \beta^{\text{revised}} u_{s,t-2}^{\text{revised}} + \beta^{\text{real-time}} u_{s,t-2}^{\text{real-time}} + \nu_{s,t},
\]

where \(y_{s,t}\) denotes either new auto registrations (from R.L. Polk) or new building permits (from the Census Bureau). Both series reflect spending done by a state’s residents, derive from actual registration data, and have no mechanical correlation with either the real-time or the revised unemployment rate. We interpret the coefficients \(\beta^{\text{revised}}\) and \(\beta^{\text{real-time}}\) as the weights one should assign to the revised and real-time unemployment rates as statistical predictors of spending behavior. The unemployment rates enter the regression with a two-month lag to reflect the timing of the release of the LAUS state unemployment data, which usually occurs for month \(t - 1\) around the 20th day of month \(t\). Therefore, agents at the beginning of month \(t\) have access to the real-time unemployment rate for month \(t - 2\) but not for month \(t - 1\) or \(t\). Agents do not know the revised unemployment rate for \(t - 2\) at the start of month \(t\), but may know the economy’s true fundamentals. Under the maintained assumption that higher
Table 7: Spending Decisions and Unemployment Data

<table>
<thead>
<tr>
<th>Dependent Variable</th>
<th>Auto Sales</th>
<th>Building Permits</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>(1)</td>
<td>(2)</td>
</tr>
<tr>
<td>Revised UR_{s,t-2}</td>
<td>−0.42**</td>
<td>−0.52**</td>
</tr>
<tr>
<td></td>
<td>(0.11)</td>
<td>(0.13)</td>
</tr>
<tr>
<td>Real-time UR_{s,t-2}</td>
<td>−0.34**</td>
<td>0.09+</td>
</tr>
<tr>
<td></td>
<td>(0.10)</td>
<td>(0.05)</td>
</tr>
<tr>
<td>State FE</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Time FE</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Dep. var. mean</td>
<td>5.4</td>
<td>5.4</td>
</tr>
<tr>
<td>Dep. var. sd</td>
<td>2.0</td>
<td>2.0</td>
</tr>
<tr>
<td>R²</td>
<td>0.61</td>
<td>0.61</td>
</tr>
<tr>
<td>Observations</td>
<td>10,096</td>
<td>9,847</td>
</tr>
</tbody>
</table>

Notes: The dependent variable is indicated in the table header. The auto sales data come from R.L. Polk and correspond to the state of residency of the purchaser. The permits data are for new private housing units and come from the Census Bureau. Standard errors are clustered by state and month and denoted in parentheses. **, *, + denote significance at the 1%, 5%, and 10% level.

unemployment is associated with lower spending, a finding of $\beta_{\text{revised}} < 0$ and $\beta_{\text{real-time}} = 0$ provides support for the joint hypothesis that revised data improve the quality of measurement of economic fundamentals and that agents in real time base their decisions on these fundamentals and ignore the measurement error.

Table 7 reports the results. Columns 1, 2, 4, and 5 show that both the revised and the real-time unemployment rates are negatively correlated with spending. The key results are shown in columns 3 and 6 in which we introduce jointly both variables in regression (7). For both auto sales and building permits, we estimate $\beta_{\text{revised}} < 0$ and $\beta_{\text{real-time}} \approx 0$. The revised unemployment rate contains all the information about spending patterns and, given knowledge of both series, one should put essentially no weight on the real-time data to predict actual spending.

Survey responses from the Michigan Survey of Consumers (MSC) provide further evidence that the revised unemployment data contains significant information. The MSC asks 500 re-
Table 8: Beliefs and Unemployment Data

<table>
<thead>
<tr>
<th>Dependent Variable</th>
<th>AVG (1)</th>
<th>PJOB (2)</th>
<th>PEXP (3)</th>
<th>PINC2 (4)</th>
<th>INEX (5)</th>
<th>DUR (6)</th>
<th>CAR (7)</th>
<th>BUS12 (8)</th>
<th>BUS5 (9)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Revised UR_{s,t-2}</td>
<td>0.028+</td>
<td>0.663*</td>
<td>0.012</td>
<td>-1.086*</td>
<td>-0.186</td>
<td>0.043*</td>
<td>0.025</td>
<td>0.007</td>
<td>0.004</td>
</tr>
<tr>
<td></td>
<td>(0.015)</td>
<td>(0.310)</td>
<td>(0.016)</td>
<td>(0.476)</td>
<td>(0.224)</td>
<td>(0.021)</td>
<td>(0.018)</td>
<td>(0.034)</td>
<td>(0.027)</td>
</tr>
<tr>
<td>Real-time UR_{s,t-2}</td>
<td>-0.015</td>
<td>-0.472</td>
<td>-0.006</td>
<td>0.477</td>
<td>0.042</td>
<td>-0.025</td>
<td>-0.016</td>
<td>0.005</td>
<td>-0.007</td>
</tr>
<tr>
<td></td>
<td>(0.011)</td>
<td>(0.310)</td>
<td>(0.012)</td>
<td>(0.403)</td>
<td>(0.197)</td>
<td>(0.018)</td>
<td>(0.015)</td>
<td>(0.027)</td>
<td>(0.021)</td>
</tr>
<tr>
<td>State FE</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Time FE</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Weighted</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Individual controls</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Dep. var. mean</td>
<td>-0.01</td>
<td>18.82</td>
<td>2.61</td>
<td>46.02</td>
<td>3.31</td>
<td>2.08</td>
<td>2.22</td>
<td>3.18</td>
<td>3.14</td>
</tr>
<tr>
<td>Dep. var. sd</td>
<td>1.00</td>
<td>25.16</td>
<td>1.31</td>
<td>36.95</td>
<td>16.50</td>
<td>1.73</td>
<td>1.81</td>
<td>1.92</td>
<td>1.79</td>
</tr>
<tr>
<td>R^2</td>
<td>0.16</td>
<td>0.47</td>
<td>0.83</td>
<td>0.71</td>
<td>0.14</td>
<td>0.64</td>
<td>0.64</td>
<td>0.78</td>
<td>0.79</td>
</tr>
<tr>
<td>Observations</td>
<td>82,291</td>
<td>81,719</td>
<td>80,529</td>
<td>70,036</td>
<td>79,425</td>
<td>78,631</td>
<td>78,626</td>
<td>75,571</td>
<td>79,123</td>
</tr>
</tbody>
</table>

Notes: The dependent variable is indicated in the table header. AVG: simple mean of normalized variables with higher values denoting worse subjective expectations. PJOB: chance will lose job in 5 years. PEXP: personal finances b/w next year (1: Will be better off. 3: Same. 5: Will be worse off). PINC2: percent chance of income increase. INEX: family income expectations 1 year recoded. DUR: durables buying attitudes (1: Good. 3: Pro-con. 5: Bad). CAR: vehicle buying attitudes (1: Good. 3: Pro-con. 5: Bad). BUS12: economy good/bad next year (1: Good times. 2: Good with qualifications. 3: Pro-con. 4: Bad with qualifications. 5: Bad times). BUS5: economy good/bad next 5 years (1: Good times. 2: Good with qualifications. 3: Pro-con. 4: Bad with qualifications. 5: Bad times). Individual controls: sex, marital status, age, age^2, age^3, four educational attainment categories, and log income, each interacted with month. Regressions are weighted using survey weights. Standard errors are clustered by state and month and denoted in parentheses. *, + denote significance at the 5% and 10% level.

Respondents each month a series of questions covering their own financial situation and their views on the economy. For survey months in or after the year 2000, the Michigan Survey Research Center allowed us to merge external state-level data to anonymized responses. Because sample sizes are too small to aggregate to the state-month level, we instead run our horse-race regression at the individual level and cluster standard errors by state and by month:

\[ y_{i,s,t} = \beta \text{Revised } u_{s,t} + \beta \text{Real-time } u_{s,t} + \Gamma X_{i,s,t} + \nu_{i,s,t}. \]  

Table 8 reports results for a subset of questions in the survey that we expect to correlate with the local unemployment rate. For brevity, we report only specifications with both unemployment rates. Averaging across the eight outcomes we consider, the first column shows that a
higher revised unemployment rate is associated with worse subjective perceptions of economic conditions. It also shows that, conditional on the revised unemployment rate, the real-time unemployment rate appears to add no information. This result repeats in various individual outcomes as shown in columns 2 to 9.

We use the results in Tables 7 and 8 to assess how our conclusions could change if the revised data do not measure perfectly the true unemployment rate. Measurement error in the revised unemployment rate would cause measurement error in the UI error $\hat{T}_{s,t}$ and the innovations $\epsilon_{s,t}$ and lead to attenuation bias in the specifications reported in the previous sections. In Appendix B we develop a formula for such attenuation bias and show that it is decreasing in the information content of the revisions. Using the results in this section that the revised data better align with true economic fundamentals than the real-time data, we derive a conservative upper bound for the possible attenuation bias. Applying this upper bound to the confidence interval upper bound of a 0.02 percentage point increase in the unemployment rate in response to a one-month UI error innovation yields a maximum response of 0.04 percentage point.

4 DMP Model with UI Benefit Extensions

In this section we use our empirical results in conjunction with a standard DMP model (Diamond, 1982; Mortensen and Pissarides, 1994) to inform the policy debate on the macroeconomic effects of benefit extensions during the Great Recession. Our empirical estimates suggest a small macroeconomic effect of extending benefits. However, the relationship between unemployment and benefit extensions may be non-linear and depends on expectations of the future path of the extensions. We show how our empirical results discipline a model which accounts for these effects.

Table 9 previews the results and summarizes our logic. In the first step of our argument, we show that an economy parameterized with a low value of benefits $b$ in the opportunity cost of employment matches the small response of unemployment to a one-month UI error innovation (less than 0.02 percentage point). In contrast, in an economy with a high $b$, the response of
Table 9: Effects of Benefit Extensions on Unemployment

<table>
<thead>
<tr>
<th>Data</th>
<th>DMP Models</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>High $b$</td>
</tr>
<tr>
<td>Response of $u_t$ to $\epsilon_t$ (max)</td>
<td>$&lt; 0.02$ pp</td>
</tr>
<tr>
<td>Effect of extensions on $u_t$ during a recession (3-year)</td>
<td>3.1 pp</td>
</tr>
</tbody>
</table>

unemployment to a one-month UI error innovation is almost an order of magnitude larger (0.14 percentage point). In the second step of our argument, we subject both economies to a sequence of large negative shocks that increase unemployment and cause benefits to extend from 6 to 20 months. As the last row of the table shows, removing the benefit extensions lowers the unemployment rate in the low $b$ model by much less than in the high $b$ model. Because only the low $b$ model matches the response of unemployment to a one-month UI error innovation, we conclude that benefit extensions play a limited role in affecting unemployment during a recession.

4.1 Model Description

We augment a DMP model with a UI policy to analyze the labor market effects of benefit extensions. The model deviates minimally from the standard model in the literature and shares many features with the models used by Hagedorn, Karahan, Manovskii, and Mitman (2015) and Mitman and Rabinovich (2014) to argue that benefit extensions cause unemployment to remain persistently high following a negative shock. The different conclusion that we reach regarding the role of benefit extensions for macroeconomic outcomes arises because our empirical estimates in Section 3 imply a lower level of the opportunity cost than assumed by these papers.

**Labor Market and Eligibility Flows.** Each period a measure $u_t$ of unemployed search for jobs and a measure $1 - u_t$ of employed produce output. Unemployed individuals find jobs at
a rate $f_t$ which is determined in equilibrium. Employed individuals separate from their jobs at an exogenous rate $\delta_t$. The law of motion for unemployment is:

$$u_{t+1} = (1 - f_t)u_t + \delta_t(1 - u_t). \quad (9)$$

Employed individuals who lose their jobs become eligible for UI benefits with probability $\gamma$. There are $u^E_t$ unemployed who are eligible for and receive UI benefits. Eligible unemployed who do not find jobs lose their eligibility with probability $e_t$. The key policy variable in our model is the (expected) duration of benefits $T^*_t$ which equals the inverse of the expiration probability, $T^*_t = 1/e_t$. Finally, there are $u_t - u^E_t$ ineligible unemployed. Ineligible unemployed who do not find jobs remain ineligible for UI benefits.

We denote by $\omega_t = u^E_t/u_t$ the fraction of unemployed who are eligible for and receive UI. This fraction evolves according to the law of motion:

$$\omega_{t+1} = \frac{\delta_t \gamma (1 - u_t)}{u_{t+1}} + \left( \frac{u_t (1 - f_t)(1 - e_t)}{u_{t+1}} \right) \omega_t. \quad (10)$$

**Household Values.** All individuals are risk-neutral and discount the future with a factor $\beta$. Employed individuals consume their wage earnings $w_t$. The value of an individual who begins period $t$ as employed is given by:

$$W_t = w_t + \beta (1 - \delta_t) \mathbb{E}_t W_{t+1} + \beta \delta_t \left( \gamma \mathbb{E}_t U^E_{t+1} + (1 - \gamma) \mathbb{E}_t U^I_{t+1} \right), \quad (11)$$

where $U^E_t$ denotes the value of an eligible unemployed and $U^I_t$ denotes the value of an ineligible unemployed. These values are given by:

$$U^E_t = \xi + B + \beta f_t \mathbb{E}_t W_{t+1} + \beta (1 - f_t) \left( e_t \mathbb{E}_t U^I_{t+1} + (1 - e_t) \mathbb{E}_t U^E_{t+1} \right), \quad (12)$$

$$U^I_t = \xi + \beta f_t \mathbb{E}_t W_{t+1} + \beta (1 - f_t) \mathbb{E}_t U^I_{t+1}. \quad (13)$$

---

27 For expository reasons, in the model $T^*_t$ denotes the total duration of benefits (including the regular benefits), whereas in the data we defined $T^*_t$ as the extension of benefits beyond their regular duration.

28 In the data we have a measure of the fraction of unemployed who receive UI benefits (the variable $\phi$) based on administrative data on UI payments. Constructing a high quality panel of take-up rates at the state-month level is not feasible with currently available data. A difference relative to the model of Chodorow-Reich and Karabarbounis (2016) is that, because of this data unavailability, here we do not consider the take-up decision of an unemployed who is eligible for benefits. Therefore, we use interchangeably the terms eligibility for UI benefits and receipt of UI benefits.
where $\xi$ is the value of non-market work and $B$ is the UI benefit per eligible unemployed.\footnote{Benefit extensions were federally funded between 2009 and 2013. We think of our model as applying to an individual state during this period and, therefore, we do not impose UI taxes on firms.} We assume that both $\xi$ and $B$ are constant over time. This allows us to focus entirely on the role of benefit extensions for fluctuations in the opportunity cost of employment.\footnote{In previous work (Chodorow-Reich and Karabarbounis, 2016), we found that the $\xi$ component of the opportunity cost is procyclical. Benefit extensions typically occur when unemployment is high and $\xi$ is low. However, our empirical exercise compares two states with different duration of benefits that have the same economic fundamentals and, therefore, it is appropriate to not control for $\xi$ in our regressions. The constancy of $\xi$ in the model is conservative for our conclusions in this section. Allowing $\xi$ to respond endogenously would lead to an even smaller effect of benefit extensions on unemployment because the decline in $\xi$ would tend to offset the increase in the value of benefits (denoted $b$ below) in the opportunity cost $z = \xi + b$.}

**Surplus and Opportunity Cost of Employment.** Firms bargaining with workers over wages cannot discriminate with respect to workers’ eligibility status. Therefore, there is a common wage for all unemployed. This implies that we need to keep track of values and flows for the average unemployed. We define the value of the average unemployed individual as:

$$U_t = \omega_t U^E_t + (1 - \omega_t) U^I_t.$$  

(14)

The surplus of employment for the average unemployed is given by the difference between the value of working and the value of unemployment. We take:

$$S_t = W_t - U_t = w_t - z_t + \beta(1 - \delta_t - f_t) \mathbb{E}_t S_{t+1},$$

(15)

where $z_t$ denotes the (flow) opportunity cost of employment for the average unemployed.

The opportunity cost of employment is defined as the flow utility that an unemployed forgoes upon moving to employment. It is given by:

$$z_t = \xi + \omega_t B - (\delta_t (\gamma - \omega_t) + (1 - f_t)\omega_t e_t) \beta \left( \mathbb{E}_t U^E_{t+1} - \mathbb{E}_t U^I_{t+1}\right),$$

(16)

where $b_t$ denotes the benefit component of the opportunity cost of employment. The expression nests the standard model (for instance, Shimer, 2005) that has $b_t = B$ if $e_t = 0$, that is when benefits do not expire, and $\gamma = \omega_t = 1$, that is when all unemployed are eligible for benefits. More generally, the flow utility loss $b_t$ of moving an average unemployed to employment is lower
than the benefit $B$. The difference occurs because some unemployed are not eligible for benefits and, even for those unemployed who are eligible, benefits will eventually expire.\footnote{The first effect is captured by the first term of $b_t$ which is lower than $B$ when $\omega_t < 1$. The second effect is captured by the second term which is positive because $\gamma > \omega_t$ and $E_t U_{t+1}^E > E_t U_{t+1}^I$.} Additionally, $b_t$ is in general time varying. Extending benefits, which here means a decline in the expiration probability $e_t$, increases the fraction of unemployed who are eligible $\omega_t$ and raises $b_t$ and the opportunity cost of employment $z_t$.

**Firm Value, Matching, and Bargaining.** The value of a firm from matching with a worker is given by:

$$J_t = p_t - w_t + \beta (1 - \delta_t) E_t J_{t+1}, \quad (17)$$

where $p_t$ denotes aggregate labor productivity. There is free entry and, therefore, the expected value of creating a vacancy equals zero:

$$\frac{\kappa}{q_t} = \beta E_t J_{t+1}, \quad (18)$$

where $\kappa$ denotes the upfront cost that an entrant pays to create a vacancy and $q_t$ denotes the rate at which vacancies are filled.

Trade in the labor market is facilitated by a constant returns to scale matching technology that converts searching by the unemployed and vacancies by firms into new matches, $m_t = M v_t^\eta u_t^{1-\eta}$. We denote by $\eta$ the elasticity of the matching function with respect to vacancies. We define market tightness as $\theta_t = v_t / u_t$. An unemployed matches with a firm at a rate $f_t(\theta_t) = m_t / u_t$ and firms fill vacancies at a rate $q_t(\theta_t) = m_t / v_t = f_t(\theta_t) / \theta_t$.

Firms and workers split the surplus from an additional match according to the generalized Nash bargaining solution. We denote by $\mu$ the bargaining power of workers. The wage is chosen to maximize the product $S_t^\mu J_t^{1-\mu}$, where $J_t$ in equation (17) is a firm’s surplus of employing a worker and $S_t$ in equation (15) is the surplus that the average unemployed derives from becoming employed. This leads to a standard wage equation:

$$w_t = \mu p_t + (1 - \mu) z_t + \mu \kappa \theta_t. \quad (19)$$
The wage is an increasing function of labor productivity, the opportunity cost, and market tightness.

**UI Policy.** The duration of UI benefits is given by $T^*_t = T_t + \hat{T}_t$, where $T_t$ denotes the duration of UI benefits in the absence of any measurement error and $\hat{T}_t$ is the UI error. Consistent with the results in Section 3.4 that agents respond only to the revised unemployment rate, we assume that firms and workers know the underlying fundamentals (for instance, $u_t, p_t, w_t$ etc.) at the beginning of each period. The statistical agency makes errors in the measurement of the true unemployment rate which result in UI errors $\hat{T}_t$.

The process for $T_t$ is:

$$T_t = \begin{cases} 
T^1, & \text{if } 0 \leq u_t < \bar{u}^1, \\
T^2, & \text{if } \bar{u}^1 \leq u_t < \bar{u}^2, \\
\vdots \\
T^J, & \text{if } \bar{u}^{J-1} \leq u_t < \bar{u}^J = 1.
\end{cases}$$

(20)

The UI error follows a first-order Markov process $\pi_T(\hat{T}_t | \hat{T}_{t-1}; u_t)$. As in the data, the unemployment rate enters into the Markov process to capture the fact that UI errors occur only in particular regions of the state space.\footnote{The timing convention in our model follows the convention in the DMP literature in which the unemployment rate $u_t$ is a state variable and has been determined in period $t-1$. For this reason UI policy in the model depends on $u_t$. We remind the reader than in the data the unemployment rate in period $t-1$ determines the extension of benefits in period $t$.}

**Equilibrium.** The state vector of the economy is given by $x_t = [u_t, \omega_t, p_t, \delta_t, \hat{T}_t]$. Given exogenous and known processes for $p_t$, $\delta_t$, and $\hat{T}_t$, an equilibrium of this model consists of functions of the state vector:

$$\{u_{t+1}(x_t), \omega_{t+1}(x_t), \theta_t(x_t), W_t(x_t), U_t^E(x_t), U_t^I(x_t), w_t(x_t), J_t(x_t), b_t(x_t), T_t(x_t)\},$$

such that: (i) The law of motion for unemployment (9) and the law of motion for eligibility (10) are satisfied. (ii) Worker values in equations (11), (12), and (13) are satisfied. (iii) The
firm value is given by equation (17) and the free-entry condition (18) holds. (iv) Wages are determined by equation (19), where the opportunity cost of employment is given by equation (16). (v) The duration of UI benefits in the absence of measurement error is given by the schedule (20). Starting from each state vector $x_t$, we have 10 equations to solve for the 10 unknowns. We discuss details of the computations in Appendix C.

**Effects of UI Policy in the Model.** An increase in the current duration of benefits $(T^*_t = 1/e_t)$ affects equilibrium outcomes to the extent that firms and workers expect it to persist in future periods. Combining equations (17) and (18), the decision to create a vacancy in the current period depends on the expectation of the present discounted value of firm profits:

$$
\frac{\kappa}{q_t(\theta_t)} = \mathbb{E}_t \sum_{j=1}^{\infty} \beta^j \left( \prod_{i=1}^{j} \frac{1 - \delta_{t+i-1}}{1 - \delta_t} \right) \left( p_{t+j} - w_{t+j} \right), \quad (21)
$$

where $q_t(\theta_t)$ is a decreasing function of current market tightness $\theta_t = v_t/u_t$. By raising the fraction of unemployed who are eligible for UI, an extension of benefits increases future opportunity costs and wages. The increase in wages lowers the expected present value of firm profits and decreases firms’ willingness to create vacancies in the current period. The decline in vacancies makes it more difficult for the unemployed to find jobs, which increases the unemployment rate.

**4.2 Parameterization**

A model period corresponds to a month. The schedule for the $T_t$ component of UI benefit duration is:

$$
T_t = \begin{cases} 
6, & \text{if } u_t < 0.065, \\
9, & \text{if } 0.065 \leq u_t < 0.08, \\
12, & \text{if } 0.08 \leq u_t < 0.09, \\
20, & \text{if } 0.09 \leq u_t.
\end{cases} \quad (22)
$$

For the UI error component, $\hat{T}_t$, we estimate the probabilities $\pi_T \left( \hat{T}_t \mid \hat{T}_{t-1}; u_t \right)$ in the data separately for each region $u_t < 0.06, 0.06 \leq u_t < 0.065$, and $u_t \geq 0.065$. 

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Table 10: Parameter Values

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<td>{0.05, 0.17}</td>
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</table>

Table 10 lists values for other parameters of the model. The discount factor equals $\beta = 0.997$. Log productivity follows an AR(1) process $\log p_{t+1} = \rho \log p_t + \sigma \nu_t^p$, with $\nu_t^p \sim N(0, 1)$, where from the data we estimate that at monthly frequency $\rho = 0.91$ and $\sigma = 0.008$. The mean separation rate is $\delta = 0.035$. We set the elasticity of the matching function with respect to vacancies to $\eta = 0.60$, worker’s bargaining power to $\mu = 0.40$, and the value of non-market work to $\xi = 0.81$. We then calibrate four parameters, $M$, $\gamma$, $B$, and $\kappa$, to hit four targets in the steady state of the model with no benefit extensions (so $T^\ast = 6$ months).

We parameterize two versions of the model. In the “low $b$” model we pick $B$ such that $b = 0.06$ in the steady state and so $z = \xi + b = 0.87$. The value of $b = 0.06$ accords with the finding in Chodorow-Reich and Karabarbounis (2016) that benefits comprise a small fraction of the average opportunity cost. In the “high $b$” model we pick $B$ such that $b = 0.15$ and $z = \xi + b = 0.96$. The value of $z = 0.96$ was found by Hagedorn and Manovskii (2008) to match the rigidity of wages with respect to productivity.

---

33 We target $\theta^T = 1$, $u^T = 0.055$, $\omega^T = 0.65$, and $b^T = \{0.06, 0.15\}$. Because we do not consider the take-up decision of the unemployed, $B$ should be understood as the after-tax value of benefits for the average eligible unemployed. This differs from the replacement rate per recipient because of taxes, utility costs of taking up benefits, and a take-up rate below one.

34 Our calibration is conservative in the sense that reducing the level of $\xi$ would produce even smaller effects of UI policy on aggregate outcomes. Chodorow-Reich and Karabarbounis (2016) show that, with standard preferences, $z$ is between 0.47 and 0.75. Hornstein, Krusell, and Violante (2011) argue that $z$ has to be even smaller in order for models to generate large frictional wage dispersion. Hall and Mueller (2015) also arrive at a small value of $z$ given the large observed dispersion in the value of a job. Costain and Reiter (2008) first pointed out that models with a high level of $z$ generate stronger effects of policies on labor market outcomes than the effects found in cross-country comparisons.
4.3 Impulse Responses With Respect to UI Error Innovations

In Figure 6 we plot the impulse of the unemployment rate with respect to a one-month UI error innovation using simulated data from our model. Following the logic outlined with the help of equation (21), the extension of UI benefits tends to reduce firm profits from filling a vacancy. In the high $b$ model, firm profits are already very small on average because average match surplus – the difference between the marginal product and the opportunity cost of employment – is small. Therefore, the extension of benefits lowers firm’s willingness to create vacancies substantially. As the left panel of Figure 6 shows, the maximal response of the unemployment rate is close to 0.14 percentage point in the high $b$ model.\footnote{In our model agents know the true fundamentals and, therefore, distinguish between a UI extension that results from an error and an extension that results from a change in the fundamentals. Because the persistence of $\hat{T}$ that we estimate in the data is lower than the persistence of the extensions we observe during the Great Recession, workers and firms in the model react to an extension of benefits caused by an error less than to an extension caused by a change in the fundamentals. We do not have a way of assessing empirically whether agents distinguish the source of benefit extensions and, therefore, our assumption that agents are fully informed about the two different causes of extensions makes the model response of unemployment to an innovation in $\hat{T}$ a lower bound.} In the low $b$ model depicted in the right panel, the unemployment rate increases by less than 0.02 percentage point. With a low $b$, firm profits are on average higher and the extension of benefits leads to smaller movements in equilibrium vacancies and unemployment.

In the data, we estimate that the unemployment rate increases by less than 0.02 percentage point when the UI error innovation increases by one month. Therefore, we conclude that the low $b$ model comes much closer than the high $b$ model in matching this response.\footnote{The difference between the two models does not reflect a failure of the low $b$ model to generate an increase in the fraction of unemployed receiving UI. We actually find that the fraction of eligible unemployed increases by more in the low $b$ model. In Appendix C we present the impulse responses for the fraction of unemployed receiving UI. We also show impulse responses for the opportunity cost and vacancies.}

4.4 Effects of Benefit Extensions on Unemployment

We now examine the effects of a benefit extension caused by a recession rather than by measurement error. We show that the macroeconomic effects are very different in the low $b$ relative to the high $b$ model.

For this experiment, we shut down all UI errors and set $\hat{T}_t = 0$ and $T^*_t = T_t$ for all periods. We start each of the low $b$ and high $b$ economies in a stochastic steady state in which no shock
Figure 6: Impulse Response of Unemployment Rate in the Model
Notes: The figure plots the coefficients on $\epsilon_t$ from the regression $u_{t+h} = \beta(h)\epsilon_t + \sum_{j=0}^{11} \gamma_j(h)u_{t-j} + \nu_{t+h}$ using data generated from model simulations.

Figure 7: Unemployment Path in the Model
Notes: The figure plots the path of unemployment in response to a sequence of negative shocks with and without benefit extensions in the high $b$ and the low $b$ model.

occurs for a large number of periods. Beginning in month 10, we introduce a sequence of shocks chosen so that unemployment reaches roughly 10 percent in the models with benefit extensions.
We depict the path of the shocks in Appendix C.\footnote{A well-known feature of the DMP model with a low opportunity cost is that it generates unemployment fluctuations of smaller magnitude than observed in the data. Following Shimer (2005), we introduce exogenous separation shocks to generate higher unemployment rates and benefit extensions. To reduce the dimensionality of the state space, we work with a process for the separation rate that depends on productivity, \( \delta_t = \delta \exp(\nu^\delta(p_t - 1)) \). We choose the parameter \( \nu^\delta \) such that both the high and the low \( b \) model generate a maximum unemployment rate of roughly 10 percent in Figure 7. We find \( \nu^\delta = 0 \) in the high \( b \) model (so we do not need exogenous separation shocks) and \( \nu^\delta = -10 \) in the low \( b \) model. In the latter model, \( \delta_t \) increases from 3.5 to roughly 5.5 percent as productivity declines. We stress that for the arguments in this paper it is not important how we generate high unemployment in the low \( b \) model. What is important is that, for some reason, the economy reaches a state where benefits are extended.}

In the left panel of Figure 7 we plot the paths of unemployment in the high \( b \) model under two different UI policy regimes. The upper line shows the path when the duration of benefits rises with unemployment according to the schedule (22). As unemployment rises, the duration of benefits is extended from the initial 6 months to eventually reach 20 months. Unemployment peaks at roughly 10 percent and remains persistently high. In the alternative UI policy regime, the duration of benefits always equals \( T_t^* = T_t = 6 \) months. The model without benefit extensions shares the same parameters and is subjected to the same sequence of shocks as the model with benefit extensions. Consistent with the conclusions of Mitman and Rabinovich (2014) and Hagedorn, Karahan, Manovskii, and Mitman (2015), the difference between the two lines shows the large effect that benefit extensions have on the path of the unemployment rate in the DMP model with a high \( b \).

By contrast, the right panel of Figure 7 shows a much smaller effect of benefit extensions on unemployment dynamics. As in the high \( b \) model, the duration of benefits increases to 20 months as soon as the unemployment rate exceeds 9 percent. However, the level of the opportunity cost is small on average and, therefore, this extension does not affect significantly the path of the unemployment rate. The average distance between the two unemployment paths is less than 0.3 percentage point. This difference is quite close to our estimates in Section 3 that did not take into account the persistence of benefit extensions or potential non-linearities in the relationship between unemployment and benefit extensions.
5 Conclusion

Identifying the effect of UI benefit extensions on macroeconomic outcomes is challenging because benefits are extended in times of elevated unemployment. This simultaneity happens both because U.S. law makes benefit extensions a function of state economic conditions and because policymakers enact emergency compensation in recessions. We use data revisions to decompose variation in the duration of benefits over time and across states into the part coming from actual differences in economic fundamentals and the part coming from measurement error in the real-time data used to determine benefit extensions. Using only the measurement error component for identification, we find an economically reasonable increase in the number of individuals receiving UI, but only a limited influence of benefit extensions on key state-level macroeconomic outcomes including unemployment, employment, vacancies, and wages.

A standard DMP model can rationalize this small response with a low opportunity cost of giving up benefits for the average unemployed. A low opportunity cost means that even large extensions of benefits have limited influence on labor market variables in the model. Together, our empirical and theoretical results imply that the unprecedented increase in benefits during the Great Recession contributed at most 0.3 percentage point to the increase in the unemployment rate.

We have not considered but acknowledge the existence of other economic channels beyond a low opportunity cost of benefits which could help to explain the limited influence of benefit extensions we measure in the data. These channels include an offsetting stimulus effect from transferring resources to unemployed individuals with high marginal propensity to consume, labor market spillovers as lower search effort by UI recipients raises job finding rates for non-recipients, and wage bargaining protocols that do not depend on the opportunity cost of employment. Quantifying each of these channels separately would be a valuable step for future research. On the other hand, we know of no labor market theory in which UI extensions substantially raise unemployment without requiring a high opportunity cost of giving up benefits and a much larger response of unemployment than we measure in the data.
Finally, the microeconomic function of UI is to provide income replacement for individuals who have lost their jobs. The value of this insurance mechanism may increase in the duration of an unemployment spell as individuals draw down on their assets and other sources of income. The results in this paper do not speak to this income support function nor to the microeconomic rationale for increasing insurance during recessions when the typical duration of unemployment spells rises. Our results simply say that UI extensions do not have large negative macroeconomic effects.

References


A Data Appendix

In this data appendix we describe the extended benefits programs and the BLS methodology to estimate the state unemployment rates.

A.1 Extended Benefits and Emergency Compensation Programs

In Table A.1 we list the full set of benefit extension programs, tiers, and triggers in operation during our sample.

A.2 State Unemployment Rate Estimation Methodology


The first step of the real-time estimation involves estimating the state space models separately for total unemployment and employment. The unemployment rate is constructed from these two estimates. Let $y_{s,t} + o_{s,t}$ denote the direct count of a variable such as state employment or unemployment from the CPS, where $o_{s,t}$ denotes any outlier component identified using intervention model methods. For each state, the observation equation is:

$$y_{s,t} = \alpha_{s,t} x_{s,t} + L_{s,t} + S_{s,t} + e_{s,t},$$  \hspace{1cm} (A.1)

where $x_{s,t}$ is an external regressor (insured unemployment for unemployment and CES payroll employment for employment), $L_{s,t}$ is a trend level, $S_{s,t}$ is a seasonal component, and $e_{s,t}$ is the...
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</tbody>
</table>

Notes: Triggers written in italics are optional. IUR is the average of the insured unemployment rate in the thirteen weeks ending two weeks before the week of the trigger notice. TUR is the average of the total unemployment rate in the three months ending with the last month of data reported as of the third Friday before the Sunday starting the week of the trigger notice. All programs and tiers obey a thirteen week rule whereby once triggered on a tier a state remains on that tier for at least thirteen weeks (barring any changes in law), and once triggered off a tier the state remains off for at least thirteen weeks. The time periods reported exclude phase-outs. EB Tier 1 Trigger 3 became operational on 03/07/1993. Authorization of the TEUC programs lapsed temporarily between 01/01/2003 and 01/07/2003. Authorization of the EUC programs lapsed temporarily between 04/04/2010 and 04/14/2010, between 05/30/2010 and 07/21/2010, and between 11/28/2010 and 12/16/2010. Between 02/22/2012 and 05/31/2012 individuals could receive up to 16 weeks of EUC Tier 4 benefits if their state was not in an EB period. The main source for this table is Department of Labor (2015).
observation error. The state space model employment or unemployment is \( Y_{s,t} = \alpha_{s,t}x_{s,t} + L_{s,t} + S_{s,t} = y_{s,t} - e_{s,t} \).

The model state equations are:

\[
\begin{align*}
\alpha_{s,t} &= \alpha_{s,t-1} + \eta_{\alpha,s,t}, \quad (A.2) \\
L_{s,t} &= L_{s,t-1} + R_{s,t} + \eta_{L,s,t}, \quad (A.3) \\
R_{s,t} &= R_{s,t-1} + \eta_{R,s,t}, \quad (A.4) \\
S_{s,t} &= \sum_{j=1}^{6} S_{j,s,t}, \quad (A.5)
\end{align*}
\]

where \( e_{s,t}, \eta_{\alpha,s,t}, \eta_{L,s,t}, \) and \( \eta_{R,s,t} \) are independent normal random variables, and \( S_{j,s,t} \) are seasonal frequency functions. A generalized Kalman filter estimates the system.\(^1\)

BLS introduced a major update in 2005 with the incorporation of real-time benchmarking to Census Division and national totals. Each month, after estimation of the state space system, BLS would allocate the residual between the sum of model estimates of not seasonally adjusted series for Census Divisions \( (L_t + I_t) \) and the national CPS total pro rata to each division, and then repeat the process for states within a division.\(^2\) In that way, the real-time sum of state employment and unemployment would always equal the national total. However, the pro rata allocation meant that state-specific residuals would “spillover” to neighboring states. In 2010, BLS began applying a one-sided moving average Henderson filter to the benchmarked series.

The most recent major update to the real-time model occurred in 2015 and involves incorporating the real-time benchmarking directly into the state space filter. The observation vector is augmented to include the difference between the sum of not seasonally adjusted model state unemployment and employment levels and their Census Division direct estimate (excluding identified outliers), and the estimation constrains the variance of the innovation in this component to be zero. Outlier components \( o_{s,t} \) are subsequently added back to the states from which

\(^1\)Because of the rotating panel structure of the CPS sample, the observation equation errors may be serially correlated. The generalized Kalman filter uses GLS instead of OLS to find the conditional mean of the state vector given the updated observation vector.

\(^2\)At the Census Division level the state space estimation excludes the external regressors insured unemployment or payroll employment. In terms of equations (A.1) to (A.5), \( \alpha_{cd,t} = 0 \) and \( var(\eta_{cd,t}) = 0 \).
they originated. The incorporation of the benchmarking within the filter substantially mitigates spillovers of unusual residuals across states within a division.

Table A.2 provides an overview of the importance of different components of the revision process using as a metric the $R^2$ from a regression of $\hat{u}_{s,t}$ on the components.\footnote{Because the procedure for the real-time data changed in 2005 and most of the UI errors in our sample occur during the Great Recession, we limit the sample in this table to 2005 to 2013.} The first row shows that the revisions to the CES employment data explain a small part of the unemployment rate revision. While the CES revisions themselves can be large, they enter into the unemployment rate only through the denominator and therefore have a smaller effect on the unemployment rate revision. The second row adds elements related to the 2015 LAUS redesign and the treatment of state-specific outliers in the CPS. Specifically, we add to the regression the difference between the vintage 2014 and vintage 2015 LAUS seasonally adjusted unemployment rates, the difference between the unemployment rate constructed directly from the CPS monthly files and the real-time LAUS seasonally unadjusted unemployment rate, the difference between the unemployment rate constructed directly from the CPS files and seasonally adjusted using an X-11 moving average and the average of the same variable for three months before and three months after the observation, and the labor force weighted average of the previous variable for other states in the same Census Division. These variables increase the explained part of $\hat{u}_{s,t}$ to 49%. In row 3, adding the component due to updated seasonal factors in the revised data further increases the explained part of $\hat{u}_{s,t}$ to 59%. Rows 4 and 5 next add lags and leads of $u_{s,t}$ to explore whether the path of the unemployment rate affects the revision through the state space smoother and symmetric filter. In row 4, adding 12 lags of the unemployment rate raises the $R^2$ by 0.02, while in row 5 adding the contemporaneous and 12 leads of the unemployment rate raises it by an additional 0.01.\footnote{The incremental $R^2$ is not invariant to the ordering of variables. Including just the 12 lags of the unemployment rate produces an $R^2$ of 0.10. Adding the contemporaneous and 12 leads raises the $R^2$ to 0.15.} Overall, these components explain 62% of the variation in the unemployment rate revision. Because the LAUS process uses a nonlinear state space model, we would not expect a linear projection on the major sources of revisions to generate an $R^2$ of 1.

Figure A.1 illustrates that in our example of Vermont the 2015 LAUS technical improvements...
Table A.2: Determinants of Unemployment Rate Errors

<table>
<thead>
<tr>
<th>Determinants</th>
<th>( R^2 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>CES revisions</td>
<td>0.03</td>
</tr>
<tr>
<td>+ 2015 LAUS redesign and identification of outliers</td>
<td>0.49</td>
</tr>
<tr>
<td>+ Updated seasonal factors</td>
<td>0.59</td>
</tr>
<tr>
<td>+ 12 lags of unemployment rate</td>
<td>0.61</td>
</tr>
<tr>
<td>+ Contemporaneous and 12 leads of unemployment rate</td>
<td>0.62</td>
</tr>
</tbody>
</table>

Notes: The table reports the \( R^2 \) from a regression of the measurement error in the unemployment rate \( \hat{u}_{s,t} \) on the regressors indicated in the left column. The sample is January 2005 to December 2013. In the first row, CES revisions are the log difference between the real-time and revised nonfarm seasonally unadjusted employment level from the CES. The second row adds the difference between the vintage 2014 and vintage 2015 LAUS seasonally adjusted unemployment rates, the difference between the unemployment rate constructed directly from the CPS monthly files and the real-time LAUS seasonally unadjusted unemployment rate, the difference between the unemployment rate constructed directly from the CPS files and seasonally adjusted using an X-11 moving average and the average of the same variable for three months before and three months after the observation, and the labor force weighted average of the previous variable for other states in the same Census Division. The third row adds the difference between the revised LAUS seasonally adjusted unemployment rate and the real-time seasonally unadjusted unemployment rate after rescaling the numerator and denominator by the revised seasonal factors for LAUS unemployment and employment. The fourth row adds 12 lags of the revised unemployment rate. The fifth row adds the contemporaneous and 12 leads of the revised unemployment rate.

account for all of the unemployment rate error during the period of the UI error in the beginning of 2010.

B Measurement Error in the Revised Data

In this appendix we examine the case in which the revised data measure the fundamentals with some error. Measurement error in the revised data introduces an attenuation bias in our estimated impulse responses. We derive an upper bound of this bias under the plausible assumption that the revised data measure fundamentals with less error than the real-time data. Even under this upper bound, we can reject the hypothesis that our estimated responses are consistent with large effects of UI benefit extensions on unemployment.

Our discussion applies to observations at the state-month level, but we drop state-month subscripts to ease the notation. Let the observed duration of benefits, \( T^* \), be equal to the sum
Figure A.1: Extended Benefits and Unemployment in Vermont

Notes: The figure plots the actual duration of benefits $T^*_s,t$ and the duration based on the revised data $T_{s,t}$ (left axis) together with the real-time $u^*_s,t$ and revised unemployment rates $u_{s,t}$ (right axis). The dashed green line shows the unemployment rate using the 2014 vintage of data.

of two orthogonal components:

$$T^* = T^F + T^E,$$  \hspace{2cm} (A.6)

where $T^F$ denotes the duration of benefits using the true unemployment rate and $T^E$ denotes the duration of benefits due to measurement error of the true unemployment rate. The true unemployment rate and $T^F$ are unknown to the econometrician. We allow $T$ to be based on an imperfect measure of the fundamentals:

$$T = T^F + T^X,$$  \hspace{2cm} (A.7)

where $T^X$ is a component due to measurement error in the revised data.

The UI error that we defined in the main text, $\hat{T}$, can be written as:

$$\hat{T} = T^* - T = T^E - T^X.$$  \hspace{2cm} (A.8)

In the presence of measurement error in the revised data, the UI error $\hat{T}$ is the difference between the measurement error in the true unemployment rate, $T^E$, and the measurement error in the revised data, $T^X$. 
The three primitive objects of our analysis are $T^F$, $T^E$, and $T^X$. We write each variable $j = \{F, E, X\}$ as the sum of its expected value plus an innovation, $T^j = \mathbb{E}T^j + \epsilon^j$. All innovations $\epsilon^j$’s are serially uncorrelated and uncorrelated with each other. The innovations in the measurement error components, $\epsilon^E$ and $\epsilon^X$, are uncorrelated with the fundamentals $F$. By contrast, the innovation $\epsilon^F$ is potentially correlated with the fundamentals $F$.

Taking expectations in equation (A.6) and using the definition of the innovations, we write the innovation in the real-time duration of benefits as:

$$\epsilon^{T^*} = \epsilon^F + \epsilon^E.$$  

(A.9)

Similarly, using equations (A.7) and (A.8), we write the innovation in the duration of UI benefits under the revised data and the innovation in the UI error (which we called $\epsilon$ in the main text) as:

$$\epsilon^T = \epsilon^F + \epsilon^X,$$  

(A.10)

$$\epsilon^\hat{T} = \epsilon^E - \epsilon^X.$$  

(A.11)

Suppose the relationship between some outcome variable $y$ (that could be measured in a future period) and the innovation in the duration of benefits under the real-time data is:

$$y = \beta \epsilon^{T^*} + \gamma F,$$  

(A.12)

where $F$ collects all other factors that affect $y$. The fundamentals in $F$ are potentially correlated with $\epsilon^T$ through $\epsilon^F$ but are uncorrelated with the measurement error component $\epsilon^E$. Using equations (A.9) and (A.11) we can write:

$$y = \beta \epsilon^F + \beta \epsilon^X + \beta \epsilon^\hat{T} + \gamma F.$$  

(A.13)

The OLS coefficient in a bivariate regression of $y$ on $\epsilon^\hat{T}$ is given by:

$$\beta_{OLS} = \frac{\text{Cov} \left( y, \epsilon^\hat{T} \right)}{\text{Var} \left( \epsilon^\hat{T} \right)} = \frac{\text{Cov} \left( \beta \epsilon^X + \beta \epsilon^\hat{T} + \epsilon^\hat{T}, \epsilon^\hat{T} \right)}{\text{Var} \left( \epsilon^\hat{T} \right)} = \beta \left( 1 - \frac{\text{Var} \left( \epsilon^X \right)}{\text{Var} \left( \epsilon^\hat{T} \right)} \right),$$  

(A.14)

where the second equality uses equation (A.13) and the fact that $\text{Cov} \left( F, \epsilon^\hat{T} \right) = \text{Cov} \left( \epsilon^F, \epsilon^\hat{T} \right) = 0$, and the third equality uses the fact that $\text{Cov} \left( \epsilon^X, \epsilon^\hat{T} \right) = \text{Cov} \left( \epsilon^X, \epsilon^E - \epsilon^X \right) = -\text{Var} \left( \epsilon^X \right)$. If
the revised data measure the true fundamentals without any error up to a constant, \( \text{Var}(e^X) = 0 \), then the OLS estimator is unbiased \( \beta^{\text{OLS}} = \beta \). The attenuation bias is increasing in the variance of the measurement error in the revised data relative to the variance of the UI error, \( \text{Var}(e^X) / \text{Var}(\hat{e}^T) \).

We now show that attenuation bias in our estimates is too small to affect our main conclusions under the plausible assumption that revised data do not deteriorate the quality of measurement of true fundamentals. We say that the revised data are a (weakly) better measure of the true fundamentals than the real-time data if the measurement error in the revised data has a (weakly) lower variance:

\[
\text{Var}(e^X) \leq \text{Var}(e^E). \quad (A.15)
\]

The assumption that the revised data contain less measurement error than the real-time data places an upper bound on the attenuation bias. From equation (A.11), we see that \( \text{Var}(\hat{e}^T) = \text{Var}(e^X) + \text{Var}(e^E) \) and, therefore, under assumption (A.15) less than 50 percent of the variance of \( e^T \) is attributed to \( e^X \):

\[
\frac{\text{Var}(e^X)}{\text{Var}(\hat{e}^T)} \leq 0.5. \quad (A.16)
\]

We estimate in the data an upper bound of \( \beta^{\text{OLS}} = 0.02 \). Using the upper bound of the bias \( \text{Var}(e^X) / \text{Var}(e^T) = 0.50 \), the true coefficient could be as large as \( \beta = 0.04 \). Using a standard error of 0.02, this \( \beta \) is still 4.5 standard errors below the 0.14 level that would rationalize a large effect of extended benefits on unemployment during the Great Recession.

This calculation is very conservative because it assumes that revisions do not improve measurement and uses the upper bound of our estimates of \( \beta \). In Section 3.4 we provided evidence that revisions are informative about actual spending patterns and beliefs. This implies that \( \text{Var}(e^X) / \text{Var}(\hat{e}^T) \) is likely to be smaller than 0.5. Indeed, we find in the data that there is smaller variance of outcomes in the revised data and, consistent with our assumption that \( \text{Var}(e^X) \leq \text{Var}(e^E) \), that \( \text{Var}(e^T) < \text{Var}(e^T^*) \). If we apply, for example, \( \text{Var}(e^X) / \text{Var}(\hat{e}^T) = 0.25 \) to our maximum estimate of \( \beta^{\text{OLS}} = 0.02 \), we obtain that the true
coefficient is $\beta < 0.03$. In general, the more informative is the revised data for the true fundamentals, the lower is $\text{Var}(\epsilon^X) / \text{Var}(\hat{\epsilon}^T)$ and the smaller is the attenuation bias.

## C Model Appendix

In this appendix we discuss further details and present additional results from the model.

**Computations.** We solve the model globally by iterating on the equilibrium conditions. We begin by guessing functions $\theta^0(u_t, \omega_t, p_t, \delta_t, \hat{T}_t)$ and $b^0(u_t, \omega_t, p_t, \delta_t, \hat{T}_t)$ defined over grids of state variables. Given these guesses, we obtain $f(\cdot), T(\cdot), u'(\cdot)$ and $\omega'(\cdot)$, where primes denote next period values, and use equation (19) to obtain the wage function $w(\cdot)$. Next, we iterate on equation (17) to solve for firm value $J(\cdot)$. Finally, we use the free-entry condition (18) and the definition of the opportunity cost in equation (16) to obtain the implied $\theta^1(\cdot)$ and $b^1(\cdot)$ functions. We update the guesses and repeat until convergence. To evaluate value functions at points $u'$ and $\omega'$ we use linear interpolation. When solving for the equilibrium policy functions, we impose that the probabilities $f(\cdot)$ and $q(\cdot)$ lie between zero and one. These restrictions also guarantee that $v$ and $\theta$ are always positive.

**Further Results.** In Figures A.2, A.3, and A.4, we present the impulses of the fraction of unemployed receiving UI, the log opportunity cost, and log vacancies to a one-month increase in the UI error innovation. In Figures A.5 and A.6 we depict the path of productivity and separations shocks underlying the experiment depicted in Figure 7 in the main text. In each figure, the left panel corresponds to the high $b$ model and the right panel corresponds to the low $b$ model.

**Regression Discontinuity.** In Figure A.7 we illustrate the Regression Discontinuity (RD) framework using model-generated data. The point we wish to make is that, under very persistent shocks, a pure RD framework is not able to detect significant effects of UI benefit extensions on macroeconomic outcomes despite the existence of such effects. For this figure, we continue
Figure A.2: Impulse Response of Fraction Receiving UI in the Model

Notes: The figure plots the coefficients on $\epsilon_t$ from the regression $\omega_{t+h} = \beta(h) \epsilon_t + \sum_{j=0}^{11} \gamma_j(h) u_{t-j} + \nu_{t+h}$ using data generated from model simulations.

to use the same parameters as in the high $b$ model of Table 10 except that we increase the persistence of log productivity to $\rho = 0.98$. We also adjust the volatility of the productivity shocks to $\sigma = 0.004$ so that the model generates the same volatility of log productivity as the baseline high $b$ model in the main text.

The right panel of Figure A.7 shows the relationship between $u_{t+1}$ in the vertical axis and $u_t$ in the horizontal axis generated by the model. The left panel of the figure shows the relationship between $u_{t+2}$ and $u_t$. The plotted lines denote third-order polynomials fitted on model-generated data left and right of the cutoffs denoted with vertical lines. As we see in the figure, there is no significant discontinuity around the points in which the duration of benefits increases sharply. When shocks are very persistent, forward-looking agents in an economy that starts just below the cutoff expect benefit extensions in the future. Therefore, equilibrium outcomes are not significantly different relative to the outcomes observed in an economy that starts just above the cutoff.
Figure A.3: Impulse Response of Log Opportunity Cost in the Model

Notes: The figure plots the coefficients on $\epsilon_t$ from the regression $\log b_{t+h} = \beta(h)\epsilon_t + \sum_{j=0}^{11} \gamma_j(h)u_{t-j} + \nu_{t+h}$ using data generated from model simulations.

Figure A.4: Impulse Response of Log Vacancies in the Model

Notes: The figure plots the coefficients on $\epsilon_t$ from the regression $\log v_{t+h} = \beta(h)\epsilon_t + \sum_{j=0}^{11} \gamma_j(h)u_{t-j} + \nu_{t+h}$ using data generated from model simulations.
Figure A.5: Productivity Path in the Model
Notes: The figure plots the path of productivity used to generate the simulation in Figure 7.

Figure A.6: Separations in the Model
Notes: The figure plots the path of the separation rate used to generate the simulation in Figure 7.
Figure A.7: Regression Discontinuity in Model-Generated Data

Notes: The figure plots the relationship between $u_t$ and $u_{t+1}$ (left panel) and $u_{t+2}$ (right panel) generated from simulated data.