# An Honest Approach to Parallel Trends* 

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November 12, 2020


#### Abstract

This paper proposes robust inference methods for difference-in-differences and eventstudy designs that do not require that the parallel trends assumption holds exactly. Instead, the researcher must only impose restrictions on the possible differences in trends between the treated and control groups. Several common intuitions expressed in applied work can be captured by such restrictions, including the notion that pretreatment differences in trends are informative about counterfactual post-treatment differences in trends. Our methodology then guarantees uniformly valid ("honest") inference when the imposed restrictions are satisfied. We first show that fixed length confidence intervals have near-optimal expected length for a practically-relevant class of restrictions. We next introduce a novel inference procedure that accommodates a wider range of restrictions, which is based on the observation that inference in our setting is equivalent to testing a system of moment inequalities with a large number of linear nuisance parameters. The resulting confidence sets are consistent, and have optimal local asymptotic power for many parameter configurations. We recommend researchers conduct sensitivity analyses to show what conclusions can be drawn under various restrictions on the possible differences in trends.


Keywords: Difference-in-differences, event-study, parallel trends, sensitivity analysis, robust inference, partial identification.

[^0]
## 1 Introduction

This paper develops robust causal inference methods for difference-in-differences and related event-study designs. ${ }^{1}$ Traditional methods for inference are valid only under the so-called "parallel trends" assumption, yet researchers are often unsure whether this assumption holds in practice. We instead propose methodology that allows for valid inference under weaker assumptions and enables the researcher to conduct sensitivity analysis with respect to these assumptions.

Our methods only require the researcher to impose that the possible differences in trends are restricted to some set $\Delta$. A variety of intuitions expressed in applied work can be formalized via such restrictions. For instance, the intuition for the common practice of testing for pre-existing differences in trends ("pre-trends") can be formalized via restrictions that impose that the pre-trends are informative about the counterfactual post-treatment differences in trends. Likewise, context-specific knowledge about long-run secular trends or simultaneous policy changes may motivate restrictions that the difference in trends be monotone or have a particular sign. We consider a large class of possible $\Delta$ 's that allows the researcher to formalize the aforementioned intuitions as well as many others. Under such restrictions, the treatment effect of interest is typically set-identified.

We then develop methods to conduct uniformly valid inference given a set of restrictions $\Delta$. We introduce two methods for inference, which we show have different strengths depending on the type of restriction $\Delta$ that is imposed, as well as a hybrid approach that combines the two.

Our first method for inference uses optimal fixed length confidence intervals (FLCIs) based on affine estimators, following Donoho (1994). FLCIs have attractive properties for certain types of restrictions - specifically, when $\Delta$ is convex and centrosymmetric - which include our baseline smoothness class used to formalize the intuition behind pre-trends testing. For these types of restrictions, results from Armstrong and Kolesar (2018, 2020) imply that the optimal FLCI has near-optimal expected length when in fact parallel trends holds.

Unfortunately, however, we show that FLCIs can have poor properties for broader classes of restrictions, such as those that incorporate sign or shape restrictions. We provide a novel characterization of when the optimal FLCI is consistent, meaning that any fixed point outside of the identified set falls outside the FLCI with probability approaching one asymptotically. The optimal FLCI is consistent for all parameter values if and only if the length of the identified set is constant over the parameter space. This condition often fails for several

[^1]leading restrictions on the class of differential trends, such as those that incorporate sign or shape restrictions. Our (in)consistency result may be of general interest in other applications where FLCIs have been used.

Motivated by this result, we introduce a second method for inference that delivers desirable asymptotic properties over a larger class of possible restrictions on the possible differences in trends. We exploit the observation that conducting inference on the treatment effect of interest under such restrictions is equivalent to a moment inequality problem with linear nuisance parameters. A practical challenge is that the number of nuisance parameters scales linearly in the number of post-treatment periods, and thus will often be large (above 10) in typical empirical applications. This renders many moment inequality procedures, which rely on test inversion over a grid for the full parameter vector, computationally infeasible. We overcome this computational challenge by employing the conditional inference procedure developed in Andrews, Roth and Pakes (2019, henceforth ARP), which delivers computationally tractable confidence sets that uniformly control size in our setting.

We then derive two novel results on the asymptotic performance of conditional confidence sets in our setting. First, we show that the conditional confidence sets are consistent for all polyhedral $\Delta$. Second, we provide a condition under which the conditional confidence sets have local asymptotic power converging to the power envelope (i.e., the upper bound on the power of any procedure that controls size uniformly). ${ }^{2}$ To prove the optimality result, we make use of duality results from linear programming and the Neyman-Pearson lemma to show that both the optimal test and our conditional test converge to a t-test in the direction of the Lagrange multipliers of the linear program that profiles out the nuisance parameters. Both of these asymptotic results are novel, and exploit additional structure in our context not present in the more general setting considered in ARP.

Our results on the local asymptotic power of the conditional confidence sets have two limitations. First, the condition needed for the conditional confidence sets to have optimal local asymptotic power does not hold for all parameter values, and in particular fails when the parameter of interest is point-identified. Second, our optimality results are under asymptotics where sampling variation grows small relative to the length of the identified set. Our asymptotic power results thus may not translate to good finite-sample power when sampling variation is large relative to the length of the identified set, particularly when there are non-binding moment restrictions that are close to binding.

Therefore, we finally introduce a novel hybrid inference procedure that combines the

[^2]relative strengths of the conditional confidence sets and FLCIs. The hybrid procedure is consistent, and has near-optimal local asymptotic power when the condition for the optimality of the conditional approach holds. Further, we find in simulations (discussed in more detail below) that hybridization with the FLCIs improves performance in finite sample when the binding and non-binding moments are not well-separated.

To explore the performance of our methods in practice, we conduct simulations calibrated to the 12 recently-published empirical papers surveyed in Roth (2019). We find that the FLCIs perform close to the optimal benchmark for excess length when $\Delta$ is our baseline smoothness class that satisfies the assumptions needed for the consistency and finite-sample near-optimality of the FLCIs. However, as predicted by the theory, the FLCIs can perform poorly relative to the other methods when $\Delta$ additionally includes sign or shape restrictions. The conditional confidence sets perform well across a wider range of simulation designs, and often have excess length within a few percent of the optimum. However, we find they can exhibit poor performance in settings where the binding and non-binding moments are not well-separated relative to the sampling variation in the data, such as when the target parameter is (nearly) point identified. Finally, the hybrid approach performs quite well across a wide range of specifications, with performance typically close to the better of the FLCIs and conditional approach. Based on our Monte Carlo simulations, we recommend the FLCIs for the special settings where the conditions for their consistency and finite-sample near-optimality hold, and otherwise recommend the hybrid approach.

We recommend applied researchers use our methods to conduct sensitivity analyses in which they report confidence sets under varying restrictions on the set of possible differences in trends. For instance, one class of restrictions we consider restricts the extent to which the difference in trends may deviate from linearity, and is governed by a single parameter that determines the degree of possible non-linearity. If the researcher is interested in testing a particular null hypothesis - e.g., the treatment effect in a particular period is zero then a simple statistic to report is the "breakdown" value of the non-linearity parameter at which the null hypothesis of interest can no longer be rejected. ${ }^{3}$ The researcher can also report how her conclusions change with the inclusion of additional sign or monotonicity restrictions motivated by context-specific knowledge. Performing such sensitivity analyses makes clear what must be assumed about the possible differences in trends in order to draw specific causal conclusions. We provide an R package, HonestDiD, for implementation of our recommended methods. ${ }^{4}$ We conclude by applying our proposed methodology to two

[^3]recently published papers.

Related literature: This paper contributes to an active literature on difference-in-differences and event-study designs by developing robust inference methods that allow for possible violations of the parallel trends assumption. Our approach is most closely related to Manski and Pepper (2018), who show that the treatment effect of interest is partially identified under "bounded variation" assumptions that relax the usual exact parallel trends assumption. We consider identification under a broad class of restrictions on the possible violations of parallel trends, which nests as a special case the bounded variation assumptions considered in Manski and Pepper (2018). This broader class of restrictions can be used to formalize a variety of arguments made intuitively in applied work - e.g., that pre-treatment differences in trends are informative about counterfactual post-treatment differences in trends. Importantly, we develop methods for conducting inference on the causal effects of treatment under these assumptions, whereas Manski and Pepper (2018) only consider identification.

Several other recent papers consider various relaxations of the parallel trends assumption. Keele, Small, Hsu and Fogarty (2019) develop techniques for testing the sensitivity of difference-in-differences designs to violations of the parallel trends assumption, but they do not incorporate information from the observed pre-trends in their sensitivity analysis. Empirical researchers commonly adjust for the extrapolation of a linear trend from the pretreatment periods when there are concerns about violations of the parallel trends assumption, which is valid if the difference in trends is exactly linear (e.g., Dobkin, Finkelstein, Kluender and Notowidigdo, 2018; Goodman-Bacon, 2018a,b; Bhuller, Havnes, Leuven and Mogstad, 2013). Our methods nest this approach as a special case, but allow for valid inference under less restrictive assumptions about the class of possible differences in trends. Freyaldenhoven, Hansen and Shapiro (2019) propose a method that allows for violations of the parallel trends assumption but requires an additional covariate that is affected by the same confounding factors as the outcome but not by the treatment of interest. Ye, Keele, Hasegawa and Small (2020) consider partial identification of treatment effects when there exist two control groups whose outcomes have a bracketing relationship with the outcome of the treated group. Leavitt (2020) proposes an empirical Bayes approach calibrated to pre-treatment differences in trends, and Bilinski and Hatfield (2020) and Dette and Schumann (2020) propose approaches based on pre-tests for the magnitude of the pre-treatment violations of parallel trends.

Our methods address several concerns related to established empirical practice in difference-in-differences and event-study designs. First, common tests for pre-trends may be underpowered against meaningful violations of parallel trends, potentially leading to severe undercoverage of conventional confidential intervals (Freyaldenhoven et al., 2019; Roth, 2019;

Bilinski and Hatfield, 2020; Kahn-Lang and Lang, 2020). Second, statistical distortions from pre-testing for pre-trends may further undermine the performance of conventional inference procedures (Roth, 2019). Third, parametric approaches to controlling for pre-existing trends may be quite sensitive to functional form assumptions (Wolfers, 2006; Lee and Solon, 2011). We address these issues by providing tools for inference that do not rely on an exact parallel trends assumption and that make clear the mapping between assumptions on the potential differences in trends and the strength of one's conclusions.

Our work is complementary to a growing literature on the causal interpretation of eventstudy coefficients in two-way fixed effects models in the presence of staggered treatment timing or heterogeneous treatment effects (Meer and West, 2016; Borusyak and Jaravel, 2016; Sun and Abraham, 2020; Athey and Imbens, 2018; de Chaisemartin and D'Haultfouille, 2018; de Chaisemartin and D'Haultfœuille, 2020; Goodman-Bacon, 2018a; Kropko and Kubinec, 2018; Callaway and Sant'Anna, 2020; Imai and Kim, 2020; Słoczyński, 2018). A key finding is that regression coefficients from conventional approaches may not produce convex weighted averages of treatment effects even if parallel trends holds. Several alternative estimators have been proposed that consistently estimate sensible causal estimands under a suitable parallel trends assumption. Our methodology can be applied to assess the sensitivity of results obtained using these methods to violations of the corresponding parallel trends assumption; see Section 7 for additional discussion.

More broadly, our approach relates to a large and active literature on sensitivity analysis and misspecification robust inference, including Imbens (2003); Rosenbaum (2005); Altonji, Elder and Taber (2005); Conley, Hansen and Rossi (2012); Kolesar and Rothe (2018); Armstrong and Kolesar (2018); Masten and Poirier (2018); Bonhomme and Weidner (2020); Oster (2019) among many others.

## 2 General set-up

We now introduce the assumptions, target parameter, and inferential goal considered in the paper. In the main text of the paper, we consider a finite-sample normal model, which arises as an asymptotic approximation to a variety of econometric settings of interest. In the supplementary materials, we show how the finite-sample results presented in this model translate to uniform asymptotic statements.

### 2.1 Finite sample normal model

Consider the following model

$$
\begin{equation*}
\hat{\beta}_{n} \sim \mathcal{N}\left(\beta, \Sigma_{n}\right) \tag{1}
\end{equation*}
$$

where $\hat{\beta}_{n} \in \mathbb{R}^{\underline{T}+\bar{T}}$ and $\Sigma_{n}=\frac{1}{n} \Sigma^{*}$ for $\Sigma^{*}$ a known, positive-definite $(\underline{T}+\bar{T}) \times(\underline{T}+\bar{T})$ matrix. We refer to $\hat{\beta}_{n}$ as the estimated event-study coefficients, and partition $\hat{\beta}_{n}$ into vectors corresponding with the pre-treatment and post-treatment periods, $\hat{\beta}_{n}=\left(\hat{\beta}_{n, \text { pre }}^{\prime}, \hat{\beta}_{n, \text { post }}^{\prime}\right)^{\prime}$, where $\hat{\beta}_{n, \text { pre }} \in \mathbb{R}^{\underline{T}}$ and $\hat{\beta}_{n, \text { post }} \in \mathbb{R}^{\bar{T}}$. We adopt analogous notation to partition other vectors that are the same length as $\hat{\beta}_{n}$.

This finite sample normal model (1) can be viewed as an asymptotic approximation to a wide range of econometric settings. Under mild regularity conditions, a variety of estimation strategies in difference-in-differences and event study designs will yield asymptotically normal estimated event-study coefficients, $\sqrt{n}\left(\hat{\beta}_{n}-\beta\right) \xrightarrow{d} \mathcal{N}\left(0, \Sigma^{*}\right) .{ }^{5}$ This convergence in distribution suggests the finite-sample approximation $\hat{\beta}_{n} \stackrel{d}{\approx} \mathcal{N}\left(\beta, \Sigma_{n}\right)$, where $\stackrel{d}{\approx}$ denotes approximate equality in distribution and $\Sigma_{n}=\frac{1}{n} \Sigma^{*}$. We derive results assuming this equality in distribution holds exactly in finite samples. In the supplemental materials, we show that results in the finite sample normal model translate to uniform asymptotic statements for a large class of data-generating processes.

We assume the mean vector $\beta$ satisfies the following causal decomposition.
Assumption 1. The parameter vector $\beta$ can be decomposed as

$$
\begin{equation*}
\beta=\underbrace{\binom{\tau_{\text {pre }}}{\tau_{\text {post }}}}_{:=\tau}+\underbrace{\binom{\delta_{\text {pre }}}{\delta_{\text {post }}}}_{:=\delta} \text { with } \tau_{\text {pre }} \equiv 0 . \tag{2}
\end{equation*}
$$

The first term, $\tau$, represents the time path of the dynamic causal effects of interest. We assume the treatment has no causal effect prior to its implementation, so $\tau_{\text {pre }}=0$. The second term, $\delta$, represents the difference in trends between the treated and untreated groups that would have occurred absent treatment. The parallel trends assumption imposes that $\delta_{\text {post }}=0$. Therefore, under parallel trends, $\beta_{\text {post }}=\tau_{\text {post }}$.

[^4]Example: Difference-in-differences We observe an outcome $Y_{i t}$ for a sample of individuals $i=1, \ldots, N$ for three time periods, $t=-1,0,1$. Individuals in the treated population $\left(D_{i}=1\right)$ receive a treatment between period $t=0$ and $t=1 .{ }^{6}$ The observed outcome equals $Y_{i, t}=D_{i} Y_{i, t}(1)+\left(1-D_{i}\right) Y_{i, t}(0)$, where $Y_{i, t}(1)$ and $Y_{i, t}(0)$ are the potential outcomes for individual $i$ in period $t$ associated with the treatment and control conditions. Assume the treatment has no causal effect prior to implementation, meaning $Y_{i, t}(1)=Y_{i, t}(0)$ for $t<1$. The causal estimand of interest is the average treatment effect on the treated (ATT), $\tau_{A T T}=\mathbb{E}\left[Y_{i, 1}(1)-Y_{i, 1}(0) \mid D_{i}=1\right]$.

In this setting, researchers commonly estimate the "dynamic event study regression"

$$
\begin{equation*}
Y_{i t}=\lambda_{i}+\phi_{t}+\sum_{s \neq 0} \beta_{s} \times \mathbb{1}[t=s] \times D_{i}+\epsilon_{i t} . \tag{3}
\end{equation*}
$$

The estimated coefficient $\hat{\beta}_{1}$ is the "difference-in-differences" of sample means across treated and untreated groups between period $t=0$ and $t=1, \hat{\beta}_{1}=\left(\bar{Y}_{1,1}-\bar{Y}_{1,0}\right)-\left(\bar{Y}_{0,1}-\bar{Y}_{0,0}\right)$, where $\bar{Y}_{d, t}$ is the sample mean of $Y_{i t}$ for treatment group $d$ in period $t$. The "pre-period" coefficient $\hat{\beta}_{-1}$ can likewise be written as $\hat{\beta}_{-1}=\left(\bar{Y}_{1,-1}-\bar{Y}_{1,0}\right)-\left(\bar{Y}_{0,-1}-\bar{Y}_{0,0}\right)$.

Taking expectations and re-arranging, we see that

$$
\begin{aligned}
\mathbb{E}\left[\hat{\beta}_{1}\right] & =\tau_{A T T}+\underbrace{\mathbb{E}\left[Y_{i, 1}(0)-Y_{i, 0}(0) \mid D_{i}=1\right]-\mathbb{E}\left[Y_{i, 1}(0)-Y_{i, 0}(0) \mid D_{i}=0\right]}_{\text {Post-period differential trend }=: \delta_{1}}, \\
\mathbb{E}\left[\hat{\beta}_{-1}\right] & =\underbrace{\mathbb{E}\left[Y_{i,-1}(0)-Y_{i, 0}(0) \mid D_{i}=1\right]-\mathbb{E}\left[Y_{i,-1}(0)-Y_{i, 0}(0) \mid D_{i}=0\right]}_{\text {Pre-period differential trend }=: \delta_{-1}} .
\end{aligned}
$$

The parameter $\beta=\mathbb{E}[\hat{\beta}]$ thus satisfies the decomposition (2), where $\tau_{\text {post }}=\tau_{A T T}$ is the ATT, $\delta_{\text {post }}=\delta_{1}$ is the difference in trends in untreated potential outcomes between $t=0$ and $t=1$, and $\delta_{\text {pre }}=\delta_{-1}$ is the analogous difference in trends for untreated potential outcomes between $t=-1$ and $t=0$. Under suitable regularity conditions, $\hat{\beta}$ will also satisfy a central limit theorem, so that (1) will hold approximately in large samples.

Remark 1. We have motivated our normal model from a sampling-based perspective, which is the most common framework for uncertainty in the difference-in-differences literature. While applicable in many cases, the sampling view may be unnatural in some settings, such as when the unit of observation is a state and all 50 states are observed (Manski and Pepper, 2018). In Rambachan and Roth (2020), we show that the normal model (1) also arises

[^5]from a design-based model that treats the population as fixed and views the assignment of treatment as the source of randomness in the data. In that setting, $\delta$ is a function of the finite-population covariance between idiosyncratic treatment probabilities and trends in untreated potential outcomes.

### 2.2 Target parameter and identification

The parameter of interest is a scalar, linear combination of the post-treatment causal effects, $\theta:=l^{\prime} \tau_{\text {post }}$ for some known $\bar{T}$-vector $l$. For example, $\theta$ equals the $t$-th period causal effect $\tau_{t}$ when the vector $l$ equals the $t$-th standard basis vector. Similarly, $\theta$ equals the average causal effect across all post-treatment periods when $l=\left(\frac{1}{T}, \ldots, \frac{1}{T}\right)^{\prime}$. Point-identification of $\theta$ is typically obtained by imposing the parallel trends assumption that $\delta_{\text {post }}=0$.

We relax the parallel trends assumption by instead assuming that $\delta$ lies in a set of possible differences in trends $\Delta$, which is specified by the researcher. This nests the usual parallel trends assumption as a special case with $\Delta=\left\{\delta: \delta_{\text {post }}=0\right\}$. Intuitively, since $\delta_{p r e}=\mathbb{E}\left[\hat{\beta}_{p r e}\right]$ is identified, the assumption that $\delta=\left(\delta_{p r e}^{\prime}, \delta_{\text {post }}^{\prime}\right)^{\prime} \in \Delta$ restricts the possible values of $\delta_{\text {post }}$ given the (identified) value of the pre-treatment difference in trends $\delta_{\text {pre }}$. It is natural to place restrictions on the relationship between $\delta_{\text {pre }}$ and $\delta_{\text {post }}$, since researchers frequently test the null hypothesis that $\delta_{\text {pre }}=0$ as a way of assessing the plausibility of the assumption that $\delta_{\text {post }}=0$.

Under the assumption that $\delta \in \Delta \neq\left\{\delta: \delta_{\text {post }}=0\right\}$, the parameter $\theta$ will typically be set-identified. For a given value of $\beta$, the set of values $\theta$ consistent with $\beta$ under the assumption $\delta \in \Delta$ is

$$
\begin{equation*}
\mathcal{S}(\beta, \Delta):=\left\{\theta: \exists \delta \in \Delta, \tau_{\text {post }} \in \mathbb{R}^{\bar{T}} \text { s.t. } l^{\prime} \tau_{\text {post }}=\theta, \beta=\delta+\binom{0}{\tau_{\text {post }}}\right\} \tag{4}
\end{equation*}
$$

which we refer to as the identified set. When $\Delta$ is a closed and convex set, the identified set has a simple characterization.

Lemma 2.1. If $\Delta$ is closed and convex, then $\mathcal{S}(\beta, \Delta)$ is an interval in $\mathbb{R}, \mathcal{S}(\beta, \Delta)=$ $\left[\theta^{l b}(\beta, \Delta), \theta^{u b}(\beta, \Delta)\right]$, where

$$
\begin{align*}
& \theta^{l b}(\beta, \Delta):=l^{\prime} \beta_{\text {post }}-\underbrace{\left(\max _{\delta} l^{\prime} \delta_{\text {post }}, \text { s.t. } \delta \in \Delta, \delta_{\text {pre }}=\beta_{\text {pre }}\right)}_{=: b^{\max }\left(\beta_{\text {pre }} ; \Delta\right)}  \tag{5}\\
& \theta^{u b}(\beta, \Delta):=l^{\prime} \beta_{\text {post }}-\underbrace{\left(\min _{\delta} l^{\prime} \delta_{\text {post }}, \text { s.t. } \delta \in \Delta, \delta_{\text {pre }}=\beta_{\text {pre }}\right)}_{=: b^{m i n}\left(\beta_{\text {pre }} ; \Delta\right)} . \tag{6}
\end{align*}
$$

Proof. Re-arranging terms in (4), the identified set can be equivalently written as $\mathcal{S}(\beta, \Delta)=$ $\left\{\theta: \exists \delta \in \Delta\right.$ s.t. $\left.\delta_{\text {pre }}=\beta_{\text {pre }}, \theta=l^{\prime} \beta_{\text {post }}-l^{\prime} \delta_{\text {post }}\right\}$. The result is then immediate.

Example: Difference-in-differences (continued) Point identification of the ATT in the difference-in-differences design is typically obtained by assuming that the counterfactual post-treatment difference in trends $\delta_{1}$ is exactly zero. Instead, we consider imposing that $\delta=\left(\delta_{-1}, \delta_{1}\right)^{\prime} \in \Delta$ for some set $\Delta$. The set $\Delta$ places restrictions on the possible values of the counterfactual post-treatment difference in trends $\delta_{1}$ (which is not directly identified) given the value of the pre-treatment difference in trends $\delta_{-1}$ (which is identified). When $\Delta$ is closed and convex, the identified set for the ATT will be $\left[\beta_{1}-b^{\max }, \beta_{1}-b^{\min }\right]$, where $b_{\text {max }}=\max _{\delta} \delta_{1}$ s.t $\left(\delta_{-1}, \delta_{1}\right)^{\prime} \in \Delta$ and $b_{\min }$ is defined analogously.

### 2.3 Possible choices of $\Delta$

The class of possible differences in trends $\Delta$ must be specified by the researcher, and the choice of $\Delta$ will depend on the economic context. We highlight several choices of $\Delta$ that may be reasonable in empirical applications and formalize intuitive arguments that are commonly made by applied researchers regarding possible violations of parallel trends. We ultimately recommend that researchers conduct sensitivity analysis with respect to a range of $\Delta$ 's that may be plausible in their context.

### 2.3.1 Smoothness restrictions

We begin by introducing a class of restrictions that formalizes the intuition behind the common practice of testing for pre-existing differences in trends (pre-trends). Researchers frequently test for pre-trends as a way of assessing the plausibility of the parallel trends assumption. These tests are motivated by the intuition that the pre-trend is informative about the counterfactual post-treatment difference in trends. In other words, the difference in trends must evolve "smoothly" over time; if not, then the fact that the pre-trend is close to zero would not be informative about the validity of the parallel trends assumption, since the (counterfactual) difference in trends could be close to zero in the pre-treatment period and then jump around the time of treatment.

We formalize this logic by introducing smoothness restrictions on the possible differences in trends. Specifically, we bound the extent to which the difference in trends can deviate from linearity. Deviations from linearity are a natural starting point since applied researchers concerned about possible violations of the parallel trends assumption commonly include
treatment-group specific linear trends in their regression specifications. ${ }^{7}$ There are concerns, however, that this linear extrapolation of the pre-trend may not quite be correct (Wolfers, 2006; Lee and Solon, 2011). A natural relaxation is therefore to require only that the difference in trends not deviate "too much" from linearity. We formalize this by bounding the extent to which the slope of the differential trend may change between consecutive periods, requiring that $\delta$ lie in the set

$$
\begin{equation*}
\Delta^{S D}(M):=\left\{\delta:\left|\left(\delta_{t+1}-\delta_{t}\right)-\left(\delta_{t}-\delta_{t-1}\right)\right| \leqslant M, \forall t\right\} \tag{7}
\end{equation*}
$$

where for $t>0, \delta_{t}$ refers to the $t$-th element of $\delta_{\text {post }}, \delta_{-t}$ refers to the $t$-th element of $\delta_{\text {pre }}$, and we adopt the convention that $\delta_{0}=0 .{ }^{8}$ The parameter $M \geqslant 0$ governs the amount by which the slope of $\delta$ can change between consecutive periods. ${ }^{9}$ In the special case where $M=0$, $\Delta^{S D}(0)$ requires that the difference in trends be exactly linear.

Figure 1: Intuition for $\Delta^{S D}(M)$


Alternatively, one might allow the smoothness of the differential trend to depend on the magnitude of the pre-trend. For instance, applied researchers may have intuition that if the observed pre-treatment difference in trends is small, then the counterfactual posttreatment difference in trends would also be small. If the two groups did not follow similar trends in the pre-treatment period, though, it may be more plausible that the difference in trends between the two groups would have changed substantially between the pre- and posttreatment periods. This intuition may be formalized by bounding the percentage change in

[^6]the slope of the differential trend across periods,
\[

$$
\begin{equation*}
\Delta^{R M}(\bar{M}):=\left\{\delta:\left|\delta_{t+1}-\delta_{t}\right| \leqslant \bar{M}\left|\delta_{t}-\delta_{t-1}\right|, \forall t\right\} . \tag{8}
\end{equation*}
$$

\]

Example: Difference-in-differences (continued) In the three-period difference-indifferences model, assuming the differential trend is exactly linear is equivalent to assuming $\Delta=\left\{\delta: \delta_{1}=-\delta_{-1}\right\}$. In contrast, assuming $\delta \in \Delta^{S D}(M)$ only requires that the linear extrapolation be approximately correct, $\delta_{1} \in\left[-\delta_{-1}-M,-\delta_{-1}+M\right]$. Likewise, assuming $\delta \in \Delta^{R M}(\bar{M})$ bounds the magnitude of $\delta_{1}$ based on the magnitude of $\delta_{-1}$, i.e. $\Delta^{R M}(\bar{M})=\left\{\left(\delta_{-1}, \delta_{1}\right)^{\prime}:\left|\delta_{1}\right| \leqslant \bar{M}\left|\delta_{-1}\right|\right\}$. The larger the magnitude of the observed pre-period violation in parallel trends, $\left|\delta_{-1}\right|$, the wider the range of possible post-period violations of parallel trends. Figure 2 gives a geometric depiction of $\Delta^{S D}$ and $\Delta^{R M}$ in this example.

Figure 2: Example choices for $\Delta$


Note: Diagrams of potential restrictions $\Delta$ on the set of possible violations of parallel trends in the threeperiod difference-in-differences model. See discussion in Section 2 for further details on each example.

### 2.3.2 Sign and monotonicity restrictions

Context-specific knowledge may sometimes further imply sign or monotonicity restrictions on the differential trend. For instance, there may be simultaneous, confounding policy changes that we expect to have a positive effect on the outcome of interest, in which case we might restrict the post-period bias to be positive, $\delta \in \Delta^{P B}:=\left\{\delta: \delta_{t} \geqslant 0 \forall t \geqslant 0\right\}$. Likewise, in some empirical settings, there may be secular pre-existing trends that we expect would have continued following the treatment date. ${ }^{10}$ We may then wish to impose that the differential trend be increasing, $\delta \in \Delta^{I}:=\left\{\delta: \delta_{t} \geqslant \delta_{t-1} \forall t\right\}$. Such sign and monotonicity restrictions

[^7]may also be combined with smoothness restrictions. For example, $\Delta^{S D P B}(M):=\Delta^{S D}(M) \cap$ $\Delta^{P B}$ and $\Delta^{R M I}(\bar{M}):=\Delta^{R M}(\bar{M}) \cap \Delta^{I}$ combine the smoothness restrictions discussed above with restrictions that the difference in trends be positive or monotonically increasing. Figure 2 gives a geometric depiction of $\Delta^{S D P B}$ and $\Delta^{R M I}$ in the three-period difference-in-differences model.

### 2.3.3 Polyhedral restrictions

The smoothness, shape, and sign restrictions discussed so far will be applicable in a variety of economic contexts. However, in some cases researchers may have context-specific knowledge that implies other types of restrictions. Throughout the paper, we therefore consider the broader class of $\Delta$ 's that take a polyhedral form, i.e. sets which can be expressed as a series of linear restrictions on $\delta$.

Assumption 2 (Polyhedral shape restriction). The class $\Delta$ takes the form $\Delta=\{\delta: A \delta \leqslant$ d\} for some known matrix $A$ and vector $d$, where the matrix $A$ has no all-zero rows.

This class of restrictions encompasses nearly all of the aforementioned examples, as well as many others. Indeed, it is immediate from Figure 2 that with two dimensions, $\Delta^{S D}, \Delta^{S D P B}$, and $\Delta^{R M I}$ are all polyhedra, and the geometric intuition from the two-period case extends to higher dimensions. ${ }^{11}$ The one exception is $\Delta^{R M}$, which is not convex and thus not a polyhedron. However, $\Delta^{R M}$ can be expressed as the union of polyhedra. One can thus form a confidence set for $\Delta^{R M}$ by taking the union of the confidence sets we develop below for each of the polyhedra that compose $\Delta^{R M}$.

Remark 2 (Bounded variation assumptions). Manski and Pepper (2018) consider identification of treatment effects under so-called "bounded variation assumptions." These assumptions can be expressed in the polyhedral form introduced in Assumption 2. Within the context of our ongoing difference-in-differences example, MP's "bounded difference-in-differences variation" assumption corresponds directly with placing a bound on the magnitude of $\left|\delta_{1}\right|$ when $\hat{\beta}_{1}$ is the coefficient from specification (3). MP also consider "bounded time" and "bounded state" variation assumptions, which correspond with bounds on the magnitudes of $\left|\mu_{11}-\mu_{10}\right|$ and $\left|\mu_{11}-\mu_{01}\right|$, where $\mu_{d s}:=\mathbb{E}[Y(0) \mid D=d, t=s]$. These restrictions can be accommodated by augmenting the vector $\hat{\beta}$ to include the sample means corresponding with

[^8]estimates of the differences in outcomes for the appropriate treatment-group by time period cells. ${ }^{12}$

Remark 3 (Ashenfelter's dip). When applying difference-in-differences to job training programs, one might worry that people who enroll in the program choose to do so in response to negative transitive shocks to earnings. If so, then the counterfactual difference in trends will exhibit the so-called Ashenfelter's dip (Ashenfelter, 1978), in which earnings groups for the treated group trend downwards (relative to control) before treatment and upwards afterwards. In this type of setting, a researchers might naturally use a polyhedral $\Delta$ to impose i) restrictions on the signs of the pre-treatment and post-treatment biases, as well as ii) restrictions on the magnitude of the rebound effect relative to the pre-treatment shock.

### 2.4 Inferential Goal

Given a particular choice of $\Delta$, our goal is to construct confidence sets that are uniformly valid for all parameter values $\theta$ in the identified set. We construct confidence sets $\mathcal{C}_{n}$ satisfying

$$
\begin{equation*}
\inf _{\delta \in \Delta, \tau} \inf _{\theta \in \mathcal{S}(\Delta, \delta+\tau)} \mathbb{P}_{\left(\delta, \tau, \Sigma_{n}\right)}\left(\theta \in \mathcal{C}_{n}\right) \geqslant 1-\alpha \tag{9}
\end{equation*}
$$

We subscript the probability operator by $\left(\delta, \tau, \Sigma_{n}\right)$ to make explicit that the distribution of $\hat{\beta}_{n}$ (and hence $\mathcal{C}_{n}$ ) depends on these parameters. In the supplemental materials, we show that the coverage requirement (9) in the normal model translates to uniform asymptotic coverage over a large class of data-generating processes.

In practice, we recommend that applied researchers tailor their choice of confidence set $\mathcal{C}_{n}$ based on their choice of $\Delta$. If the researcher selects $\Delta^{S D}(M)$ or a related $\Delta$ satisfying particular properties described below, we recommend that the researcher use the optimal fixed length confidence interval (FLCI) described in Section 3. Otherwise, we recommend that the researcher use the conditional-FLCI hybrid confidence set, which is introduced in Section 5. Our practical recommendations are based on the theoretical properties of these confidence sets that we derive in Sections 3-5 and the simulation results in Section 6. An applied reader interested in applying our methods but not their theoretical properties may wish to skip ahead to Sections 7-8, in which we provide further details on our practical recommendations and illustrate them in applications to two recently published empirical papers.

[^9]
## 3 Inference using Fixed Length Confidence Intervals

We first consider fixed length confidence intervals (FLCIs) based on affine estimators. We show that FLCIs deliver finite-sample guarantees for certain choices of $\Delta$, including our baselines smoothness class $\Delta^{S D}$, but may perform poorly for other types of restrictions.

### 3.1 Constructing FLCIs

Following Donoho (1994) and Armstrong and Kolesar (2018, 2020), we consider fixed length confidence intervals based on an affine estimator for $\theta$,

$$
\begin{equation*}
\mathcal{C}_{\alpha, n}(a, v, \chi)=\left(a+v^{\prime} \hat{\beta}_{n}\right) \pm \chi \tag{10}
\end{equation*}
$$

where $a$ and $\chi$ are scalars and $v \in \mathbb{R}^{T}+\bar{T}$. We wish to minimize the half-length of the confidence interval $\chi$ subject to the constraint that $\mathcal{C}_{\alpha, n}(a, v, \chi)$ satisfies the coverage requirement (9).

To do so, note that $a+v^{\prime} \hat{\beta}_{n} \sim \mathcal{N}\left(a+v^{\prime} \beta, v^{\prime} \Sigma_{n} v\right)$, and hence $\left|a+v^{\prime} \hat{\beta}_{n}-\theta\right| \sim\left|\mathcal{N}\left(b, v^{\prime} \Sigma_{n} v\right)\right|$, where $b=a+v^{\prime} \beta-\theta$ is the bias of the affine estimator $a+v^{\prime} \hat{\beta}_{n}$ for $\theta$. Observe further that $\theta \in \mathcal{C}_{n}(a, v, \chi)$ if and only if $\left|a+v^{\prime} \hat{\beta}_{n}-\theta\right| \leqslant \chi$. For fixed values $a$ and $v$, the smallest value of $\chi$ that satisfies (9) is therefore the $1-\alpha$ quantile of the $\left|\mathcal{N}\left(\bar{b}, v^{\prime} \Sigma_{n} v\right)\right|$ distribution, where $\bar{b}$ is the worst-case bias of the affine estimator,

$$
\begin{equation*}
\bar{b}(a, v):=\sup _{\delta \in \Delta, \tau_{\text {post }} \in \mathbb{R}^{\bar{T}}}\left|a+v^{\prime}\left(\delta+\binom{0}{\tau_{\text {post }}}\right)-l^{\prime} \tau_{\text {post }}\right| . \tag{11}
\end{equation*}
$$

Let $c v_{\alpha}(t)$ denote the $1-\alpha$ quantile of the folded normal distribution $|\mathcal{N}(t, 1)| .^{13}$ For fixed $a$ and $v$, the smallest value of $\chi$ satisfying the coverage requirement (9) is

$$
\begin{equation*}
\chi_{n}(a, v ; \alpha)=\sigma_{v, n} \cdot c v_{\alpha}\left(\bar{b}(a, v) / \sigma_{v, n}\right) \tag{12}
\end{equation*}
$$

where $\sigma_{v, n}:=\sqrt{v^{\prime} \Sigma_{n} v}$.
The minimum-length FLCI is then constructed by choosing the values of $a$ and $v$ to minimize (12). This minimization optimally trades off bias and variance, since the halflength $\chi_{n}(a, v ; \alpha)$ is increasing in both the worst-case bias $\bar{b}$ and the variance $\sigma_{v, n}^{2}$ (assuming $\alpha \in(0,0.5])$. When $\Delta$ is convex, this minimization can be solved as a nested optimization problem, where both the inner and outer minimizations are convex (Low, 1995; Armstrong

[^10]and Kolesar, 2018, 2020). We denote by $\mathcal{C}_{\alpha, n}^{F L C I}$ the $1-\alpha$ level FLCI with the shortest length,
\[

$$
\begin{equation*}
\mathcal{C}_{\alpha, n}^{F L C I}=\left(a_{n}+v_{n}^{\prime} \hat{\beta}_{n}\right) \pm \chi_{n} \tag{13}
\end{equation*}
$$

\]

where $\chi_{n}:=\inf _{a, v} \chi_{n}(a, v ; \alpha)$ and $a_{n}, v_{n}$ are the optimal values in the minimization.

Example: $\Delta^{S D}(M)$. Suppose $\theta=\tau_{1}$. For $\Delta^{S D}(M)$, the affine estimator used by the optimal FLCI takes the form

$$
\begin{equation*}
a+v^{\prime} \hat{\beta}_{n}=\hat{\beta}_{n, 1}-\sum_{s=-\underline{T}+1}^{0} w_{s}\left(\hat{\beta}_{n, s}-\hat{\beta}_{n, s-1}\right) \tag{14}
\end{equation*}
$$

where the weights $w_{s}$ sum to one (but may be negative). It takes the event-study coefficient for period 1 and subtracts out a weighted sum of the estimated slopes between consecutive pre-periods. Intuitively, since $\Delta^{S D}$ restricts the changes in the slope of the underlying trend across periods, but not the slope of the trend itself, an affine estimator with finite bias must subtract out an estimate of the slope of the trend between $t=0$ and $t=1$ using the observed slopes in the pre-period. The worst-case bias will be smaller if more weight is placed on preperiods closer to the treatment date, but it may reduce variance to place more weight on earlier pre-periods. The weights $w_{s}$ are optimally chosen to balance this tradeoff.

### 3.2 Finite-sample near optimality

In particular cases of interest, such as when $\Delta=\Delta^{S D}(M)$, the FLCIs introduced above have near-optimal expected length in the finite-sample normal model. The following result, which is an immediate consequence of results in Armstrong and Kolesar (2018, 2020), bounds the ratio of the expected length of the shortest possible confidence interval that controls size relative to the length of the optimal FLCI.

Assumption 3. Assume i) $\Delta$ is convex and centrosymmetric (i.e. $\delta \in \Delta$ implies $-\delta \in \Delta$ ), and ii) $\delta_{A} \in \Delta$ is such that $\left(\delta-\delta_{A}\right) \in \Delta$ for all $\delta \in \Delta$.

Proposition 3.1. Suppose $\delta_{A}$ and $\Delta$ satisfy Assumption 3. ${ }^{14}$ Let $\mathcal{I}_{\alpha}\left(\Delta, \Sigma_{n}\right)$ denote the class of confidence sets that satisfy the finite sample coverage criterion in (9) at the $1-\alpha$ level. Then, for any $\tau_{A} \in \mathbb{R}^{\bar{T}}, \Sigma^{*}$ positive definite, and $n>0$,

[^11]$$
\frac{\inf _{\mathcal{C}_{\alpha, n} \in \mathcal{I}_{\alpha}\left(\Delta, \Sigma_{n}\right)} \mathbb{E}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left[\lambda\left(\mathcal{C}_{\alpha, n}\right)\right]}{2 \chi_{n}} \geqslant \frac{z_{1-\alpha}(1-\alpha)-\tilde{z}_{\alpha} \Phi\left(\tilde{z}_{\alpha}\right)+\phi\left(z_{1-\alpha}\right)-\phi\left(\tilde{z}_{\alpha}\right)}{z_{1-\alpha / 2}}
$$
where $\lambda(\cdot)$ denotes the length (Lebesgue measure) of a set and $\tilde{z}_{\alpha}=z_{1-\alpha}-z_{1-\alpha / 2}$.
Part i) of Assumption 3 is satisfied for $\Delta^{S D}$ but not for our other ongoing examples. For example, $\Delta^{S D P B}$ and $\Delta^{R M I}$ are convex but not centrosymmetric, and $\Delta^{R M}$ is neither convex nor centrosymmetric. Part ii) of Assumption 3 is always satisfied when parallel trends holds in both the pre-treatment and post-treatment periods $\left(\delta_{A}=0\right)$. It also holds whenever $\delta_{A}$ is a linear trend for the case of $\Delta^{S D}(M)$. For $\alpha=0.05$, the lower bound in Proposition 3.1 evaluates to 0.72 , so the expected length of the shortest possible confidence set that satisfies the coverage requirement (9) is at most $28 \%$ shorter than the length of the optimal FLCI. ${ }^{15} \mathrm{~A}$ nice feature of this result is that it places no restrictions on $\Sigma$, and thus allows the sampling variation in the data to be large (or small) relative to the length of the identified set.

## 3.3 (In)Consistency of FLCIs

The finite-sample guarantees discussed above do not apply for several types of restrictions $\Delta$ of importance, including those that incorporate sign and shape restrictions. We now show that the FLCIs can perform poorly under such restrictions. We first provide two illustrative examples, and then introduce a formal inconsistency result.

Example: $\Delta^{S D P B}(M)$ and $\Delta^{S D I}(M)$. Suppose $\theta=\tau_{1}$. One can show that the worstcase bias of an affine estimator over $\Delta^{S D P B}(M)$ is the same as the worst-case bias for that estimator over $\Delta^{S D}(M) .{ }^{16}$ The same argument applies using $\Delta^{S D I}(M):=\Delta^{S D}(M) \cap \Delta^{I}$, which adds the restriction that $\delta$ be monotonically increasing to $\Delta^{S D}$. Since the construction of the optimal FLCI depends only on the worst-case bias and variance of the affine estimator, it follows that the optimal FLCI constructed using $\Delta^{S D P B}(M)$ or $\Delta^{S D I}(M)$ is the same as the one constructed using $\Delta^{S D}(M)$. Therefore, the optimal FLCI does not adapt to additional sign or monotonicity restrictions.

[^12]Example: $\Delta^{R M I}(\bar{M})$. Suppose $\theta=\tau_{1}$. If $\Delta=\Delta^{R M I}(\bar{M})$ and $\bar{M}>0$, then all affine estimators for $\tau_{1}$ have infinite worst-case bias. ${ }^{17}$ Thus, the FLCI is the entire real line.

We next provide a formal result on the (in)consistency of the FLCIs. Specifically, we consider "small- $\Sigma$ " asymptotics wherein the sampling uncertainty grows small relative to the length of the identified set, and consider when the FLCIs include points bounded away from the identified set with non-vanishing probability. ${ }^{18}$ Recall from Lemma 2.1 that the identified set $\mathcal{S}(\beta, \Delta)$ is an interval when $\Delta$ is convex, with length equal to $\theta^{u b}(\beta, \Delta)-\theta^{l b}(\beta, \Delta)=$ $b^{\max }\left(\beta_{\text {pre }}, \Delta\right)-b^{\min }\left(\beta_{\text {pre }}, \Delta\right)$. Since the length of the identified set only depends on $\Delta$ and $\beta_{\text {pre }}$, denote it by $\operatorname{LID}\left(\beta_{\text {pre }}, \Delta\right)$. Our next result shows that $\mathcal{C}_{\alpha, n}^{F L C I}$ is consistent if and only if $L I D\left(\beta_{\text {pre }}, \Delta\right)$ is its maximum possible value, provided that the identified set is not the entire real line (in which case any procedure is trivially consistent).

Assumption 4 (Identified set maximal length and finite). Suppose $\delta_{A, p r e}$ is such that $L I D\left(\delta_{A, \text { pre }}, \Delta\right)=\sup _{\delta_{\text {pre }} \in \Delta_{\text {pre }}} L I D\left(\delta_{\text {pre }}, \Delta\right)<\infty$, where $\Delta_{\text {pre }}=\left\{\delta_{\text {pre }} \in \mathbb{R}^{\underline{T}}: \exists \delta_{\text {post }}\right.$ s.t. $\left(\delta_{\text {pre }}^{\prime}, \delta_{\text {post }}^{\prime}\right)^{\prime} \in$ $\Delta\}$ is the set of possible values for $\delta_{\text {pre }}$.

Proposition 3.2. Suppose $\Delta$ is convex and $\alpha \in(0, .5]$. Fix $\delta_{A} \in \Delta$ and $\tau_{A} \in \mathbb{R}^{\bar{T}}$, and suppose $\mathcal{S}\left(\delta_{A}+\tau_{A}, \Delta\right) \neq \mathbb{R}$. Then $\left(\delta_{A}, \Delta\right)$ satisfy Assumption 4 if and only if $\mathcal{C}_{\alpha, n}^{F L C I}$ is consistent, meaning that

$$
\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\theta_{\text {out }} \in \mathcal{C}_{\alpha, n}^{F L C I}\right)=0 \text { for all } \theta_{\text {out }} \notin \mathcal{S}_{\theta}\left(\delta_{A}+\tau_{A}, \Delta\right)
$$

Thus, if Assumption 4 fails, then $\mathcal{C}_{\alpha, n}^{F L C I}$ is inconsistent in the strong sense that it includes fixed points outside of the identified set with non-vanishing probability. It follows that there will be some $\delta_{A} \in \Delta$ such that the FLCI is inconsistent under $\delta_{A}$ unless the identified set is always the same length. We also show in Lemma B. 26 in the Appendix that the conditions of Proposition 3.1 imply that Assumption 4 holds. Thus, the FLCIs obtain finite sample near-optimality in only a subset of the cases where they are consistent.

Remark 4. In the three-period difference-in-differences example, the length of the identified set corresponds with the height of $\Delta$ in Figure 3, and so Assumption 4 holds if and only if $\Delta$ achieves its maximal height at $\delta_{-1}$. As shown in Figure 3, the assumption holds everywhere for $\Delta^{S D}$ (since the identified set is always the same length), for values of $\delta$ where the sign restrictions do not bind for $\Delta^{S D P B}$, and nowhere for $\Delta^{R M I}$. The restrictiveness of Assumption 4 thus depends greatly on $\Delta$.

[^13]Figure 3: Diagram of where Assumptions 3 and 4 hold. The values of $\delta$ are colored red (neither holds), light green (Assumption 4 only), and dark green (both hold).



Remark 5. Proposition 3.2 implies that FLCIs can potentially be inconsistent when $\Delta$ is convex and centrosymmetric if $\delta \neq 0$. For example, if $\Delta=\left\{\delta \in \Delta^{S D}(M) \mid \delta_{1} \leqslant M\right\}$, then the FLCI is inconsistent whenever $\delta_{-1} \neq 0$, even though Proposition 3.1 implies that the FLCI is near-optimal for $\delta=0$. As discussed above, however, such inconsistency does not arise for our baseline smoothness class $\Delta^{S D}(M)$.

Remark 6. In Appendix A.1, we further show that if Assumption 4 along with an additional condition (Assumption 5 introduced below) hold, then the FLCI also has local asymptotic power approaching the power envelope under the same asymptotics considered in Proposition 3.2.

The results in this section establish that when certain conditions on $\Delta$ are satisfied, the FLCIs are consistent and have desirable finite-sample guarantees in terms of expected length. These conditions hold for our baseline smoothness class $\Delta^{S D}$, but fail for choices of $\Delta$ that may be of interest in empirical applications such as those that incorporate sign and monotonicity restrictions. This motivates us to next consider an alternative method for inference that can accommodate a larger range of restrictions.

## 4 Inference using Conditional Confidence Sets

In this section, we introduce a more general procedure for inference that has good asymptotic properties over a large class of possible restrictions $\Delta$. We show that inference on the partially identified parameter $\theta=l^{\prime} \tau_{\text {post }}$ in this setting is equivalent to testing a system of moment inequalities with a potentially large number of nuisance parameters that enter the
moments linearly. We then apply the conditional approach developed in ARP to obtain computationally tractable tests and confidence sets. We derive novel results on the asymptotic properties of the conditional test in our context, exploiting additional structure in our setting not found in ARP.

### 4.1 Representation as a moment inequality problem with linear nuisance parameters

Consider the problem of testing the null hypothesis, $H_{0}: \theta=\bar{\theta}, \delta \in \Delta$ when $\Delta=\{\delta: A \delta \leqslant$ $d\}$. We now show that testing $H_{0}$ is equivalent to testing a system of moment inequalities with linear nuisance parameters.

The model (1) implies $\mathbb{E}_{\left(\delta, \tau, \Sigma_{n}\right)}\left[\hat{\beta}_{n}-\tau\right]=\delta$, and hence $\delta \in \Delta$ if and only if $\mathbb{E}_{\left(\delta, \tau, \Sigma_{n}\right)}\left[A \hat{\beta}_{n}-A \tau\right] \leqslant$ d. Defining $Y_{n}=A \hat{\beta}_{n}-d$ and $M_{\text {post }}=[0, I]^{\prime}$ to be the matrix such that $\tau=M_{\text {post }} \tau_{p o s t}$, it is immediate that the null hypothesis $H_{0}$ is equivalent to the composite null

$$
\begin{equation*}
H_{0}: \exists \tau_{\text {post }} \in \mathbb{R}^{\bar{T}} \text { s.t. } l^{\prime} \tau_{\text {post }}=\bar{\theta} \text { and } \mathbb{E}_{\left(\delta, \tau, \Sigma_{n}\right)}\left[Y_{n}-A M_{\text {post }} \tau_{\text {post }}\right] \leqslant 0 . \tag{15}
\end{equation*}
$$

In this equivalent form, $\tau_{\text {post }} \in \mathbb{R}^{\bar{T}}$ is a vector of nuisance parameters that must satisfy the linear constraint $l^{\prime} \tau_{\text {post }}=\bar{\theta}$.

By applying a change of basis, we can further re-write $H_{0}$ as an equivalent composite null hypothesis with an unconstrained nuisance parameter. Re-write the expression $A M_{\text {post }} \tau_{\text {post }}$ as $\tilde{A}\binom{\theta}{\tilde{\tau}}$, where $\tilde{A}$ is the matrix that results from applying a suitable change of basis to the columns of $A M_{\text {post }}$, and $\tilde{\tau} \in \mathbb{R}^{\bar{T}-1} .{ }^{19}$ The null $H_{0}$ is then equivalent to

$$
\begin{equation*}
H_{0}: \exists \tilde{\tau} \in \mathbb{R}^{\bar{T}-1} \text { s.t. } \mathbb{E}\left[\tilde{Y}_{n}(\bar{\theta})-\tilde{X} \tilde{\tau}\right] \leqslant 0 \tag{16}
\end{equation*}
$$

where $\tilde{Y}(\bar{\theta})=Y_{n}-\tilde{A}_{(\cdot, 1)} \bar{\theta}$ and $\tilde{X}=\tilde{A}_{(\cdot,-1)}$. Since $\tilde{Y}_{n}(\bar{\theta})$ is normally distributed with covariance matrix $\tilde{\Sigma}_{n}=A \Sigma_{n} A^{\prime}$ under the finite-sample normal model (1), testing $H_{0}: \theta=\bar{\theta}, \delta \in \Delta$ is equivalent to testing a set of moment inequalities with linear nuisance parameters.

Remark 7. The hypothesis (16) is a special case of the testing problem studied in ARP, which focuses on testing null hypotheses of the form $H_{0}: \exists \tau$ s.t. $\mathbb{E}[Y(\theta)-X \tau \mid X] \leqslant 0$,

[^14]almost surely. Our setting is a special case of this framework in which: i) the variable $X$ takes the degenerate distribution $X=\tilde{X}$, and ii) $Y(\theta)=\tilde{Y}(\theta)$ is linear in $\theta$. The first feature plays an important role in developing our novel consistency and local asymptotic power results presented later in this section: if i) fails and $X$ is continuously distributed, then the tests proposed by ARP will generally not be consistent, as they do not allow for the number of moments to grow with $n$. The current proof of the optimal local asymptotic result also exploits the geometry of feature ii), although we conjecture that this could be relaxed to allow $Y(\theta)$ to vary smoothly in $\theta$.

### 4.2 Constructing conditional confidence sets

An important practical consideration for testing hypotheses of the form (16) is that the dimension of the nuisance parameter $\tilde{\tau} \in \mathbb{R}^{\bar{T}-1}$ grows linearly with the number of post-periods $\bar{T}$ and may be large in practice. For instance, in Section 8 we apply our methodology to a recent paper in which $\bar{T}=23$. Moreover, 5 of the 12 recent event-study papers reviewed in Roth (2019) have $\bar{T}>10$. This renders many moment inequality methods, especially those which rely on test inversion over a grid for the full parameter vector, practically infeasible in this context. We now show how the conditional approach of ARP, which directly exploits the linear structure of the hypothesis (16), can be applied to obtain computationally tractable and powerful tests even when the number of post-periods $\bar{T}$ is large. ${ }^{20}$

Suppose we wish to test (16) for some fixed $\bar{\theta}$. The conditional testing approach considers tests based on the test statistic

$$
\begin{equation*}
\hat{\eta}:=\min _{\eta, \tilde{\tau}} \eta \text { s.t. } \tilde{Y}_{n}(\bar{\theta})-\tilde{X} \tilde{\tau} \leqslant \tilde{\sigma}_{n} \cdot \eta, \tag{17}
\end{equation*}
$$

where $\tilde{\sigma}_{n}=\sqrt{\operatorname{diag}\left(\tilde{\Sigma}_{n}\right)}$. This linear program selects the value of the nuisance parameters $\tilde{\tau} \in \mathbb{R}^{\bar{T}-1}$ that produces the most slack in the maximum studentized moment. Duality results from linear programming (e.g. Schrijver (1986), Section 7.4) imply that the value $\hat{\eta}$ obtained

[^15]from the primal program (17) equals the optimal value of the dual program, ${ }^{21}$
\[

$$
\begin{equation*}
\hat{\eta}=\max _{\gamma} \gamma^{\prime} \tilde{Y}_{n}(\bar{\theta}) \text { s.t. } \gamma^{\prime} \tilde{X}=0, \gamma^{\prime} \tilde{\sigma}_{n}=1, \gamma \geqslant 0 . \tag{18}
\end{equation*}
$$

\]

If a vector $\gamma_{*}$ is optimal in the dual problem above, then it is a vector of Lagrange multipliers for the primal problem. We denote by $\hat{V}_{n}$ the set of optimal vertices of the dual program. ${ }^{22}$

To derive critical values, we analyze the distribution of $\hat{\eta}$ conditional on the event that a vertex $\gamma_{*}$ is optimal in the dual problem. Lemma 9 of ARP shows that conditional on the event $\gamma_{*} \in \hat{V}_{n}$ and a sufficient statistic $S_{n}$ for the nuisance parameters, the test statistic $\hat{\eta}$ follows a truncated normal distribution with

$$
\begin{equation*}
\hat{\eta}\left|\left\{\gamma_{*} \in \hat{V}_{n}, S_{n}=s\right\} \sim \xi\right| \xi \in\left[v^{l o}, v^{u p}\right], \tag{19}
\end{equation*}
$$

where $\xi \sim \mathcal{N}\left(\gamma_{*}^{\prime} \tilde{\mu}, \gamma_{*}^{\prime} \tilde{\Sigma}_{n} \gamma_{*}\right), \tilde{\mu}=\mathbb{E}\left[\tilde{Y}_{n}(\bar{\theta})\right], S_{n}=\left(I-\frac{\tilde{\Sigma}_{n} \gamma_{*}}{\gamma_{*}^{\prime} \tilde{\Sigma}_{n} \gamma_{*}} \gamma_{*}^{\prime}\right) \tilde{Y}_{n}(\bar{\theta})$, and $v^{l o}, v^{u p}$ are known functions of $\tilde{\Sigma}_{n}, s, \gamma_{*} .{ }^{23}$ All quantiles of the conditional distribution of $\hat{\eta}$ in the previous display are increasing in $\gamma_{*}^{\prime} \tilde{\mu},{ }^{24}$ and the null hypothesis (16) implies $\gamma_{*}^{\prime} \tilde{\mu} \leqslant 0$.

We therefore select the critical value for the conditional test to be the $1-\alpha$ quantile of the truncated normal distribution $\xi \mid \xi \in\left[v^{l o}, v^{u p}\right]$ under the worst-case assumption that $\gamma_{*}^{\prime} \tilde{\mu}=0$. Let $\psi_{\alpha}^{C}\left(\tilde{Y}_{n}(\bar{\theta}), \tilde{\Sigma}_{n}\right)$ denote an indicator for whether the conditional test rejects at the $1-\alpha$ level. The conditional test is defined as

$$
\begin{equation*}
\psi_{\alpha}^{C}\left(\tilde{Y}_{n}(\bar{\theta}), \tilde{\Sigma}_{n}\right)=1 \Longleftrightarrow F_{\xi \mid \xi \in\left[v^{l o}, v^{u p}\right]}\left(\hat{\eta} ; \gamma_{*}^{\prime} \tilde{\Sigma}_{n} \gamma_{*}\right)>1-\alpha, \tag{20}
\end{equation*}
$$

where $F_{\xi \mid \xi \in\left[v^{l o}, v^{u p}\right]}\left(\cdot ; \sigma^{2}\right)$ is the CDF of $\xi \sim \mathcal{N}\left(0, \sigma^{2}\right)$ truncated to $\left[v^{l o}, v^{u p}\right]$. It follows immediately from Proposition 6 in ARP that the conditional test controls size,

$$
\begin{equation*}
\sup _{\delta \in \Delta, \tau} \sup _{\theta \in \mathcal{S}(\Delta, \delta+\tau)} \mathbb{E}_{\left(\delta, \tau, \Sigma_{n}\right)}\left[\psi_{\alpha}^{C}\left(\tilde{Y}_{n}(\theta), \tilde{\Sigma}_{n}\right)\right] \leqslant \alpha \tag{21}
\end{equation*}
$$

A confidence set satisfying the uniform coverage criterion (9) can be constructed by test

[^16]inversion for the scalar parameter $\theta$. The conditional confidence set is given by
\[

$$
\begin{equation*}
\mathcal{C}_{\alpha, n}^{C}:=\left\{\bar{\theta}: \psi_{\alpha}^{C}\left(\tilde{Y}_{n}(\bar{\theta}), \tilde{\Sigma}_{n}\right)=0\right\} . \tag{22}
\end{equation*}
$$

\]

Remark 8. For each value of $\bar{\theta}$, the test statistic $\hat{\eta}$ can be computed by solving the linear program (17). To form the confidence set $\mathcal{C}_{\alpha, n}^{C}$, one only needs to perform test inversion over a grid of values for the scalar parameter $\theta$, and thus the problem remains highly tractable even when $\bar{T}$ is large. Moreover, the commonly-used dual simplex algorithm for linear programming returns a vertex to the dual solution (18), so an optimal dual vertex $\gamma_{*}$ can be obtained from standard solvers without further calculation.

Remark 9. Consider the simple setting in which we have one post-period ( $\bar{T}=1$ ) and are interested in the treatment effect in the first period, $\theta=\tau_{1}$. In this case, there are no nuisance parameters, and the form of the conditional test simplifies substantially. The test statistic $\hat{\eta}$ is the maximum of the studentized moments, $\hat{\eta}=\max _{j} \tilde{Y}_{n, j} / \tilde{\sigma}_{n, j}$, where $\tilde{\sigma}_{n, j}$ is the standard deviation of $\tilde{Y}_{n, j}$. The conditional test rejects in this case if and only if $\frac{\Phi(\hat{\eta})-\Phi\left(v^{l o}\right)}{1-\Phi\left(v^{l o}\right)}>1-\alpha$. Moreover, if the moments $\tilde{Y}_{n}$ are uncorrelated with each other, then $v^{l o}$ is the maximum of the non-binding studentized moments, $v^{l o}=\max _{j \neq \hat{j}} \tilde{Y}_{n, j} / \tilde{\sigma}_{n, j}$, where $\hat{j}$ denotes the location of the maximum studentized moment.

### 4.3 Consistency and optimal local asymptotic power of conditional confidence sets

We now present two novel results on the asymptotic power of the conditional test in our setting. We first show that the conditional test is consistent, meaning that any fixed point outside of the identified set is rejected with probability approaching one as the sample size $n \rightarrow \infty$.

Proposition 4.1. The conditional test is consistent. For any $\delta_{A} \in \Delta, \tau_{A} \in \mathbb{R}^{\bar{T}}$, and $\theta^{\text {out }} \notin$ $\mathcal{S}\left(\delta_{A}+\tau_{A}, \Delta\right)$,

$$
\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\theta_{\text {out }} \notin \mathcal{C}_{\alpha, n}^{C}\right)=1
$$

Thus, in contrast to the optimal FLCI, the conditional test is consistent for all polyhedral $\Delta$.

We next consider the local asymptotic power of the conditional test. We provide a condition under which the power of the conditional test against local alternatives converges to the power envelope. This condition guarantees that the binding and non-binding moments are sufficiently well-separated at points close to the boundary of the identified set.

Assumption 5. Let $\Delta=\{\delta: A \delta \leqslant d\}$ and fix $\delta_{A} \in \Delta$. Consider the optimization:

$$
b^{\max }\left(\delta_{A, p r e}\right)=\max _{\delta} l^{\prime} \delta_{\text {post }} \text { s.t. } A \delta \leqslant d, \delta_{\text {pre }}=\delta_{A, \text { pre }}
$$

and assume it has a finite solution. For $\delta^{*}$ a maximizer to the above problem, let $B\left(\delta^{*}\right)$ index the set of binding inequality constraints, so that $A_{\left(B\left(\delta^{*}\right), \cdot\right)} \delta^{*}=d_{B\left(\delta^{*}\right)}$ and $A_{\left(-B\left(\delta^{*}\right), \cdot\right)} \delta^{*}-$ $d_{-B\left(\delta^{*}\right)}=-\epsilon_{-B\left(\delta^{*}\right)}<0$. Assume that there exists a maximizer $\delta^{*}$ to the problem above such that the rank of $A_{\left(B\left(\delta^{*}\right), p o s t\right)}$ is equal to $\left|B\left(\delta^{*}\right)\right|$. Analogously, assume that there is a finite solution to the analogous problem that replaces max with min, and that there is a minimizer $\delta^{* *}$ such that $A_{\left(B\left(\delta^{* *)}\right), p o s t\right)}$ has rank $\left|B\left(\delta^{* *}\right)\right|$.

Assumption 5 considers the problem of finding the differential trend $\delta \in \Delta$ that is consistent with the pre-trend identified from the data $\left(\delta_{A, p r e}\right)$ and causes $l^{\prime} \hat{\beta}_{\text {post }}$ to be maximally biased for $\theta:=l^{\prime} \tau_{\text {post }}$. It requires that the "right" number of moments bind when we do this optimization.

Remark 10. Assumption 5 is closely related to, but slightly weaker than, linear independence constraint qualification (LICQ). LICQ has been used recently in the moment inequality settings of Gafarov (2019), Cho and Russell (2019), Flynn (2019), and Kaido and Santos (2014); see Kaido, Molinari and Stoye (2020) for a synthesis. We show in Appendix A. 2 that LICQ is equivalent to a modified version of Assumption 5 that replaces "there exists a maximizer $\delta^{* "}$ with "for every maximizer $\delta^{* "}$ (and analogously for the minimizer $\delta^{* *}$ ). Thus, LICQ is equivalent to Assumption 5 when the optimizations considered in Assumption 5 have unique solutions, but potentially weaker when there are multiple solutions. We note that many of the aforementioned papers require LICQ for asymptotic size control, whereas we only impose Assumption 5 for our results on local asymptotic power.

Remark 11. In the special case with one pre-period ( $\underline{T}=1$ ) and one post-period $(\bar{T}=1)$, Assumption 5 has a simple graphical interpretation. It is satisfied whenever $\Delta$ has nonempty interior and $\delta$ is not vertically aligned with a vertex. Figure 4 shows the areas at which Assumption 5 holds/fails for three of our ongoing examples. The assumption holds everywhere for $\Delta^{S D}$ when $M>0$, and Lebesgue almost everywhere for $\Delta^{S D P B}$ and $\Delta^{R M I}$ when $M>0$ and $\bar{M}>0$. The sets $\Delta^{S D}(0), \Delta^{S D P B}(0), \Delta^{R M I}(0)$ all have empty interior, and so Assumption 5 fails for these cases (in which $\theta$ is point-identified). More generally, one can show that Assumption 5 does not hold if $\theta$ is point identified.

Figure 4: Diagram of where Assumption 5 holds. The assumption holds (fails) for values of $\delta$ plotted in green (red).



Let $\mathcal{I}_{\alpha}\left(\Delta, \Sigma_{n}\right)$ denote the class of confidence sets that satisfy the finite sample coverage criterion in (9) at the $1-\alpha$ level. Under Assumption 5, the power of the conditional test against local alternatives converges to the optimum over $\mathcal{I}_{\alpha}\left(\Delta, \Sigma_{n}\right)$ as $n \rightarrow \infty$.

Proposition 4.2. Fix $\delta_{A} \in \Delta, \tau_{A}$, and suppose $\Sigma^{*}$ is positive definite. Let $\theta_{A}^{u b}=\sup _{\theta} \mathcal{S}\left(\delta_{A}+\right.$ $\left.\tau_{A}, \Delta\right)$ be the upper bound of the identified set. Suppose Assumption 5 holds. Then, for any $x>0$,

$$
\begin{aligned}
\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\alpha, n}^{C}\right) & =\lim _{n \rightarrow \infty} \sup _{\mathcal{C}_{\alpha, n} \in \mathcal{I}_{\alpha}\left(\Delta, \Sigma_{n}\right)} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\alpha, n}\right) \\
& =\Phi\left(c^{*} x-z_{1-\alpha}\right),
\end{aligned}
$$

for a positive constant $c^{*} .{ }^{25}$ The analogous result holds replacing $\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x$ with $\theta_{A}^{l b}-\frac{1}{\sqrt{n}} x$, for $\theta_{A}^{l b}$ the lower bound of the identified set (although the constant $c^{*}$ may differ).

We now provide an outline of the proof of our local asymptotic optimality result, the details of which are contained in the appendix. The proof proceeds in two parts: the first part characterizes the asymptotically optimal test, and the second shows that our conditional test converges to this optimal test.

We first show that under Assumption 5, the local asymptotic power of any test that controls size is bounded above by that of a particular one-sided t-test. Specifically, Assumption 5 implies that there is a unique set of Lagrange multipliers $\bar{\gamma}$ in the "population version" of

[^17]the test statistic $\hat{\eta}\left(\theta^{u b}\right)$ that replaces $\tilde{Y}\left(\theta^{u b}\right)$ with its expectation $\tilde{\mu}\left(\theta^{u b}\right)$ in (17). We then show that testing $H_{0}: \theta=\theta^{u b}, \delta \in \Delta$ against a local alternative can be represented as a test of a convex null against a point alternative in the normal location model. Applying the Neyman-Pearson lemma, we show that the optimal test is a one-sided t-test in the direction of $\bar{\gamma}$ for alternatives sufficiently close to $\theta^{u b}$.

We next show that the conditional test converges in probability to the optimal one-sided t-test discussed above. Since Assumption 5 implies that $\bar{\gamma}$ is the unique dual solution to the "population version" of $\hat{\eta}$, it follows that $\bar{\gamma}$ will be optimal in the dual problem for $\hat{\eta}$ with probability approaching one as $\Sigma_{n} \rightarrow 0$. Thus, with probability approaching one the test statistic for the conditional test will be $\hat{\eta}=\bar{\gamma}^{\prime} \tilde{Y}$, which corresponds with that of the one-sided t-test. Finally, recall that the critical value of the conditional test is based on the $1-\alpha$ quantile of the distribution of $\gamma_{*}^{\prime} \tilde{Y}$ conditional on $\gamma_{*}$ being optimal. However, since $\bar{\gamma}$ is optimal with probability approaching 1 , the distribution of $\bar{\gamma}^{\prime} \tilde{Y}$ conditional on $\bar{\gamma}$ being optimal approaches its unconditional distribution, which is normal. Thus, the critical value of the conditional test approaches the $1-\alpha$ quantile of the normal distribution. ${ }^{26}$

Remark 12. Equation (21) and Proposition 4.2 together show that the conditional approach uniformly controls size over all values of $\delta \in \Delta$, and is asymptotically efficient when $\delta$ further satisfies Assumption 5. In general, we cannot guarantee that the bounds of the identified set will be differentiable as a function of $\beta=\delta+\tau$, and the impossibility results in Hirano and Porter (2012) imply that no regular estimators of the identified set bounds exist when differentiability fails. However, one can show that if Assumption 5 holds, then the identified set bounds are differentiable in $\beta$. Proposition 4.2 therefore implies that although the conditional test controls size uniformly for all values of $\delta \in \Delta$, this does not come at the expense of efficiency in cases where Assumption 5 holds. Since researchers often do not know ex ante whether Assumption 5 is satisfied, this "robustness" property is desirable. Our results are thus somewhat analogous to results in the weak identification literature that show that certain procedures control size under weak identification but are efficient under strong identification (e.g., Moreira (2003)).

Remark 13 (Relationship to other methods). We are not aware of results analogous to Proposition 4.2 for any other moment inequality procedure that controls size in the finite sample normal model. Observe that if Assumption 5 holds, then it also holds if $\Delta$ is augmented to include a moment that is non-binding at both endpoints of the identified set. Hence, for Proposition 4.2 to hold, the local asymptotic power of the test needs to be unaffected by the inclusion of such slack moments. For example, although relatively insensitive

[^18]to the inclusion of slack moments, the procedures of Romano, Shaikh and Wolf (2014) and Andrews and Barwick (2012) are still affected by the inclusion of slack moments via the changes to the first-stage critical value and size-adjustment factor, respectively. ${ }^{27}$

Remark 14 (Finite sample power of the conditional test). Note that the argument above for the optimality of the conditional approach relies on a unique vector of Lagrange multipliers $\bar{\gamma}$ being dual-optimal with probability approaching 1 asymptotically. The asymptotic guarantees of Proposition 4.2 thus may not translate to good finite-sample performance in settings where multiple vectors of Lagrange multipliers are optimal with nontrivial probability. Since a vector of Lagrange multipliers corresponds with a set of active moments in the primal problem (17), this will tend to occur in cases where the set of binding and non-binding moments are not "well-separated" relative to the sampling variation in the data. Such a situation will tend to arise when Assumption 5 is "close" to being violated. ${ }^{28}$

## 5 Conditional-FLCI Hybrid Confidence Sets

Taken together, the results in Section 3 show that the FLCIs have attractive finite-sample properties for particular classes $\Delta$ of interest, but they may perform poorly even asymptotically for other types of restrictions. On the other hand, the conditional tests have good asymptotic properties for a wider range of restrictions, but they may perform poorly in finite samples in settings where the binding and non-binding moments are not well-separated relative to the sampling variation in the data. To address these differing strengths, we propose a novel confidence set that hybridizes the conditional test with the optimal FLCI based on an affine estimator. This conditional-FLCI hybrid confidence set achieves similar desirable asymptotic properties as the conditional confidence set for a wide range of $\Delta \mathrm{s}$. In simulations (discussed in more detail below), it leads to substantial improvements in the power of the conditional test in a variety of cases where the moments are not well-separated.

The conditional-FLCI hybrid confidence set is constructed by first testing whether a candidate parameter value lies within the optimal level- $(1-\kappa)$ FLCI, and then applying a conditional test to all parameter values that lie within the optimal FLCI. In the second stage, we use a modified version of the conditional test that i) adjusts size to account for the first-stage test, and ii) conditions on the event that the first-stage test fails to reject. Since

[^19]the construction of the hybrid test uses similar steps to the construction of the FLCIs and conditional test, we defer many of the technical details to Appendix A.3.

Formally, suppose that $0<\kappa<\alpha .{ }^{29}$ Consider the level $(1-\kappa)$ optimal FLCI, $\mathcal{C}_{\kappa, n}^{F L C I}=$ $a_{n}+v_{n}^{\prime} \hat{\beta}_{n} \pm \chi_{n}$. Lemma A. 3 shows that the distribution of the test statistic $\hat{\eta}$ defined in (17) follows a truncated normal distribution conditional on the parameter value $\bar{\theta}$ falling within the level $(1-\kappa)$ optimal FLCI. With this result, the construction of the second-stage of the conditional-FLCI hybrid test is analogous to the construction of the conditional test, except it uses the modified size $\tilde{\alpha}=\frac{\alpha-\kappa}{1-\kappa}$ to account for the first-stage test. The conditional-FLCI hybrid test $\psi_{C-F L C I}$ equals

$$
\psi_{\kappa, \alpha}^{C-F L C I}\left(\hat{\beta}_{n}, \bar{\theta}, \tilde{\Sigma}_{n}\right)=1 \Longleftrightarrow \theta \notin \mathcal{C}_{\kappa, n}^{F L C I}, \quad \text { OR } F_{\xi \mid \xi \in\left[v_{C-F L C I}^{l}, v_{C-F L C I} u^{u}\right]}(\hat{\eta})>1-\tilde{\alpha},
$$

where $F_{\xi \mid \xi \in\left[v_{C-F L C I} v^{l}, v_{C-F L C I I}\right]}(\cdot)$ denotes the CDF of the truncated normal distribution derived in Lemma A.3.

Since the FLCI controls size, the first stage test rejects with probability at most $\kappa$ under the null that $\theta=\bar{\theta}$. The second-stage test rejects with probability at most $\tilde{\alpha}=\frac{\alpha-\kappa}{1-\kappa}$ conditional on $\theta \in \mathcal{C}_{\kappa, n}^{F L C I}$. Together, these results imply that the conditional-FLCI hybrid test controls size,

$$
\begin{equation*}
\sup _{\delta \in \Delta, \tau} \sup _{\theta \in \mathcal{S}(\Delta, \delta+\tau)} \mathbb{E}_{\left(\delta, \tau, \Sigma_{n}\right)}\left[\psi_{\kappa, \alpha}^{C-F L C I}\left(\hat{\beta}_{n}, \bar{\theta}, \tilde{\Sigma}_{n}\right)\right] \leqslant \alpha \tag{23}
\end{equation*}
$$

We therefore construct a conditional-FLCI hybrid confidence set for the parameter $\theta$ that satisfies (9) by inverting the conditional-FLCI test,

$$
\begin{equation*}
\mathcal{C}_{\kappa, \alpha, n}^{C-F L C I}=\left\{\theta: \psi_{\kappa, \alpha}^{C-F L C I}\left(\hat{\beta}_{n}, \bar{\theta}, \tilde{\Sigma}_{n}\right)=0\right\} . \tag{24}
\end{equation*}
$$

In Appendix A.3, we show that the conditional-FLCI hybrid confidence set inherits some desirable asymptotic properties from the conditional approach: it is asymptotically consistent, and under the same conditions as Proposition 4.2, the conditional-FLCI hybrid test has local asymptotic power at least as good as the optimal $\frac{\alpha-\kappa}{1-\kappa}$ test.

## 6 Simulation study

In this section, we present a series of simulations illustrating the performance of the confidence sets discussed above across a range of relevant data-generating processes. We find

[^20]good size control for all three of our proposed procedures, and therefore focus in the main text on a comparison of power. In the supplementary material, we present results on size control and other additional simulation results.

### 6.1 Simulation Design

Our simulations are calibrated using the estimated covariance matrix from the 12 recentlypublished papers surveyed in Roth (2019). ${ }^{30}$ For any given paper in the survey, we denote by $\hat{\Sigma}$ the estimated variance-covariance matrix from the event-study in the paper, calculated using the clustering scheme specified by the authors. We then simulate event-study coefficients $\hat{\beta}_{s}$ from a normal model under the assumption of parallel trends and zero treatment effects, $\hat{\beta}_{s} \sim \mathcal{N}(0, \hat{\Sigma}) \cdot{ }^{31}$ In simulation $s$, we construct nominal $95 \%$ confidence intervals for the parameter of interest $\theta$ using the pair $\left(\hat{\beta}_{s}, \hat{\Sigma}\right)$ for each proposed procedure. The parameter of interest is the causal effect in the first post-period $\left(\theta=\tau_{1}\right) .{ }^{32}$

For a given choice of $\Delta$, we compute the identified set $\mathcal{S}(0, \Delta)$ and calculate the expected excess length for each of the proposed confidence sets. The excess length of a confidence set $\mathcal{C}(\hat{\beta})$ is the length of the part of the confidence set that falls outside of the identified set, defined as $E L(\mathcal{C} ; \hat{\beta})=\lambda(\mathcal{C}(\hat{\beta}) \backslash \mathcal{S}(0, \Delta))$. We benchmark the expected excess length of our proposed procedures relative to the optimal bound over confidence sets that satisfy the uniform coverage requirement (9). ${ }^{33}$ For each paper, we conduct 1000 simulations and compute the optimal bound and the average excess length for the FLCI, conditional confidence set, FLCI, and conditional-FLCI hybrid confidence set. The excess length efficiency of a given procedure equals the ratio of the optimal bound to the simulated expected excess length. We report the efficiency ratios for the median paper in the survey.

We consider three choices of $\Delta$ to highlight the performance of the confidence sets across a range of conditions: $\Delta^{S D}(M), \Delta^{S D P B}(M)$ and $\Delta^{S D I}(M)$. Table 1 summarizes which of our theoretical results hold for each of the simulation designs.

In all simulations, the units of the parameter $M$ are standardized to equal the standard

[^21]|  | $\Delta^{S D}$ | $\Delta^{S D P B}$ | $\Delta^{S D I}$ |
| :--- | :---: | :---: | :---: |
| Conditional / Hybrid |  |  |  |
| Consistent | $\checkmark$ | $\checkmark$ | $\checkmark$ |
| Asymptotically (near-)optimal | $\checkmark$ | $\checkmark$ | $\times$ |
| FLCI |  |  |  |
| Consistent | $\checkmark$ | $\times$ | $\times$ |
| Asymptotically (near-)optimal | $\checkmark$ | $\times$ | $\times$ |
| Finite-sample near-optimal | $\checkmark$ | $\times$ | $\times$ |

## Table 1: Summary of expected properties for each simulation design

error of the first post-period event study coefficient $\left(\sigma_{1}\right)$. We show results for a variety of choices of $M / \sigma_{1}$. All of the procedures and the optimal benchmarks are invariant to scale, meaning that the confidence set (or optimal benchmark) using $\left(M, \frac{1}{n} \Sigma^{*}\right)$ is $\frac{1}{n}$ times that using $\left(n M, \Sigma^{*}\right)$. Therefore, simulation results on excess length as $M / \sigma_{1}$ grows large are isomorphic to our asymptotic results presented earlier in which $n \rightarrow \infty$ for $\Sigma_{n}=\frac{1}{n} \Sigma^{*}$ and $M>0$ fixed. The simulation results also have a finite-sample interpretation, illustrating how our results change as we allow the set of underlying trends to be more non-linear, holding $\Sigma^{*}$ constant.

The supplementary materials present results from several alternative simulation exercises. We find similar results using the empirical distribution from the first paper in Roth (2019)'s survey rather than the calibrated normal model studied in the main text. We also find qualitatively similar results when using the average of the post-treatment causal effects as the target parameter.

### 6.2 Simulation Results

Results for $\Delta^{S D}(M)$ : The top left panel of Figure 5 plots the efficiency ratio for each procedure as a function of $M / \sigma_{1}$ when $\Delta=\Delta^{S D}$. All procedures perform well as $M / \sigma_{1}$ grows large with efficiency ratios approaching 1 , illustrating our asymptotic (near-)optimality results. The FLCIs also perform quite well for smaller values of $M / \sigma_{1}$, including the pointidentified case where $M=0$, illustrating the finite-sample near-optimality results for the FLCIs when Assumption 3 holds. Although the conditional confidence sets have efficiency approaching the optimal bound for $M / \sigma_{1}$ large, their efficiency when $M / \sigma_{1}=0$ is only about $50 \%$. This reflects the fact that when $M=0$, the parameter is point-identified and Assumption 5 fails. The conditional-FLCI hybrid substantially improves efficiency for small values of $M / \sigma_{1}$, while still retaining near-optimal performance as $M / \sigma_{1}$ grows large.

Results for $\Delta^{S D P B}(M)$ : The top right panel of Figure 5 plots the efficiency ratio for each procedure as a function of $M / \sigma_{1}$ when $\Delta=\Delta^{S D P B}$. The efficiency ratios for the conditional

Figure 5: Simulation results: Median efficiency ratios for proposed procedures.


Note: Median efficiency ratios for our proposed confidence sets. The efficiency ratio for a procedure is defined as the optimal expected excess length divided by the procedure's actual expected excess length. The results for the FLCI are plotted in green, the results for the conditional-FLCI hybrid confidence interval in red and the results for the conditional confidence interval in blue. Results are averaged over 1000 simulations for each of the 12 papers surveyed, and the median across papers is reported here.
and hybrid confidence sets are (near-)optimal as $M / \sigma_{1}$ grows large, highlighting our asymptotic (near-)optimality results for these procedures in this simulation design. However, the efficiency ratios for the FLCIs steadily decrease as $M / \sigma_{1}$ increases, which reflects the fact that the FLCIs are not consistent in this simulation design when $M>0$. We again see that the conditional-FLCI hybrid improves efficiency when $M / \sigma_{1}$ is small, while retaining near-optimal performance as $M / \sigma_{1}$ grows large.

Results for $\Delta^{S D I}$ The bottom panel of Figure 5 plots the efficiency ratio for each procedure as a function of $M / \sigma_{1}$ when $\Delta=\Delta^{S D I}$. As summarized in Table 1, the conditions for asymptotic (near-)optimality do not hold for any of our procedures in this simulation design. Nonetheless, the conditional and hybrid procedures still perform quite well for large values of $M / \sigma_{1}$, with efficiency approaching about $90 \%$. This evidence is encouraging as it shows that they may perform well asymptotically in cases where Assumption 5 fails. The efficiency of the FLCIs degrades as $M / \sigma_{1}$ grows, reflecting that the FLCIs are inconsistent under this simulation design when $M>0$. Once again, the conditional-FLCI hybrid improves efficiency when $M / \sigma_{1}$ is small, while retaining similar performance to the conditional approach as $M / \sigma_{1}$ grows large.

## 7 Practical Guidance

We now provide practical guidance on how these methods may be used to assess the robustness of conclusions in difference-in-differences and event-study designs. We recommend that applied researchers conduct the following steps to assess the robustness of their conclusions in difference-in-differences and related designs.

1) Estimate an "event-study"-type specification that produces a vector of asympototically normal estimates $\hat{\beta}$, consisting of "pre-period" coefficients $\hat{\beta}_{\text {pre }}$ and "post-period" coefficients $\hat{\beta}_{\text {post }}$, where the post-period coefficients have a causal interpretation under a suitable parallel trends assumption.
2) Perform a sensitivity analysis where inference is conducted under different assumptions about the set of possible violations of parallel trends $\Delta$.
3) Provide economic benchmarks for evaluating the different choices of $\Delta$. This involves using context-specific knowledge about potential confounding factors or using information from pre-treatment periods and placebo groups.

We recommend researchers select either the optimal FLCI or the conditional-FLCI hybrid conditional confidence set based upon the properties of their specified choice of $\Delta$. For cases (e.g. $\Delta=\Delta^{S D}(M)$ ) where the conditions for the consistency of the FLCIs are nonrestrictive and the conditions for finite-sample near-optimality under parallel trends hold, we recommend that the researchers use the optimal FLCI. Outside of these special cases e.g., when context-specific knowledge motivates sign or shape restrictions - we recommend that researchers use the conditional-FLCI hybrid confidence set. Our R package, HonestDiD, implements our methods and chooses the recommended procedure by default.

### 7.1 When to Use Our Methods

The methods in this paper can be applied in most empirical settings in which researchers use an "event-study plot" to evaluate pre-existing trends. Our methods require the researcher to use an estimator $\hat{\beta}_{n}$ with an asymptotic normal limit, $\sqrt{n}\left(\hat{\beta}_{n}-\beta\right) \rightarrow_{d} \mathcal{N}\left(0, \Sigma^{*}\right)$, and that the reduced-form parameter $\beta$ satisfies the causal decomposition in Assumption 1. We now address two considerations that commonly arise in practice: i) staggered treatment timing, and ii) anticipatory effects.

First, a recent literature has shown that the coefficients from standard two-way fixed effect models may not be causally interpretable in the presence of staggered treatment timing and heterogeneous treatment effects across cohorts. To address these issues, Sun and Abraham (2020) and Callaway and Sant'Anna (2020) provide alternative strategies for estimating weighted averages of cohort-specific treatment effects at a fixed lag (or for placebo analysis, lead) relative to treatment, which yield consistent estimates under a suitable parallel trends assumption. ${ }^{34}$

These estimates are asymptotically normal under mild regularity conditions, and so our recommended sensitivity analysis can be applied to gauge sensitivity to violations of the needed parallel trends assumption. In empirical settings with staggered treatment timing and heterogeneous treatment effects, we therefore recommend that researchers first use the methods of Sun and Abraham (2020) or Callaway and Sant'Anna (2020) for estimation and then apply our results to conduct sensitivity analysis.

Next, in some cases, there may be changes in behavior in anticipation of the policy of interest, and therefore, $\beta_{\text {pre }}$ may reflect the anticipatory effects of the policy (e.g., see Malani and Reif (2015)). This violates Assumption 1, which assumes pre-treatment coefficients do

[^22]not reflect causal effects. A simple solution is available if one is willing to assume that anticipatory effects only occur in a fixed window prior to the policy change. Under such an assumption, the researcher may re-normalize the definition of the "pre-treatment" period to be the period prior to when anticipatory effects can occur, in which case $\beta_{\text {pre }}$ is determined only based on untreated potential outcomes.

### 7.2 Sensitivity Analysis

We recommend that researchers report confidence sets under different assumptions about the set of possible differences in trends $\Delta$. This allows the reader to evaluate what assumptions need to be imposed in order to obtain informative inference.

For instance, in many cases a reasonable baseline choice for $\Delta$ may be $\Delta^{S D}(M)$, which relaxes the assumption of linear differences in trends by imposing that the slope of the differential trend can change by no more than $M$ in consecutive periods. By reporting robust confidence sets for different values of $M$, the researcher may evaluate the extent to which their conclusions change as we allow for the possibility of greater non-linearities in the underlying trend. If there is a particular null hypothesis of interest (e.g. the treatment effect is zero), the researcher can report the "breakdown" value of $M$ at which the null hypothesis can no longer be rejected. ${ }^{35}$ The researcher may also assess how these conclusions change if they impose further sign or shape restrictions motivated by context-specific economic knowledge - e.g. the bias is weakly positive, or the trend is monotone.

### 7.3 Evaluating a choice of $\Delta$

When conducting sensitivity analysis over possible choices of $\Delta$, researchers may wonder how to evaluate whether a particular choice of $\Delta$ is reasonable. For instance, suppose a researcher is considering sets of the form $\Delta^{S D}(M)$. How, then, should she evaluate what value of possible non-linearity $M$ is reasonable? For ease of exposition, we focus on how to evaluate the choice of $M$, although analogous remarks apply to conducting sensitivity for other forms of $\Delta$ as well.

Nothing in the data itself can place an upper bound on the parameter $M$. This is because $M$ bounds the magnitude of possible non-linearity in the counterfactual difference in trends $\delta_{\text {post }}$ and thus is not identified. Applied researchers therefore must use domain-specific knowledge to evaluate whether a particular choice of $M$ is plausible in a given empirical

[^23]setting. To help applied researchers do so, we discuss two approaches that benchmark possible values of $M$ using knowledge of potential confounds and using untreated groups or periods.

Benchmarking using knowledge of potential confounds. Applied researchers may calibrate $M$ by considering the types of economic mechanisms that would produce a violation of the parallel trends assumption, and benchmark $M$ using knowledge of the likely magnitudes of those mechanisms. This suggestion echoes Kahn-Lang and Lang (2020), who advocate for the use of domain-specific knowledge in justifying the parallel trends assumption. We provide an example of this type of reasoning in our application to Lovenheim and Willen (2019) in Section 8.

Benchmarking using untreated groups or periods. In some settings, researchers may observe untreated (placebo) groups who they think are "at least as dissimilar" as the groups used in their main analysis. In this case, it may be sensible to form a confidence interval for the largest change in slope between periods among the placebo groups, and use the upper bound of that interval as a benchmark for $M .{ }^{36}$ Along similar lines, one could also construct an upper bound on the largest change in slope in the pre-period for the groups used in the main event-study of interest. One could then benchmark $M$ in terms of multiples of the largest value observed in the pre-period. ${ }^{37}$

Finally, while an upper bound on the parameter $M$ may not be learned from the data, the observed pre-period data may provide an informative lower bound on possible values of $M$. Since $M$ is an upper limit on how much the slope of $\delta$ can change between periods, the largest second difference in $\delta_{\text {pre }}$ must be no larger than $M$ in absolute value. As $\delta_{\text {pre }}$ equals the expected value of the pre-period coefficients $\hat{\beta}_{\text {pre }}$, we can test this hypothesis using the pre-period coefficients. ${ }^{38}$ We caution, however, that this exercise provides only a lower bound

[^24]on the possible value of $M$. The fact that the pre-period second differences in $\delta$ are small does not on its own place a bound on how large the second differences in the post-period could have been under the counterfactual. Nonetheless, this test may be useful in diagnosing situations where the researcher-imposed bound is implausible.

## 8 Empirical Applications

We now apply our methods to two recently published papers, illustrating how empirical researchers may use these methods to conduct formal sensitivity analyses in difference-indifferences and event-study designs.

### 8.1 The effect of duty-to-bargain laws on long-run student outcomes

Lovenheim and Willen (2019, henceforth LW) study the impact of state-level public sector duty-to-bargain (DTB) laws, which mandated that school districts bargain in good faith with teachers' unions. LW examine the impacts of these laws on the adult labor market outcomes of people who were students around the time that these laws were passed, comparing individuals across different states and different birth cohorts to exploit the differential timing of the passage of DTB laws across states. The authors estimate the following regression specification separately for men and women, using data from the American Community Survery (ACS),

$$
\begin{equation*}
Y_{s c t}=\sum_{r=-11}^{21} D_{s c r} \beta_{r}+X_{s c t}^{\prime} \gamma+\lambda_{c t}+\phi_{s}+\epsilon_{s c t} . \tag{25}
\end{equation*}
$$

$Y_{\text {sct }}$ is an average outcome for the cohort of students born in state $s$ in cohort $c$ in ACS calendar year $t . D_{s c r}$ is an indicator for whether state $s$ passed a DTB law $r$ years before cohort $c$ turned age 18. ${ }^{39}$ The coefficients $\left\{\hat{\beta}_{r}\right\}$ estimate the dynamic treatment effect (or placebo effect) $r$ years after DTB passage. ${ }^{40}$ The remaining terms include time-varying controls, birth-cohort-by-ACS-year fixed effects, and state fixed effects. Standard errors are

[^25]clustered at the state level as in LW, and we normalize the coefficient $\beta_{-2}$ to $0 .{ }^{41}$ We focus on the results where the outcome is employment.

Figure 6: Event-study coefficients $\left\{\beta_{r}\right\}$ for employment, estimated using the event-study specification in (25).


Figure 6 plots the estimated event-study coefficients $\left\{\hat{\beta}_{r}\right\}$ from specification (25). In the event-study for men (left panel), the pre-period coefficients are relatively close to zero, whereas the longer-run post-period coefficients are negative. By contrast, the results for women (right panel) suggest a downward-sloping pre-existing trend. LW therefore interpret the results for men causally, and "urge caution in lending a causal interpretation" to the results for women.

Figure 7 reports results of a sensitivity analysis for the treatment effect on employment for the cohort 15 years after the passage of a DTB law (as in Table 2 of LW), constructing robust confidence sets under varying assumptions on the class of possible violations of parallel trends. In blue, we plot the original OLS confidence intervals for $\hat{\beta}_{15}$ from specification (25). In red, we plot FLCIs when $\Delta=\Delta^{S D}(M)$ for different values of $M$. In the sensitivity analysis for men (left panel), we see that the FLCIs are similar to those from OLS when allowing for violations of parallel trends that are approximately linear ( $M \approx 0$ ), but become wider as we allow for more non-linearity; the breakdown value for a significant effect is $M \approx 0.01$. For women (right panel), the original OLS estimates are negative and the confidence interval rules out 0 . When we allow for linear violations of parallel trends $(M=0)$, however, the picture changes substantially owing to the pre-existing downward trend that is visible in

[^26]Figure 7: Sensitivity analysis for $\theta=\tau_{15}$ using $\Delta=\Delta^{S D}(M)$


Figure 6. Indeed, for $M<0.01$ the robust confidence set contains only positive values. Thus, if we were to impose the same smoothness restrictions for men as for women, we would either have to reconcile significant effects of opposite signs by gender (if $M<0.01$ ) or we would not be able to rule out null effects for both genders $(M \geqslant 0.1)$.

Figure 8: Sensitivity analysis with and without imposing monotonicity


LW attribute the downward-sloping pre-trend in employment for women to "secular trends" affecting female labor supply, motivating us to introduce the shape restriction that $\delta$ is monotonically decreasing. Figure 8 shows how the sensitivity analysis for women changes when we incorporate this shape restriction, comparing the earlier results for $\Delta=\Delta^{S D}(M)$ to those using $\Delta=\Delta^{S D D}:=\Delta^{S D}(M) \cap\left\{\delta: \delta_{t} \leqslant \delta_{t-1}, \forall t\right\}$. The confidence sets imposing
the shape restriction are constructed using the conditional-FLCI hybrid. We see that these shape restrictions can be informative: the lower bound of the robust confidence set over $\Delta^{S D D}(M)$ never falls substantially below the lower bound of the OLS confidence interval, even when $M$ is large.

To evaluate the magnitudes of $M$, we consider the following calibration exercise: if violations of parallel trends were driven by confounding changes in education quality, what would a given value of $M$ imply about the evolution of those confounds? Chetty, Friedman and Rockoff (2014) estimate that a 1 standard deviation increase in teacher value-added (VA) corresponds with a 0.4 percentage point increase in adult employment. Hence, a value of $M=0.01$ would correspond with allowing the slope of the differential trend in education quality to change by one-fourtieth of a standard deviation of teacher VA across consecutive periods. Since the robust confidence sets for both men and women begin to include zero around this value of $M$, the strength with which we can rule out a null effect depends on our assessment of the economic plausibility of such non-linearities.

### 8.2 Estimating the incidence of a value-added tax cut

Benzarti and Carloni (2019, henceforth, BC) study the incidence of a decrease in the valueadded tax (VAT) on restaurants in France. France reduced its VAT on sit-down restaurants from 19.6 to 5.5 percent in July of 2009. BC analyze the impact of this change using a dynamic difference-in-differences design that compares restaurants to a control group of other market services firms that were not affected by the VAT change. Their regression specification is

$$
\begin{equation*}
Y_{i r t}=\sum_{s=2004}^{2012} \beta_{s} \times 1[t=s] \times D_{i r}+\phi_{i}+\lambda_{t}+\epsilon_{i r t}, \tag{26}
\end{equation*}
$$

where $Y_{i r t}$ is an outcome of interest for firm $i$ in region $r$ in year $t ; D_{i r}$ is an indicator for whether firm $i$ in region $r$ is a restaurant; and $\phi_{i}$ and $\lambda_{t}$ are firm and year fixed effects. The coefficient $\beta_{2008}$ is normalized to 0 . BC cluster standard errors at the regional level. BC's main finding is that the VAT reduction had a large effect on restaurant profits. Figure 9 shows the estimated event-study coefficients from specification (26) when the outcome is the $\log$ of (before-tax) restaurant profits.

The left panel of Figure 9 shows a sensitivity analysis for the treatment effect in 2009 using $\Delta=\Delta^{S D}(M)$. The confidence sets contain only positive values unless $M$ exceeds 0.22 , allowing us to reject a null effect on profits in 2009 if we are willing to restrict the slope of the differential trend to change by no more than $22 \log$ points between periods. To provide additional context for the magnitudes of $M$, we consider benchmarks using changes in slope

Figure 9: Event-study coefficients $\left\{\beta_{s}\right\}$ for $\log$ profits, estimated using the event-study specification in (26).

in the pre-period, as discussed in Section 7.3. A $95 \%$ interval for the largest change in slope using the pre-period data is [0.09, 0.21]. Thus, we can reject a null effect in 2009 unless we are willing to allow for changes in slope of the underlying trend that are larger than the upper bound of the $95 \%$ CI for the largest change in slope in the pre-period.

Figure 10: Sensitivity analysis for $\theta=\tau_{2009}$ using $\Delta=\Delta^{S D}(M)$ and $\Delta=\Delta^{S D N B}(M)$.


Using context-specific knowledge, BC argue that their estimates likely understate the effect of the VAT cut on profits. Since the VAT cut occurred at the same time that a payroll subsidy for restaurants was terminated, BC write, "a conservative interpretation of our results is that we are estimating a lower bound on the effect of the VAT cut on profits" (pg. 40). This argument may be made precise by imposing that the bias of the post-period event-study
coefficients is negative. The right panel of Figure 10 imposes the additional constraint that the sign of the bias be negative - that is, we set $\Delta=\Delta^{S D N B}:=\Delta^{S D}(M) \cap\left\{\delta: \delta_{\text {post }} \leqslant 0\right\}$. With this added constraint, the robust confidence sets now rule out effects on profits smaller than $15 \log$ points for all values of $M$.

## 9 Conclusion

This paper considers the problem of conducting inference in difference-in-differences and related designs that is robust to violations of the parallel trends assumption. We introduce a variety of possible restrictions on the class of possible differences in trends that formalize common intuitive arguments made in applied work. We then introduce inference procedures that are uniformly valid so long as the difference in trends satisfies these restrictions, and derive novel results on the power of these procedures. We recommend that applied researchers use our proposed confidence sets to conduct formal sensitivity analyses, in which they report confidence sets for the causal effect of interest under a variety of possible restrictions on the underlying trends. Such sensitivity analyses make transparent what assumptions are needed in order to obtain informative inference and help researchers assess whether those assumptions are plausible in a given setting.

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# An Honest Approach to Parallel Trends 

Online Appendix<br>Ashesh Rambachan Jonathan Roth

November 12, 2020

This online appendix contains proofs and additional results for the paper "An Honest Approach to Parallel Trends" by Ashesh Rambachan and Jonathan Roth. Section A collects together additional results that are referenced in the main text. Section B contains proofs and auxiliary lemmas for the results in the main text. The supplementary materials provide statements and proofs of uniform asymptotic results along with additional simulation results.

## A Additional Results

## A. 1 Optimal local asymptotic power of FLCIs

As discussed in Remark 6, the FLCIs have local asymptotic power converging to the power envelope provided that Assumption 4 and Assumption 5 are satisfied. We now formally state this result. The proof is given in Section B.

Proposition A.1. Fix $\delta_{A} \in \Delta, \tau_{A} \in \mathbb{R}^{\bar{T}}$ and suppose $\Sigma^{*}$ is positive definite. Let $\theta_{A}^{u b}=$ $\sup _{\theta} \mathcal{S}\left(\Delta, \delta_{A}+\tau_{A}\right)$ be the upper bound of the identified set. Suppose that Assumption 5 holds and $\delta_{A, p r e}$ satisfies Assumption 4. Then, for any $x>0$ and $\alpha \in(0,0.5]$,
$\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\alpha, n}^{F L C I}\right)=\lim _{n \rightarrow \infty} \sup _{\mathcal{C}_{\alpha, n} \in \mathcal{I}_{\alpha}\left(\Delta, \Sigma_{n}\right)} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\alpha, n}\right)$.
The analogous result holds replacing $\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x$ with $\theta_{A}^{l b}-\frac{1}{\sqrt{n}} x$, for $\theta_{A}^{l b}$ the lower bound of the identified set.

Thus, $\mathcal{C}_{\alpha, n}^{F L C I}$ behaves similarly to $\mathcal{C}_{\alpha, n}^{C}$ as $n \rightarrow \infty$ when Assumption 4 and Assumption 5 hold.

## A. 2 Connection to linear independence constraint qualification (LICQ)

In this section, we draw connections between linear independence constraint qualification (LICQ) and Assumption 5, under which the power of the conditional test converges to the
power envelope asymptotically. We show that LICQ implies Assumption 5. We follow the notation of Kaido et al. (2020).

Suppose $\Delta=\{\delta: A \delta \leqslant d\}$. Let $m\left(\tau_{\text {post }} ; \beta\right)=A\left(\beta-M_{\text {post }} \tau_{\text {post }}\right)-d$, and let $\mathrm{T}(\Delta, \beta):=$ $\left\{\tau_{\text {post }}: m\left(\tau_{\text {post }} ; \beta\right) \leqslant 0\right\}$ be the identified set for the full parameter vector $\tau_{\text {post }}$. Define the set of support points in direction $p$ to be $S(p, \mathrm{~T}):=\left\{\tau_{\text {post }}: p^{\prime} \tau_{\text {post }}=\sup _{\tau_{\text {post }} \in \mathrm{T}} p^{\prime} \tau_{\text {post }}\right\}$.

Definition 1. The linear constraint constraint qualification (LICQ) is satisfied in the direction $p$ if, for all support points in the direction $p$, the gradients of the binding constraints are linearly independent. That is, for all $\tau_{\text {post }} \in S(p, \mathrm{~T})$, the set $\left\{D_{\tau_{\text {post }}} m_{j}\left(\tau_{\text {post }}, \beta\right)\right.$ : $\left.m_{j}\left(\tau_{\text {post }}, \beta\right)=0\right\}$ is linearly independent, where $D_{\tau_{p o s t}}$ denotes the gradient with respect to $\tau_{\text {post }}$.

LICQ in the directions $l$ and $-l$ is equivalent to restrictions on the binding moments in the problems $b^{\min }$ and $b^{\max }$.

Lemma A.1. Suppose $\beta_{A}=\delta_{A}+M_{\text {post }} \tau_{A, p o s t}$ for some $\delta_{A} \in \Delta=\{\delta: A \delta \leqslant d\}$ and $\tau_{A, \text { post }} \in \mathbb{R}^{\bar{T}}$. Then the following are equivalent: (i) LICQ is satisfied in the direction $l$; (ii) For any solution $\delta^{* *}$ to the linear program

$$
b^{\min }\left(\delta_{A, p r e}\right)=\min _{\delta} l^{\prime} \delta_{\text {post }} \text { s.t. } A \delta \leqslant d, \delta_{p r e}=\delta_{A, p r e}
$$

the matrix $A_{\left(B\left(\delta^{* *)}, p o s t\right)\right.}$ with rows corresponding with the binding inequality constraints at $\delta^{* *}$ has rank $\left|B\left(\delta^{* *}\right)\right|$. Analogous results hold replacing $l$ with $-l$ in (i) and min with max in (ii).

Proof. We first show (i) implies (ii). Let $\delta^{* *}$ be a solution to the minimization problem for $b^{\text {min }}$. Let $\tau_{\text {post }}^{* *}=\beta_{A, \text { post }}-\delta_{\text {post }}^{* *}$. Observe that $l^{\prime} \tau_{\text {post }}^{* *}=l^{\prime} \beta_{A, \text { post }}-b^{\text {min }}\left(\delta_{A, \text { post }}\right)$. From (6), we then see that $l^{\prime} \tau_{\text {post }}^{* *}=\theta^{u b}$ and hence $\tau_{\text {post }}^{* *} \in S(l, \mathrm{~T})$. Now, note that by construction, $m\left(\beta_{A}, \tau_{\text {post }}^{* *}\right)=A\left(\beta_{A}-M_{\text {post }} \tau_{\text {post }}^{* *}-d\right)=A \delta^{* *}-d$, so the binding constraints in $m\left(\beta_{A}, \tau_{\text {post }}^{* *}\right)$ correspond with the binding constraints in the minimization for $b^{m i n}$. Finally, observe that $D_{\tau_{\text {post }}} m\left(\beta_{A}, \tau_{\text {post }}^{* *}\right)=A_{(\cdot, p o s t)}$. It then follows from (i) that the rows of $A_{(B(\delta * *), p o s t)}$ are linearly independent, which gives the desired result.

Conversely, suppose $\tau_{\text {post }}^{* *} \in S(l, \tau)$. By definition, there exists some $\delta^{* *} \in \Delta$ such that $\delta^{* *}=\beta_{A}-M_{\text {post }} \tau_{\text {post }}^{* *}$, and $l^{\prime} \tau_{\text {post }}^{* *}=\theta^{u b}$. Thus, $\theta^{u b}=l^{\prime} \beta_{A, \text { post }}-l^{\prime} \delta^{* *}$. It then follows from (6) that $l^{\prime} \delta^{* *}=b^{\min }\left(\delta_{A, p r e}\right)$, so $\delta^{* *}$ is a solution to the optimization $b^{m i n}$. (ii) then implies that $A_{\left(B\left(\delta^{* *}, p o s t\right)\right.}$ has linearly independent rows. By the same argument as earlier in the proof, $A_{\left(B\left(\delta^{* *}, p o s t\right)\right.}$ corresponds with the matrix of gradients for the binding constraints in $m\left(\beta_{A}, \tau_{\text {post }}^{* *}\right)$, from which we see that LICQ is satisfied.

Therefore, if LICQ holds in the directions $l$ and $-l$, then Assumption 5 is satisfied. Indeed, if LICQ holds, then Lemma 5 implies that the rank condition in Assumption 5 holds for any solutions $\delta^{*}$ and $\delta^{* *}$ to the problems $b^{\text {max }}$ and $b^{\text {min }}$. By contrast, Assumption 5 only requires the rank condition to hold for at least one solution to $b^{\max }$ and $b^{\min }$.

It is possible for a linear program to have multiple solutions, and for the rows of the binding constraints to be linearly independent (non-degenerate) for some solutions but not for others (e.g., see Example 1 on p. 146 of Sierksma (2001)). Assumption 5 is thus potentially weaker than LICQ if there are multiple solutions to the problem for $b^{\max }$ or $b^{\min }$.

## A. 3 Details on the conditional-FLCI hybrid Confidence Sets

We provide further technical details on the construction of conditional-FLCI hybrid confidence sets discussed in Section 5. To construct the conditional-FLCI hybrid confidence sets, we first provide a lemma that implies that the affine estimator at which the optimal FLCI is centered can be written as an affine function of $A \hat{\beta}$, where recall that $A$ is the matrix defining the polyhedral set, $\Delta=\{\delta: A \delta \leqslant d\}$.

Lemma A.2. Suppose $\Delta=\{\delta: A \delta \leqslant d\} \neq \varnothing$, and $(a, v)$ are such that $\bar{b}(a, v)<\infty$. Then, there exists $\tilde{v}$ such that $v^{\prime}=\tilde{v}^{\prime} A$.

Proof. Note that

$$
\bar{b}(a, v)=\max _{\delta, \tau_{\text {post }}}\left|v^{\prime}\left(\delta+M_{\text {post }} \tau_{\text {post }}\right)-l^{\prime} \tau_{\text {post }}\right| \text { s.t. } A \delta-d \leqslant 0 .
$$

We will show that if $\bar{b}(a, v)$ is finite, then for all $\tilde{\delta} \in \Delta, A \tilde{\delta}=0$ implies $v^{\prime} \tilde{\delta}=0$. This implies that $v$ is in the rowspace of $A$, from which the result follows. To prove this, suppose towards contradiction that $\tilde{\delta}$ is such that $A \tilde{\delta}=0$ and $v^{\prime} \tilde{\delta} \neq 0$. Since $A \tilde{\delta}=0$, it follows that $\delta_{c}:=\left(\delta_{0}+c \cdot \tilde{\delta}\right)$ is in $\Delta$ for any $\delta_{0} \in \Delta$ and $c \in \mathbb{R}$. However, it then follows that for any fixed $\tau_{\text {post }}$ and $\delta_{0}$, the objective in the previous display can be made arbitrarily large at ( $\delta_{c}, \tau_{\text {post }}$ ) by taking $c \rightarrow \infty$.

Consider the level $1-\kappa$ optimal FLCI, $\mathcal{C}_{\kappa, n}^{F L C I}=a_{n}+v_{n}^{\prime} \hat{\beta}_{n} \pm \chi_{n}$. By Lemma A.2, there exists some vector $\tilde{v}_{n}$ such that the level $1-\kappa$ optimal FLCI can be written as $a_{n}+\tilde{v}_{n}^{\prime} A \hat{\beta}_{n} \pm \chi_{n}$. Since $\tilde{Y}_{n}(\theta)=A \hat{\beta}_{n}-\tilde{A}_{(\cdot, 1)} \theta-d$, it follows that $\bar{\theta} \in \mathcal{C}_{\kappa, n}^{F L C I}$ if and only if

$$
\begin{aligned}
\tilde{v}_{n}^{\prime} \tilde{Y}_{n}(\bar{\theta}) & \left.\leqslant \chi_{n}-a_{n}-\tilde{v}_{n}^{\prime} d+\left(1-\tilde{v}_{n}^{\prime} \tilde{A}_{(\cdot, 1)}\right) \bar{\theta}\right), \\
-\tilde{v}_{n}^{\prime} \tilde{Y}_{n}(\bar{\theta}) & \left.\leqslant \chi_{n}+a_{n}+\tilde{v}_{n}^{\prime} d-\left(1-\tilde{v}_{n}^{\prime} \tilde{A}_{(\cdot, 1)}\right) \bar{\theta}\right) .
\end{aligned}
$$

One can further show that $\left.\left(1-\tilde{v}_{n}^{\prime} \tilde{A}_{(\cdot, 1)}\right) \bar{\theta}\right)=0$, which simplifies the upper bounds above. ${ }^{42}$ Defining the matrix $\tilde{V}_{n}=\left(\tilde{v}_{n}^{\prime},-\tilde{v}_{n}^{\prime}\right)^{\prime}$ and the vector $d_{n}(\bar{\theta})$ which stacks the upper-bounds of the inequalities in the previous display, we see that the optimal level $1-\kappa$ FLCI contains the parameter value $\bar{\theta}$ if and only if $\bar{V}_{n} \tilde{Y}_{n}(\bar{\theta}) \leqslant \bar{d}_{n}(\bar{\theta})$.

With this equivalent representation of the optimal FLCI, we now characterize the distribution of the test statistic $\hat{\eta}$ (17) conditional on the parameter $\theta$ falling within the optimal FLCI.

Lemma A.3. $\hat{\eta}\left|\left\{\gamma_{*} \in \hat{V}_{n}, S_{n}=s, \bar{\theta} \in \mathcal{C}_{\kappa, n}^{F L C I}\right\} \sim \xi\right| \xi \in\left[v_{C-F L C I}^{l o}, v_{C-F L C I}^{u p}\right]$, where $\xi \sim \mathcal{N}\left(\gamma_{*}^{\prime} \tilde{\mu}, \gamma_{*}^{\prime} \tilde{\Sigma}_{n} \gamma_{*}\right)$, $v_{C-F L C I}^{l o}:=\max \left\{v^{l o}, v_{F L C I}^{l o}\right\}, v_{C-F L C I}^{u p}:=\min \left\{v^{u p}, v_{F L C I}^{u p}\right\} ; v^{l o}$ and $v^{u p}$ are as defined in Sec-
 $c_{n, \gamma_{*}}=\frac{\tilde{\Sigma}_{n} \gamma_{*}}{\gamma_{*}^{\prime} \Sigma_{n} \gamma_{*}}$ and $S_{n}=\left(I-\frac{\Sigma_{n} \gamma_{*}}{\gamma_{*}^{\prime} \Sigma_{n} \gamma_{*}} \gamma_{*}^{\prime}\right) \tilde{Y}_{n}(\bar{\theta})$, and $\gamma_{*}$ is the vector of Lagrange multipliers for the primal problem (18).

Proof. The proof follows an analogous argument to Lemma 9 in ARP. Recall that conditional on $\gamma_{*} \in \hat{V}_{n}, \hat{\eta}=\gamma_{*}^{\prime} \tilde{Y}_{n}$. Recall also that $\theta \in \mathcal{C}_{\kappa, n}^{F L C I}$ if and only if $\tilde{V}_{n} \tilde{Y}_{n} \leqslant \bar{d}_{n}$. Observe that the set of values of $\tilde{Y}_{n}$ such that

$$
\gamma_{*}^{\prime} \tilde{Y}_{n}=\left(\max \gamma^{\prime} \tilde{Y}_{n} \text { s.t. } \gamma \geqslant 0, \gamma^{\prime} \tilde{A}_{(\cdot,-1)}=0, \gamma^{\prime} \tilde{\sigma}_{n}=1\right) \text { and } \tilde{V}_{n} \tilde{Y}_{n} \leqslant \bar{d}_{n}
$$

is convex. This follows from the fact that if the expression above holds for both $\tilde{Y}_{n}$ and $\tilde{Y}_{n}^{*}$, then $\gamma_{*}^{\prime} \tilde{Y}_{n} \geqslant \gamma^{\prime} \tilde{Y}_{n}$ and $\gamma_{*}^{\prime} \tilde{Y}_{n}^{*} \geqslant \gamma^{\prime} \tilde{Y}_{n}^{*}$ for all $\gamma$ feasible in the maximization. It then follows that $\gamma_{*}^{\prime}\left(\alpha \tilde{Y}_{n}^{*}+(1-\alpha) \tilde{Y}_{n}\right) \geqslant \gamma^{\prime}\left(\alpha \tilde{Y}_{n}^{*}+(1-\alpha) \tilde{Y}_{n}\right)$ for any $\alpha \in(0,1)$. Thus, $\left(\alpha \tilde{Y}_{n}^{*}+(1-\alpha) \tilde{Y}_{n}\right)$ is also equal to the maximum. It is likewise clear that the second constraint holds for a convex combination of $\tilde{Y}_{n}$ and $\tilde{Y}_{n}^{*}$.

Thus, once we condition on $S_{n}$, the set of values of $\gamma_{*}^{\prime} \tilde{Y}_{n}$ such that $\gamma_{*} \in \hat{V}_{n}$ and $\tilde{V}_{n} \tilde{Y}_{n} \leqslant \bar{d}_{n}$ is an interval. It thus suffices to find the endpoints. Without loss of generality, we focus on the lower bound. For ease of notation, let $F:=\left\{\gamma \geqslant 0, \gamma^{\prime} \tilde{A}_{(\cdot,-1)}=0, \gamma^{\prime} \tilde{\sigma}_{n}=1\right\}$ denote the feasible region for the maximization. Then we are interested in

$$
\min _{\left\{\tilde{Y}_{n}: S_{n}=s\right\}}\left\{\gamma_{*}^{\prime} \tilde{Y}_{n}: \gamma_{*}^{\prime} \tilde{Y}_{n}=\max _{\gamma \in F} \gamma^{\prime} \tilde{Y}_{n}, \tilde{V}_{n} \tilde{Y}_{n} \leqslant \bar{d}_{n}\right\} .
$$

Recalling that $S_{n}=\left(I-c_{n, \gamma_{*}} \gamma_{*}^{\prime}\right) \tilde{Y}_{n}$ for $c_{n, \gamma_{*}}=\frac{\tilde{\Sigma}_{n} \gamma_{*}}{\gamma_{*}^{\prime} \tilde{\Sigma}_{n} \gamma_{*}}$, the expression becomes

[^27]$$
\min _{\left\{\tilde{Y}_{n}: S_{n}=s\right\}}\left\{\gamma_{*}^{\prime} \tilde{Y}_{n}: \gamma_{*}^{\prime} \tilde{Y}_{n}=\max _{\gamma \in F} \gamma^{\prime}\left(s+c_{n, \gamma_{*}} \gamma_{*}^{\prime} \tilde{Y}_{n}\right), \tilde{V}_{n} \tilde{Y}_{n} \leqslant \bar{d}_{n}\right\}
$$
which is equivalent to
$$
\min \left\{\left\{x: x=\max _{\gamma \in F} \gamma^{\prime}\left(s+c_{n, \gamma_{*}} x\right)\right\} \cap\left\{\gamma_{*}^{\prime} \tilde{Y}_{n}: \tilde{Y}_{n} \text { s.t. } S_{n}=s, \tilde{V}_{n} \tilde{Y}_{n} \leqslant \bar{d}_{n}\right\}\right\}
$$

However, the first set in the minimization above is the interval $\left[v^{l o}, v^{u p}\right]$, and the polyhedral lemma in Lee et al. (2016) (Lemma 5.1) implies that second set is the interval $\left[v_{F L C I}^{l o}, v_{F L C I}^{u p}\right]$. Thus, the expression above is $\max \left\{v^{l o}, v_{F L C I}^{l o}\right\}$, as desired. The argument for the lower bound of the interval is analogous. Finally, the independence of $\gamma_{*}^{\prime} \tilde{Y}_{n}$ and $S_{n}$ implies that the distribution of $\gamma_{*}^{\prime} \tilde{Y}_{n}$ conditional on $\left\{\gamma_{*} \in \hat{V}_{n}, S_{n}=s, \bar{\theta} \in \mathcal{C}_{n, \kappa}^{F L C I}\right\}$ is truncated normal.

We now show that the conditional-FLCI hybrid confidence sets have asymptotic properties similar to those of the conditional test. The proofs of these results are provided in Section B.

Proposition A. 2 (Consistency). The conditional-FLCI hybrid test is consistent. For any $\delta_{A} \in \Delta, \tau_{A} \in \mathbb{R}^{\bar{T}}, \theta_{\text {out }} \notin \mathcal{S}\left(\Delta, \delta_{A}+\tau_{A}\right), \alpha \in(0, .5]$, and $\kappa \in(0, \alpha)$,

$$
\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\theta_{\text {out }} \notin \mathcal{C}_{\kappa, \alpha, n}^{C-F L C I}\right)=1 .
$$

Proposition A. 3 (Local asymptotic power). Fix $\delta_{A} \in \Delta, \tau_{A}$, and $\Sigma^{*}$ positive definite. Suppose Assumption 5 holds. Suppose $\alpha \in(0, .5], \kappa \in(0, \alpha)$, and let $\tilde{\alpha}=\frac{\alpha-\kappa}{1-\kappa}$. Then,
$\liminf _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\kappa, \alpha, n}^{C-F L C I}\right) \geqslant \lim _{n \rightarrow \infty} \sup _{\mathcal{C}_{\alpha, n} \in \mathcal{I}_{\bar{\alpha}}\left(\Delta, \Sigma_{n}\right)} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\alpha, n}\right)$.
The analogous result holds replacing $\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x$ with $\theta_{A}^{l b}-\frac{1}{\sqrt{n}} x$, for $\theta_{A}^{l b}$ the lower bound of the identified set (although the constant $c^{*}$ may differ).

## B Proofs of Main Finite Sample Normal Results

## B. 1 Proofs of Main Finite Sample Normal Results

Throughout the proofs, we will use the following notation. Let $\tilde{Y}\left(\hat{\beta}_{n}, A, d, \bar{\theta}\right):=A \hat{\beta}_{n}-d-$ $\tilde{A}_{(\cdot, 1)} \bar{\theta}$. Define $\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, d, \bar{\theta}, \Sigma\right):=\psi_{\alpha}^{C}\left(\tilde{Y}\left(\hat{\beta}_{n} ; A, d, \bar{\theta}\right), A \Sigma A^{\prime}\right)$ to be an indicator for whether the conditional test constructed using ( $\hat{\beta}_{n}, A, d, \bar{\theta}, \Sigma$ ) rejects.

## Proof of Proposition 3.2

Proof. First, suppose Assumption 4 holds. Without loss of generality, we show $\mathbb{P}\left(\left(\theta^{u b}+x\right) \in \mathcal{C}_{\alpha, n}^{F L C I}\right) \rightarrow$ 0 for any $x>0$. By Lemma B. 20 there exists $(\bar{a}, \bar{v})$ such that $\bar{b}(\bar{a}, \bar{v})=\frac{1}{2} \operatorname{LID}\left(\Delta, \delta_{\text {pre }}\right)=: \bar{b}_{\text {min }}$ and $\mathbb{E}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left[\bar{a}+\bar{v}^{\prime} \hat{\beta}_{n}\right]=\frac{1}{2}\left(\theta^{u b}+\theta^{l b}\right)=: \theta^{\text {mid }}$. Let $\overline{\mathcal{C}}_{n}:=\bar{a}+\bar{v}^{\prime} \hat{\beta}_{n} \pm \chi_{n}(\bar{a}, \bar{v})$ denote the fixed length confidence interval based on ( $\bar{a}, \bar{v}$ ).

By construction, $\bar{\chi}_{n}:=\chi_{n}(\bar{a}, \bar{v})$ is the $1-\alpha$ quantile of the $\left|\mathcal{N}\left(\bar{b}_{\text {min }}, \sigma_{\bar{v}, n}^{2}\right)\right|$ distribution. Since $\sigma_{\bar{v}, n}^{2}=\frac{1}{n} \sigma_{\bar{v}, 1}^{2} \rightarrow 0$, the $\left|\mathcal{N}\left(\bar{b}_{m i n}, \sigma_{\bar{v}, n}^{2}\right)\right|$ distribution collapses to a point mass at $\bar{b}_{\text {min }}$, and thus $\bar{\chi}_{n} \rightarrow \bar{b}_{\text {min }}$. By construction the length of the shortest FLCI $\chi_{n}:=\chi_{n}\left(a_{n}, v_{n}\right)$ must be less than or equal to $\bar{\chi}_{n}$, and so $\lim \sup _{n \rightarrow \infty} \chi_{n} \leqslant \bar{b}_{\text {min }}$. Let $b_{n}:=\bar{b}\left(a_{n}, v_{n}\right)$ be the worst-case bias of the optimal FLCI. Since $\alpha \in(0, .5]$, Lemma B. 21 implies that $\chi_{n} \geqslant b_{n}$. Additionally, Lemma B. 19 implies that $b_{n} \geqslant \frac{1}{2} \operatorname{LID}\left(\Delta, \delta_{\text {pre }}\right)=\bar{b}_{\text {min }}$, and thus $\chi_{n} \geqslant \bar{b}_{\text {min }}$. Hence, $\chi_{n} \rightarrow \bar{b}_{\text {min }}$ implies $b_{n} \rightarrow \bar{b}_{\text {min }}$. Additionally, note that for $\alpha \in(0,0.5], \chi_{n}(a, v)$ is increasing in both $\bar{b}(a, v)$ and $\sigma_{v, n}$. Since $\bar{b}_{\text {min }} \leqslant b_{n}$ and $\chi_{n} \leqslant \bar{\chi}_{n}$, it must be that $\sigma_{v_{n}, n} \leqslant \sigma_{\bar{v}, n}$, from which it follows that $\sigma_{v_{n}, n} \rightarrow 0$.

Now, we claim that $\mu_{n}:=\mathbb{E}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left[a_{n}+v_{n}^{\prime} \hat{\beta}_{n}\right]$ converges to $\theta^{\text {mid }}:=\frac{1}{2}\left(\theta^{u b}+\theta^{l b}\right)$. To show this, note that $\mu_{n}=a_{n}+v_{n}^{\prime} \beta_{A}$ for $\beta_{A}=\delta_{A}+\tau_{A}$. Since $\theta^{u b}, \theta^{l b} \in \mathcal{S}\left(\Delta, \beta_{A}\right)$, by the definition of the identified set there exist $\delta^{u b}, \delta^{l b} \in \Delta$ and $\tau^{u b}, \tau^{l b}$ such that $\beta_{A}=\delta^{u b}+\tau^{u b}=$ $\delta^{l b}+\tau^{l b}, \theta^{u b}=l^{\prime} \tau_{\text {post }}^{u b}$, and $\theta^{l b}=l^{\prime} \tau_{\text {post }}^{l b}$. Thus, $\theta^{u b}-\mathbb{E}_{\left(\delta^{u b}, \tau^{u b}, \Sigma_{n}\right)}\left[a_{n}+v_{n}^{\prime} \hat{\beta}_{n}\right]=\theta^{u b}-\mu_{n}$ and $\mathbb{E}_{\left(\delta^{l b}, \tau^{l b}, \Sigma_{n}\right)}\left[a_{n}+v_{n}^{\prime} \hat{\beta}_{n}\right]-\theta^{l b}=\mu_{n}-\theta^{l b}$. This implies that $b_{n} \geqslant \max \left\{\theta^{u b}-\mu_{n}, \mu_{n}-\theta^{l b}\right\}=$ $\bar{b}_{\text {min }}+\left|\mu_{n}-\theta^{\text {mid }}\right|$, where the equality uses the fact that $\theta^{u b}-\theta^{l b}=\operatorname{LID}\left(\Delta, \delta_{A, p r e}\right)=2 \bar{b}_{\text {min }}$. Since we've shown that $b_{n} \rightarrow \bar{b}_{\text {min }}$, it follows that $\mu_{n} \rightarrow \theta^{\text {mid }}$, as desired.

Next, note that if $\hat{\beta}_{n} \sim \mathcal{N}\left(\delta_{A}+\tau_{A}, \Sigma_{n}\right)$, then $a_{n}+v_{n}^{\prime} \hat{\beta}_{n} \sim \mathcal{N}\left(\mu_{n}, \sigma_{v_{n}, n}^{2}\right)$. Observe that $\bar{\theta} \in \mathcal{C}_{\alpha, n}^{F L C I}$ if and only if $a_{n}+v_{n}^{\prime} \hat{\beta}_{n} \in\left[\bar{\theta}-\chi_{n}, \bar{\theta}+\chi_{n}\right]$. Thus,

$$
\mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\bar{\theta} \in \mathcal{C}_{\alpha, n}^{F L C I}\right)=\Phi\left(\frac{\bar{\theta}+\chi_{n}-\mu_{n}}{\sigma_{v_{n}, n}}\right)-\Phi\left(\frac{\bar{\theta}-\chi_{n}-\mu_{n}}{\sigma_{v_{n}, n}}\right) .
$$

Now, recalling that $\theta^{u b}=\theta^{\text {mid }}+\bar{b}_{\text {min }}$ by construction, we have $\mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta^{u b}+x\right) \in \mathcal{C}_{\alpha, n}^{F L C I}\right)$ equals

$$
\begin{equation*}
\Phi\left(\frac{\theta^{m i d}+\bar{b}_{m i n}+x+\chi_{n}-\mu_{n}}{\sigma_{v_{n}, n}}\right)-\Phi\left(\frac{\theta^{m i d}+\bar{b}_{m i n}+x-\chi_{n}-\mu_{n}}{\sigma_{v_{n}, n}}\right) \tag{27}
\end{equation*}
$$

Note that the term inside the second normal CDF in the previous display equals

$$
-\frac{\chi_{n}-b_{n}}{\sigma_{v_{n}, n}}+\frac{x+\theta^{m i d}-\mu_{n}+\bar{b}_{\min }-b_{n}}{\sigma_{v_{n}, n}} .
$$

However, the first summand above is bounded between $-z_{1-\alpha / 2}$ and $-z_{1-\alpha}$ by Lemma B.21. Additionally, we've shown that $\theta^{\text {mid }}-\mu_{n} \rightarrow 0$ and $\bar{b}_{\text {min }}-b_{n} \rightarrow 0$, so the numerator of the
second summand converges to $x>0$. Since the denominator $\sigma_{v_{n}, n} \rightarrow 0$, the expression in the previous display diverges to $\infty$, and hence the second normal CDF term in (27) converges to 1, which implies that $\mathbb{P}\left(\left(\theta^{u b}+x\right) \in \mathcal{C}_{\alpha, n}^{F L C I}\right) \rightarrow 0$, as needed.

Conversely, suppose Assumption 4 fails. Let $L_{A}:=\operatorname{LID}\left(\Delta, \delta_{A, p r e}\right)$ and $\bar{L}:=\sup _{\tilde{\delta}_{p r e} \in \Delta_{\text {pre }}} L I D\left(\Delta, \tilde{\delta}_{\text {pre }}\right)$. By Lemma B.19, $b_{n}:=\bar{b}\left(a_{n}, v_{n}\right) \geqslant \frac{1}{2} \bar{L}=: \bar{b}_{\text {min }}$. As argued earlier in the proof, since $\alpha \in(0, .5], \chi_{n} \geqslant b_{n}=\frac{1}{2} \bar{L}$. If $\bar{L}=\infty$, then $\mathcal{C}_{\alpha, n}^{F L C I}$ is the real line, and thus never rejects, so $\mathcal{C}_{\alpha, n}^{F L C I}$ is trivially inconsistent under the assumption that $\mathcal{S}_{\theta}\left(\Delta, \delta_{A}+\tau_{A}\right) \neq \mathbb{R}$. For the remainder of the proof, we assume $L_{A}<\bar{L}<\infty$. From Lemma 2.1, $\mathcal{S}\left(\delta_{A}+\tau_{A}, \Delta\right)=\left[\theta^{l b}, \theta^{u b}\right]$, where $\theta^{u b}-\theta^{l b}=\operatorname{LID}\left(\Delta, \delta_{A, p r e}\right)=L_{A}$. Let $\epsilon=\frac{1}{4}\left(\bar{L}-L_{A}\right)$, and set $\theta_{1}^{\text {out }}:=\theta^{u b}+\epsilon$ and $\theta_{2}^{\text {out }}:=\theta^{l b}-\epsilon$. Let $\theta^{\text {mid }}=\frac{1}{2}\left(\theta^{u b}+\theta^{l b}\right)$ be the midpoint of the identified set. By construction, $\theta_{1}^{\text {out }}-\theta^{\text {mid }}=\theta^{\text {mid }}-\theta_{2}^{\text {out }}=\frac{1}{2} L_{A}+\epsilon<\frac{1}{2} \bar{L}$. Since $\mathcal{C}_{\alpha, n}^{F L C I}$ is an interval with half-length at least $\frac{1}{2} \bar{L}$, it follows that if $\theta^{\text {mid }} \in \mathcal{C}_{\alpha, n}^{F L C I}$ then at least one of $\theta_{1}^{\text {out }}, \theta_{2}^{\text {out }}$ is also in $\mathcal{C}_{\alpha, n}^{F L C I}$. Hence, $\mathbb{P}\left(\theta_{1}^{\text {out }} \in \mathcal{C}_{\alpha, n}^{F L C I}\right)+\mathbb{P}\left(\theta_{2}^{\text {out }} \in \mathcal{C}_{\alpha, n}^{F L C I}\right) \geqslant \mathbb{P}\left(\theta^{\text {mid }} \in \mathcal{C}_{\alpha, n}^{F L C I}\right) \geqslant 1-\alpha$, where the final bound follows since $\mathcal{C}_{\alpha, n}^{F L C I}$ has correct coverage. It follows that $\lim \sup _{n \rightarrow \infty} \mathbb{P}\left(\theta_{j}^{\text {out }} \in \mathcal{C}_{\alpha, n}^{F L C I}\right) \geqslant \frac{1}{2}(1-\alpha)>0$ for at least one $j \in\{1,2\}$.

## Proof of Proposition 4.1

Proof. Lemma 2.1 showed that the identified set is an interval, $\mathcal{S}\left(\delta_{A}+\tau_{A}, \Delta\right)=\left[\theta^{l b}, \theta^{u b}\right]$, and so if $\theta^{\text {out }} \notin \mathcal{S}\left(\delta_{A}+\tau_{A}, \Delta\right)$, then we must have either $\theta^{\text {out }}=\theta^{u b}+x$ or $\theta^{\text {out }}=\theta^{l b}-x$ for some $x>0$. Without loss of generality, consider the case $\theta^{o u t}=\theta^{u b}+x$, so

$$
\liminf _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\theta^{\text {out }} \notin \mathcal{C}_{\alpha, n}^{C}\right)=\liminf _{n \rightarrow \infty} \mathbb{E}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left[\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, d, \theta^{u b}+x, \Sigma_{n}\right)\right]
$$

Lemma B. 2 along with $\Sigma_{n}=\frac{1}{n} \Sigma^{*}$ imply $\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, d, \theta^{u b}+x, \Sigma_{n}\right)=\psi_{\alpha}^{C}\left(\sqrt{n} \hat{\beta}_{n} ; A, \sqrt{n} d, \sqrt{n} \theta^{u b}+\right.$ $\left.\sqrt{n} x, \Sigma^{*}\right)$. Thus,

$$
\liminf _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\theta^{\text {out }} \notin \mathcal{C}_{\alpha, n}^{C}\right)=\liminf _{n \rightarrow \infty} \mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \sqrt{n} \theta^{u b}+\sqrt{n} x, \Sigma^{*}\right)\right]
$$

where we further used that $\hat{\beta}_{n} \sim \mathcal{N}\left(\beta_{A}, \Sigma_{n}\right)$ implies $\sqrt{n} \hat{\beta}_{n} \sim \mathcal{N}\left(\sqrt{n} \beta_{A}, \Sigma^{*}\right)$. Lemma B. 1 implies that $\sqrt{n} \theta^{u b}=\theta_{n}^{u b}$, for $\theta_{n}^{u b}=\sup \mathcal{S}\left(\sqrt{n} \delta_{A}+\sqrt{n} \tau_{A}, \Delta_{n}\right)$ and $\Delta_{n}=\{\delta: A \delta \leqslant \sqrt{n} d\}$. It follows from Lemma B. 18 that

$$
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \sqrt{n} \theta^{u b}+\sqrt{n} x, \Sigma^{*}\right)\right] \geqslant \rho_{L B}\left(x, \Sigma^{*}\right),
$$

for $\rho_{L B}$ a function with $\lim _{x \rightarrow \infty} \rho_{L B}\left(x, \Sigma^{*}\right)=1$. It is immediate from the previous two displays that $\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\theta_{\text {out }} \notin \mathcal{C}_{\alpha, n}^{C}\right)=1$ as desired.

## Proof of Proposition 4.2

Proof. We show that each of the limits in the proposition equals $\Phi\left(c^{*} x-z_{1-\alpha}\right)$. Following the same steps as proof of Proposition 4.1, the first limit of interest can be written as

$$
\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\alpha, n}^{C}\right)=\lim _{n \rightarrow \infty} \mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)\right]
$$

The term on the right-hand side converges to $\Phi\left(c^{*} x-z_{1-\alpha}\right)$ by Lemma B.8.
We next turn to the second limit. Consider testing $H_{0}: \delta \in \Delta=\{\delta: A \delta \leqslant d\}, \theta=\bar{\theta}$ against $H_{1}:(\delta, \tau)=\left(\delta_{A}, \tau_{A}\right)$. Observe that the null is equivalent to $H_{0}: \beta \in \mathcal{B}_{0}(\bar{\theta}):=$ $\left\{\beta: \exists \tau_{\text {post }}\right.$ s.t. $\left.l^{\prime} \tau_{\text {post }}=\bar{\theta}, A \beta-d-A M_{\text {post }} \tau_{\text {post }} \leqslant 0\right\}$ and the alternative is equivalent to $H_{1}: \beta=\delta_{A}+\tau_{A}=: \beta_{A}$. It is clear from the definition of $\mathcal{B}_{0}$ that it is convex. From Lemma B.5, the most powerful test that controls size is a one-sided t-test (Neyman-Pearson test) that rejects for large values of $\left(\beta_{A}-\tilde{\beta}_{n}\right)^{\prime} \Sigma_{n}^{-1} \hat{\beta}_{n}$, where $\tilde{\beta}:=\arg \min _{\beta \in \mathcal{B}_{0}}\left\|\beta_{A}-\beta\right\|_{\Sigma_{n}}$. Define $\psi_{\alpha}^{M P}\left(\hat{\beta}_{n} ; A, d, \bar{\theta}, \Sigma_{n}, \delta_{A}, \tau_{A}\right)$ to be an indicator for whether the Neyman-Pearson test rejects $H_{0}$ in favor $H_{1}$ given a draw $\hat{\beta}_{n}$ that is assumed to be normally distributed with covariance $\Sigma_{n}$. The second limit can thus be written as

$$
\begin{aligned}
& \lim _{n \rightarrow \infty} \sup _{\mathcal{C}_{\alpha, n} \in \mathcal{I}_{\alpha}\left(\Delta, \frac{1}{n} \Sigma^{*}\right)} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\alpha, n}\right)= \\
& \lim _{n \rightarrow \infty} \mathbb{E}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left[\psi_{\alpha}^{M P}\left(\hat{\beta}_{n} ; A, d, \theta^{u b}+\frac{1}{\sqrt{n}} x, \Sigma_{n}, \delta_{A}, \tau_{A}\right)\right]
\end{aligned}
$$

From Lemma B. 6 and the fact that $\Sigma_{n}=\frac{1}{n} \Sigma^{*}, \psi_{\alpha}^{M P}\left(\hat{\beta}_{n} ; A, d, \theta^{u b}+\frac{1}{\sqrt{n}} x, \Sigma_{n}, \delta_{A}, \tau_{A}\right)=$ $\psi_{\alpha}^{M P}\left(\sqrt{n} \hat{\beta}_{n} ; A, \sqrt{n} d, \sqrt{n} \theta^{u b}+x, \Sigma^{*}, \sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}\right)$. It follows that

$$
\begin{gathered}
\lim _{n \rightarrow \infty} \sup _{\mathcal{C}_{\alpha, n} \in \mathcal{I}_{\alpha}\left(\Delta, \Sigma_{n}\right)} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\alpha, n}\right) \stackrel{(1)}{=} \\
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\alpha}^{M P}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \sqrt{n} \theta^{u b}+x, \Sigma^{*}, \sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}\right)\right] \stackrel{(2)}{=} \\
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\alpha}^{M P}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}, \sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}\right)\right] \stackrel{(3)}{\longrightarrow} \Phi\left(c^{*} x-z_{1-\alpha}\right),
\end{gathered}
$$

where (1) used that if $\hat{\beta}_{n} \sim \mathcal{N}\left(\beta_{A}, \frac{1}{n} \Sigma^{*}\right)$, then $\sqrt{n} \hat{\beta}_{n} \sim \mathcal{N}\left(\sqrt{n} \beta_{A}, \Sigma^{*}\right)$, (2) used that $\theta_{n}^{u b}=\sqrt{n} \theta^{u b}$ and (3) follows by Lemma B.12.

## Proof of Proposition A. 1

Proof. Following the same argument as in the proof to Proposition 3.2, we can show that
$\mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta^{u b}+\frac{x}{\sqrt{n}}\right) \in \mathcal{C}_{\alpha, n}^{F L C I}\right)$ equals

$$
\begin{equation*}
\Phi\left(\frac{\theta^{\text {mid }}+\bar{b}_{\text {min }}+\frac{x}{\sqrt{n}}+\chi_{n}-\mu_{n}}{\sigma_{v_{n}, n}}\right)-\Phi\left(\frac{\theta^{\text {mid }}+\bar{b}_{m i n}+\frac{x}{\sqrt{n}}-\chi_{n}-\mu_{n}}{\sigma_{v_{n}, n}}\right), \tag{28}
\end{equation*}
$$

where $\bar{b}_{\text {min }}=\frac{1}{2} L I D\left(\Delta, \delta_{A, \text { pre }}\right), \mu_{n}=a_{n}+v_{n}^{\prime}\left(\delta_{A}+\tau_{A}\right)$, and $\theta^{\text {mid }}$ is the midpoint of $\mathcal{S}\left(\Delta, \delta_{A}+\right.$ $\left.\tau_{A}\right)$.

The term inside the second normal CDF in the previous display equals

$$
\begin{equation*}
-\frac{\chi_{n}-b_{n}}{\sigma_{v_{n}, n}}+\frac{x}{\sqrt{n} \sigma_{v_{n}, n}}+\frac{\theta^{\text {mid }}-\mu_{n}+\bar{b}_{\text {min }}-b_{n}}{\sigma_{v_{n}, n}} . \tag{29}
\end{equation*}
$$

We first show the first term in (29) converges to $-z_{1-\alpha}$. Since $\chi_{n}$ is the $1-\alpha$ quantile of the $\left|\mathcal{N}\left(b_{n}, \sigma_{v_{n}, n}^{2}\right)\right|$ distribution, $\Phi\left(\frac{\chi_{n}-b_{n}}{\sigma_{v_{n}, n}}\right)-\Phi\left(\frac{-\chi_{n}-b_{n}}{\sigma_{v_{n}, n}}\right)=1-\alpha$. Lemma B. 25 implies that $\bar{b}_{\text {min }}=\frac{1}{2} \sup _{\tilde{\delta}_{p r e}} L I D\left(\Delta, \tilde{\delta}_{\text {pre }}\right)>0$. We argued in the proof to Proposition 3.2 that $b_{n} \geqslant \bar{b}_{\text {min }}>0, \chi_{n} \geqslant 0$, and $\sigma_{v_{n}, n} \rightarrow 0$, from which we see that $\frac{-\chi_{n}-b_{n}}{\sigma_{v_{n}, n}} \rightarrow-\infty$. It follows that $\Phi\left(\frac{\chi_{n}-b_{n}}{\sigma_{v_{n}, n}}\right) \rightarrow 1-\alpha$, and hence $\frac{\chi_{n}-b_{n}}{\sigma_{v_{n}, n}} \rightarrow z_{1-\alpha}$.

Next, we show the second term in (29) converges to $c^{*} x$, for the constant $c^{*}$ defined in Proposition 4.2. Lemma B. 23 implies that $\lim _{n \rightarrow \infty} \frac{x}{\sqrt{n} \sigma_{v_{n}, n}}=\lim _{n \rightarrow \infty} \frac{x}{\sqrt{n} \sigma_{\bar{v}, n}}=\frac{x}{\sigma_{\bar{v}, 1}}$, where $\bar{v}$ is the unique value such that there exists $(\bar{a}, \bar{v})$ with $\bar{b}(\bar{a}, \bar{v})=\bar{b}_{\text {min }}$. Moreover, Lemma B. 22 implies that $1 / \sigma_{\bar{v}, 1}=c^{*}$, from which we see that the limit of the second term is $c^{*} x$, as desired.

Now, we show the third term in (29) converges to 0 . We argued in the proof to Proposition 3.2 that $\left|\mu_{n}-\theta^{\text {mid }}\right| \leqslant b_{n}-\bar{b}_{\text {min }}$. It thus suffices to show that $\frac{b_{n}-\bar{b}_{\text {min }}}{\sigma_{v_{n}, n}} \rightarrow 0$. Lemma B. 22 implies that there is a unique pair $(\bar{a}, \bar{v})$ such that $\bar{b}(\bar{a}, \bar{v})=\bar{b}_{\text {min }}$. Let $\bar{\chi}_{n}=\chi_{n}(\bar{a}, \bar{v})$ and $\chi_{n}=\chi_{n}\left(a_{n}, v_{n}\right)$. Note that $\chi_{n} \leqslant \bar{\chi}_{n}$ by construction, and $b_{n} \geqslant \bar{b}_{\text {min }}$ by Lemma B.19. Hence, using the bounds from Lemma B.21, we have that $b_{n}+\sigma_{v_{n}, n} z_{1-\alpha} \leqslant \chi_{n} \leqslant \bar{\chi}_{n}=\sigma_{\bar{v}, n} c v_{\alpha}\left(\frac{\bar{b}_{\text {min }}}{\sigma_{\bar{v}, n}}\right)$, which, along with the inequality $b_{n} \geqslant \bar{b}_{\text {min }}$, implies that

$$
\begin{aligned}
0 \leqslant \frac{b_{n}-\bar{b}_{m i n}}{\sigma_{v_{n}, n}} \leqslant & \frac{\sigma_{\bar{v}, n}}{\sigma_{v_{n}, n}} c v_{\alpha}\left(\frac{\bar{b}_{m i n}}{\sigma_{\bar{v}, n}}\right)-\left(z_{1-\alpha}+\frac{\bar{b}_{m i n}}{\sigma_{v_{n}, n}}\right) \\
= & {\left[c v_{\alpha}\left(\frac{\bar{b}_{m i n}}{\sigma_{\bar{v}, n}}\right)-\left(z_{1-\alpha}+\frac{\bar{b}_{m i n}}{\sigma_{\bar{v}, n}}\right)\right]+} \\
& {\left[\left(\frac{\sigma_{\bar{v}, n}}{\sigma_{v_{n}, n}}-1\right) c v_{\alpha}\left(\frac{\bar{b}_{\text {min }}}{\sigma_{\bar{v}, n}}\right)-\left(\frac{\bar{b}_{\text {min }}}{\sigma_{v_{n}, n}}-\frac{\bar{b}_{m i n}}{\sigma_{\bar{v}, n}}\right)\right] . }
\end{aligned}
$$

The first bracketed expression in the upper bound above converges to 0 by Lemma B.24. Applying the upper bound from Lemma B. 21 to the $c v_{\alpha}$ term in the second bracketed expression, we obtain that the second bracketed expression is bounded above by $\left(\frac{\sigma_{\bar{v}, n}}{\sigma_{v_{n}, n}}-1\right) z_{1-\alpha / 2}$, which converges to 0 by Lemma B.23.

Combining the results above, we see that the expression in (29) converges to $c^{*} x-$ $z_{1-\alpha}$. It follows that $\lim \sup _{n \rightarrow \infty} \mathbb{P}\left(\left(\theta^{u b}+\frac{x}{\sqrt{n}}\right) \in \mathcal{C}_{\alpha, n}^{F L C I}\right) \leqslant 1-\Phi\left(c^{*} x-z_{1-\alpha}\right)$, and hence $\liminf _{n \rightarrow \infty} \mathbb{P}\left(\left(\theta^{u b}+\frac{x}{\sqrt{n}}\right) \notin \mathcal{C}_{\alpha, n}^{F L C I}\right) \geqslant \Phi\left(c^{*} x-z_{1-\alpha}\right)$. Proposition 4.2 gives that $\Phi\left(c^{*} x-z_{1-\alpha}\right)$ is the optimal local asymptotic power over procedures that control size, from which the result follows.

## Proof of Proposition A. 2

Proof. The proof follows from the same argument as for Proposition 4.1, replacing Lemma B. 2 with Lemma B.4, and Lemma B. 16 with Lemma B.17.

## Proof of Proposition A. 3

Proof. By an invariance to scale argument analogous to that in the proof of Proposition 4.2, $\liminf _{n \rightarrow \infty} \mathbb{P}_{\left(\delta_{A}, \tau_{A}, \Sigma_{n}\right)}\left(\left(\theta_{A}^{u b}+\frac{1}{\sqrt{n}} x\right) \notin \mathcal{C}_{\kappa, \alpha, n}^{C-F L C I}\right)$ equals

$$
\liminf _{n \rightarrow \infty} \mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\kappa, \alpha}^{C-F L C I}\left(\hat{\beta}_{n}, A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)\right] .
$$

From Proposition 4.2, it thus suffices to show

$$
\begin{aligned}
& \liminf _{n \rightarrow \infty} \mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\kappa, \alpha}^{C-F L C I}\left(\hat{\beta}_{n}, A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)\right] \geqslant \\
& \liminf _{n \rightarrow \infty} \mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\tilde{\alpha}}^{C}\left(\hat{\beta}_{n}, A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)\right] .
\end{aligned}
$$

Note that the second stage of the test $\psi_{\kappa, \alpha}^{C-F L C I}$ is nearly identical to $\psi_{\tilde{\alpha}}^{C}$ except it uses $v_{C-F L C I}^{l o}:=\max \left\{v^{l o}, v_{F L C I}^{l o}\right\}$ and $v_{C-F L C I}^{u p}:=\min \left\{v^{u p}, v_{F L C I}^{u p}\right\}$ instead of $v^{l o}$ and $v^{u p}$. Since $F_{\xi: \xi \in\left[v^{l o}, v^{u p}\right]}(\hat{\eta})$ is decreasing in $v^{l o}$ and $v^{u p}$, it suffices to show that $v_{F L C I}^{l o} \xrightarrow{P_{n}} p-\infty$, where $P_{n}$ denotes the sequence of distributions under which $(\delta, \tau, \Sigma)=\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)$.

Let $\Delta_{n}=\{\delta: A \delta \leqslant \sqrt{n} d\}$. Let $v_{n}=v_{n}\left(\Delta_{n}, \Sigma^{*}\right)$ and $\breve{v}_{n}=v_{n}\left(\Delta, \Sigma_{n}\right)$. Define $a_{n}$ and $\breve{a}_{n}$, and $\breve{\chi}_{n}$ and $\chi_{n}$ analogously. By Lemma B.3, $v_{n}=\breve{v}_{n}, a_{n}=\sqrt{n} \breve{a}_{n}, \chi_{n}=\sqrt{n} \breve{\chi}_{n}$, and $\bar{b}\left(a, v ; \Delta_{n}\right)=\sqrt{n} \bar{b}(\breve{a}, \breve{v}, \Delta)$. We argued in the proof to Lemma B. 23 that $\breve{v}_{n} \rightarrow \bar{v}$. Further, we showed in the proof to Lemma B. 22 that $\bar{v}=-\bar{\gamma} A$, where $\bar{\gamma}_{-B}=0$ and $\bar{\gamma}_{B}$ is the unique vector such that $\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)}=1, \bar{\gamma}_{B}^{\prime} \tilde{A}_{(B,-1)}=0$. Likewise, we argued in the proof to Lemma
B. 23 that $\breve{a}_{n} \rightarrow \bar{a}$, for $\bar{a}$ the unique value such that $\bar{b}(\bar{a}, \bar{v} ; \Delta)=b_{\min }(\Delta)$. We also showed in the proof to Proposition 3.2 that $\breve{\chi}_{n} \rightarrow b_{\text {min }}(\Delta)$.

Let $\tilde{v}_{n}$ be a vector such that $\tilde{v}_{n}^{\prime} A=v^{\prime}$ (which exists by Lemma A.2). Observe that

$$
\tilde{v}_{n}^{\prime} \tilde{\Sigma} \bar{\gamma}=\tilde{v}_{n}^{\prime} A \Sigma^{*} A^{\prime} \bar{\gamma} \rightarrow \bar{v}^{\prime} \Sigma^{*} A^{\prime} \bar{\gamma}=-\bar{\gamma}^{\prime} A \Sigma^{*} A^{\prime} \bar{\gamma}=-\bar{\gamma}^{\prime} \tilde{\Sigma} \bar{\gamma}
$$

where we use $\tilde{v}_{n}^{\prime} A=v_{n}, v_{n} \rightarrow \bar{v}=-\bar{\gamma}^{\prime} A$ as shown above, and the identity $\tilde{\Sigma}=A \Sigma^{*} A^{\prime}$.
Now, Lemma B. 27 implies that there is a constant $c>0$ such that, with probability approaching one under $P_{n}, c \cdot \bar{\gamma}$ is an optimal vertex of the dual problem for $\psi_{\kappa, \alpha}^{C-F L C I}\left(\hat{\beta}_{n}, A, \sqrt{n} d, \theta_{n}^{u b}+\right.$ $\left.x, \Sigma^{*}\right)$. Observe from Lemma A. 3 that if $\gamma_{*}$ is an optimal vertex, and $\frac{v_{n}^{\prime} \tilde{\Sigma} \gamma_{*}}{\gamma_{*}^{\prime} \tilde{\Sigma} \gamma_{*}}<0$, then the value of $v_{F L C I}^{l o}$ used in $\psi_{\kappa, \alpha}^{C-F L C I}\left(\hat{\beta}_{n}, A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)$ is

$$
\begin{equation*}
v_{F L C I}^{l o}=\frac{d_{n, 1}-\tilde{v}_{n}^{\prime}\left(I-\frac{\tilde{\Sigma} \gamma_{*}}{\gamma_{*}^{\prime} \tilde{\Sigma} \gamma_{*}} \gamma_{*}^{\prime}\right) \tilde{Y}_{n}}{\tilde{v}_{n}^{\prime} \tilde{\Sigma} \gamma_{*} / \gamma_{*}^{\prime} \tilde{\Sigma} \gamma_{*}}=\frac{-\left(\tilde{v}_{n}^{\prime} \tilde{Y}_{n}-d_{n, 1}\right)}{v_{n}^{\prime} \tilde{\Sigma} \gamma_{*} / \gamma_{*}^{\prime} \tilde{\Sigma} \gamma_{*}}+\gamma_{*}^{\prime} \tilde{Y}_{n} \tag{30}
\end{equation*}
$$

where $\tilde{Y}_{n}=A \hat{\beta}_{n}-\sqrt{n} d-\tilde{A}_{(\cdot, 1)}\left(\theta_{n}^{u b}+x\right)$. Since $c \bar{\gamma}$ is optimal in the dual with probability approaching one under $P_{n}$, and

$$
\begin{equation*}
\frac{v_{n}^{\prime} \tilde{\Sigma} c \bar{\gamma}}{c^{2} \bar{\gamma}^{\prime} \tilde{\Sigma} \bar{\gamma}} \rightarrow-\frac{1}{c}<0 \tag{31}
\end{equation*}
$$

by the argument above, we have that with probability approaching 1 under $P_{n}$,

$$
\begin{equation*}
v_{F L C I}^{l o}=\frac{-\left(\tilde{v}_{n}^{\prime} \tilde{Y}_{n}-d_{n, 1}\right)}{v_{n}^{\prime} \tilde{\Sigma} c \bar{\gamma} / c^{2} \bar{\gamma}^{\prime} \tilde{\Sigma} \bar{\gamma}}+c \bar{\gamma}^{\prime} \tilde{Y}_{n} \tag{32}
\end{equation*}
$$

Now, we showed in the proof to Lemma B. 8 that $\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\breve{Y}_{n, B}\right]=-\tilde{A}_{(B, 1)} x$ regardless of $n$, where $\breve{Y}_{n}=\tilde{Y}_{n}-\tilde{A}_{(\cdot,-1)}\left(\sqrt{n} \tilde{\tau}_{1}^{u b}\right)$ for a vector $\tilde{\tau}_{1}^{u b}$. Since $\bar{\gamma}_{-B}=0$ and $\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B,-1)}=0$, it follows that $\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\bar{\gamma}^{\prime} \tilde{Y}_{n}\right]=-\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)} x$ regardless of $n$. Thus,

$$
\begin{equation*}
c \bar{\gamma}^{\prime} \tilde{Y}_{n} \stackrel{P_{n}}{\sim} \mathcal{N}\left(-c \bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)} x, c^{2} \bar{\gamma}^{\prime} \tilde{\Sigma} \bar{\gamma}\right) \tag{33}
\end{equation*}
$$

Now, note that by construction, $\tilde{v}_{n}^{\prime} \tilde{Y}_{n}-d_{n, 1}=a_{n}+v_{n}^{\prime} \hat{\beta}-\left(\theta_{n}^{u b}+x\right)-\chi_{n}$. Further, we have that $\hat{\beta}_{n} \stackrel{P_{n}}{\sim} \mathcal{N}\left(\sqrt{n} \beta_{A}, \Sigma^{*}\right)$, where $\beta_{A}=\delta_{A}+\tau_{A}$. It follows that under $P_{n}, \tilde{v}_{n}^{\prime} \tilde{Y}_{n}-d_{n, 1}=$ $a_{n}+v_{n}^{\prime} \sqrt{n} \beta_{A}-\left(\theta_{n}^{u b}+x\right)-\chi_{n}+v_{n}^{\prime} \xi$, where $\xi \sim \mathcal{N}\left(0, \Sigma^{*}\right)$. Applying the equalities $v_{n}=\breve{v}_{n}$, $a=\sqrt{n} \breve{a}_{n}, \chi_{n}=\sqrt{n} \check{\chi}$ derived above, along with the fact that $\theta_{n}^{u b}=\sqrt{n} \theta_{1}^{u b}$ by Lemma B.1, we see that under $P_{n}$,

$$
\begin{equation*}
\tilde{v}_{n}^{\prime} \tilde{Y}_{n}-\tilde{d}_{1}=\sqrt{n}\left(\breve{a}_{n}+\breve{v}_{n}^{\prime} \beta_{A}-\theta_{1}^{u b}-\breve{\chi}_{n}\right)-x+\breve{v}_{n}^{\prime} \xi \tag{34}
\end{equation*}
$$

Since $\breve{v}_{n}^{\prime} \rightarrow \bar{v}$, it follows that $\breve{v}_{n}^{\prime} \xi \rightarrow{ }_{d} \bar{v}^{\prime} \xi$ by Slutsky's lemma.
Additionally, the results above imply that $\breve{a}_{n}+\breve{v}_{n}^{\prime} \beta_{A}-\theta_{1}^{u b}-\breve{\chi}_{n} \rightarrow \bar{a}+\bar{v}^{\prime} \beta_{A}-\theta_{1}^{u b}-\bar{b}_{m i n}(\Delta)$. We claim that this limit is strictly negative. Since Assumption 5 holds, Lemma B. 25 implies that $\operatorname{LID}\left(\Delta, \delta_{A}\right)>0$. Hence, for $\epsilon>0$ sufficiently small, we have that $\theta_{1}^{u b}-\epsilon \in \mathcal{S}\left(\Delta, \beta_{A}\right)$. If the limit above were weakly positive, then we would have $\bar{a}+\bar{v}^{\prime} \beta_{A}-\left(\theta_{1}^{u b}-\epsilon\right)-\bar{b}_{\text {min }}(\Delta)>0$. However, this implies that $\bar{b}(\bar{a}, \bar{v})>\bar{b}_{\text {min }}(\Delta)$, which is a contradiction. The limit must thus be strictly negative, as desired. We then see from (34) that

$$
\begin{equation*}
\tilde{v}_{n}^{\prime} \tilde{Y}_{n}\left(\theta_{n}^{u b}+x\right)-d_{n, 1} \xrightarrow{P_{n}} p-\infty . \tag{35}
\end{equation*}
$$

Displays (31), (32), (33), and (35) together give that $v_{F L C I}^{l o} \xrightarrow{P_{n}}-\infty$, as desired.

## B. 2 Auxiliary Lemmas for Finite Sample Normal Results

Lemma B.1. For any $n>0$, let $\Delta_{n}=\{\delta: A \delta \leqslant \sqrt{n} d\}$. Fix $\delta_{A} \in \Delta_{1}$ and $\tau_{A}$. Then, $\mathcal{S}\left(\sqrt{n} \delta_{A}+\sqrt{n} \tau_{A}, \Delta_{n}\right)=\sqrt{n} \mathcal{S}\left(\delta_{A}+\tau_{A}, \Delta_{1}\right)$. This implies $\theta_{n}^{u b}=\sqrt{n} \theta_{1}^{u b}$, where $\theta_{n}^{u b}:=$ $\sup _{\theta} \mathcal{S}\left(\sqrt{n} \delta_{A}+\sqrt{n} \tau_{A}, \Delta_{n}\right)$, and $\theta_{n}^{l b}=\sqrt{n} \theta_{1}^{l b}$, for $\theta_{n}^{l b}:=\inf _{\theta} \mathcal{S}\left(\sqrt{n} \delta_{A}+\sqrt{n} \tau_{A}, \Delta_{n}\right)$

Proof. Let $\mathcal{S}_{n}=\mathcal{S}\left(\sqrt{n} \delta_{A}+\sqrt{n} \tau_{A}, \Delta_{n}\right)$ and $\beta_{A}=\delta_{A}+\tau_{A}$. By definition, $\bar{\theta}_{n} \in \mathcal{S}_{n}$ iff there exists a vector $\tau_{\text {post }} \in \mathbb{R}^{\bar{T}}$ such that $l^{\prime} \tau_{\text {post }}=\bar{\theta}_{n}$ and $A\left(\sqrt{n} \beta_{A}-M_{\text {post }} \tau_{\text {post }}-\sqrt{n} d\right) \leqslant 0$. Using the change of basis described in Section 4.1, it follows that $\bar{\theta}_{n} \in \mathcal{S}_{n}$ iff there exists $\tilde{\tau}_{n} \in \mathbb{R}^{\bar{T}-1}$ such that

$$
\begin{equation*}
A \sqrt{n} \beta_{A}-\sqrt{n} d-\tilde{A}_{(\cdot, 1)} \bar{\theta}_{n}-\tilde{A}_{(\cdot,-1)} \tilde{\tau}_{n} \leqslant 0 \tag{36}
\end{equation*}
$$

Thus, $\bar{\theta}_{1} \in \mathcal{S}_{1}$ iff there exists $\tilde{\tau}_{1}$ such that

$$
\begin{equation*}
A \beta_{A}-d-\tilde{A}_{(\cdot, 1)} \bar{\theta}_{1}-\tilde{A}_{(\cdot,-1)} \tilde{\tau}_{1} \leqslant 0 \tag{37}
\end{equation*}
$$

If there exists a $\tilde{\tau}_{1}$ such that (37) holds for $\bar{\theta}_{1}$, then multiplying both sides of (37) by $\sqrt{n}$ implies that (36) holds with $\bar{\theta}_{n}=\sqrt{n} \bar{\theta}_{1}$ and $\tilde{\tau}_{n}=\sqrt{n} \tilde{\tau}_{1}$. Likewise, if there exists a $\tilde{\tau}_{n}$ such that (36) holds for $\bar{\theta}_{n}$, then multiplying both sides of (36) by $\frac{1}{\sqrt{n}}$ implies that (37) holds with $\bar{\theta}_{1}=\frac{1}{\sqrt{n}} \bar{\theta}_{n}$ and $\tilde{\tau}_{1}=\frac{1}{\sqrt{n}} \tilde{\tau}_{n}$. The desired result follows immediately.

Lemma B.2. For any $n>0$ and $(\hat{\beta} ; A, d, \bar{\theta}, \Sigma), \psi_{\alpha}^{C}(\hat{\beta} ; A, d, \bar{\theta}, \Sigma)=\psi_{\alpha}^{C}(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, n \Sigma)$.

Proof. Using the change of basis described in Section 4.1, the test statistic used to calculate $\psi_{\alpha}^{C}(\hat{\beta} ; A, d, \bar{\theta}, \Sigma)$ is

$$
\min _{\eta, \tilde{\tau}} \eta \quad \text { s.t } \quad A \hat{\beta}-d-\tilde{A}_{(\cdot, 1)} \bar{\theta}-\tilde{A}_{(\cdot,-1)} \tilde{\tau} \leqslant \eta \tilde{\sigma}
$$

where $\tilde{\sigma}$ is the vector containing the square roots of the diagonal elements of $\tilde{\Sigma}=A \Sigma A^{\prime}$. Since multiplying the constraints by $\sqrt{n}$ does not change the feasible set, this optimization is equivalent to

$$
\min _{\eta, \tilde{\tau}} \eta \quad \text { s.t. } \quad A \sqrt{n} \hat{\beta}-\sqrt{n} d-\tilde{A}_{(\cdot, 1)} \sqrt{n} \bar{\theta}-\tilde{A}_{(\cdot,-1)} \sqrt{n} \tilde{\tau} \leqslant \eta \sqrt{n} \tilde{\sigma} .
$$

However, since $\tilde{\tau}$ enters only in the constraint, and $\left\{\sqrt{n} \tilde{\tau}: \tilde{\tau} \in \mathbb{R}^{\bar{T}-1}\right\}=\left\{\tilde{\tau} \in \mathbb{R}^{\bar{T}-1}\right\}$, this linear program is equivalent to

$$
\min _{\eta, \tilde{\tau}} \eta \text { s.t } A \sqrt{n} \hat{\beta}-\sqrt{n} d-\tilde{A}_{(\cdot, 1)} \sqrt{n} \bar{\theta}-\tilde{A}_{(\cdot,-1)} \tilde{\tau} \leqslant \eta \sqrt{n} \tilde{\sigma}
$$

which is the test statistic used to calculate $\psi_{\alpha}^{C}(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, n \Sigma)$. Thus, the test statistics used for the two problems are the same. Additionally, the feasible set for the dual for the unscaled problem is $F_{1}=\left\{\gamma: \gamma^{\prime} \tilde{A}_{(\cdot,-1)}=0, \gamma^{\prime} \tilde{\sigma}=1, \gamma \geqslant 0\right\}$, whereas for the problem scaled by $\sqrt{n}$ it is $F_{n}=\left\{\gamma: \gamma^{\prime} \tilde{A}_{(\cdot,-1)}=0, \gamma^{\prime} \sqrt{n} \tilde{\sigma}=1, \gamma \geqslant 0\right\}=\frac{1}{\sqrt{n}} F_{1}$. It follows that $V_{n}=\frac{1}{\sqrt{n}} V_{1}$, for $V_{1}$ and $V_{n}$ respectively the vertices of $F_{1}$ and $F_{n}$. Moreover, it is immediate that if $\gamma_{1}$ is an optimal vertex of the unscaled problem, then $\gamma_{n}=\frac{1}{\sqrt{n}} \gamma_{1}$ will be an optimal vertex of the problem scaled by $\sqrt{n}$.

Recall that the critical value for the conditional test depends on $\gamma_{*}^{\prime} \tilde{\Sigma} \gamma_{*}$, where $\gamma_{*}$ is an optimal vertex, and the values $v^{l o}$ and $v^{u p}$ which are functions of $\gamma_{*}, \tilde{\Sigma}$, and a sufficient statistic $S$. However, for $\gamma_{n}=\frac{1}{\sqrt{n}} \gamma_{1}$, we have that $\gamma_{n}^{\prime}(n \tilde{\Sigma}) \gamma_{n}=\frac{1}{\sqrt{n}} \gamma_{1}^{\prime}(n \tilde{\Sigma}) \frac{1}{\sqrt{n}} \gamma_{1}=\gamma_{1}^{\prime} \tilde{\Sigma} \gamma_{1}$, and so the variances are the same. Let $\tilde{Y}_{1}=A \hat{\beta}-d-\tilde{A}_{(\cdot, 1)} \bar{\theta}$ and $\tilde{Y}_{n}=A \sqrt{n} \hat{\beta}-\sqrt{n} d-\tilde{A}_{(\cdot, 1)} \sqrt{n} \bar{\theta}=$ $\sqrt{n} \tilde{Y}_{1}$. The sufficient statistic used to construct $v^{l o}$ and $v^{u p}$ in the first problem is $S_{1}=(I-$ $\left.\frac{\Sigma}{\Sigma_{1}^{\prime} \gamma_{1} \gamma_{1}^{\prime}}\right) \tilde{Y}_{1}$, whereas for the second problem it is $S_{n}=\left(I-\frac{n \tilde{\Sigma} \gamma_{n} \gamma_{n}^{\prime}}{\gamma_{n}^{\prime} n \Sigma \gamma_{n}}\right) \tilde{Y}_{n}$. The identities $\tilde{Y}_{n}=\sqrt{n} \tilde{Y}_{1}$ and $\gamma_{1}=\sqrt{n} \gamma_{n}$ immediately imply that $S_{n}=\sqrt{n} S_{1}$. The values $v^{l o}$ and $v^{u p}$ for the first problem are then the minimum and maximum of $C_{1}=\left\{c: c=\max _{\tilde{\gamma}_{1} \in V_{1}} \tilde{\gamma}_{1}^{\prime}\left(S_{1}+\frac{\tilde{\Sigma} \gamma_{1}}{\gamma_{1}^{\prime} \tilde{\gamma_{1}}} c\right)\right\}$. Likewise, the values $v^{l o}$ and $v^{u p}$ for the second problem are the the minimum and maximum of $C_{n}=\left\{c: c=\max _{\tilde{\gamma}_{n} \in V_{n}} \tilde{\gamma}_{n}^{\prime}\left(S_{n}+\frac{n \tilde{\Sigma} \gamma_{n}}{\gamma_{n}^{\prime} n \tilde{\Sigma} \gamma_{n}} c\right)\right\}$, However, since $V_{n}=\sqrt{n} V_{1}, S_{n}=\sqrt{n} S_{1}$, and $\gamma_{n}=\frac{1}{\sqrt{n}} \gamma_{1}$, we have that for any $c$,

$$
\left.\max _{\tilde{\gamma}_{1} \in V_{1}} \tilde{\gamma}_{1}^{\prime}\left(S_{1}+\frac{\tilde{\Sigma} \gamma_{1}}{\gamma_{1}^{\prime} \tilde{\Sigma} \gamma_{1}} c\right)=\max _{\tilde{\gamma}_{n} \in V_{n}} \sqrt{n} \tilde{\gamma}_{n}^{\prime}\left(\frac{1}{\sqrt{n}} S_{n}+\frac{\tilde{\Sigma} \sqrt{n} \gamma_{n}}{\gamma_{n}^{\prime} n \tilde{\Sigma} \gamma_{n}} c\right)=\max _{\tilde{\gamma}_{n} \in V_{n}} \tilde{\gamma}_{n}^{\prime}\left(S_{n}+\frac{n \tilde{\Sigma} \gamma_{n}}{\gamma_{n}^{\prime} n \tilde{\Sigma} \gamma_{n}} c\right)\right\},
$$

from which it is immediate that $C_{1}=C_{n}$, and hence the values of $v^{l o}$ and $v^{u p}$ are the same across the two problems as well. Since the test statistics and critical values of the two problems are the same, they are equivalent.

Lemma B.3. Let $v_{n}\left(\Delta, \Sigma_{n}\right)$ be the vector $v_{n}$ used in the optimal FLCI as defined in Section 3, making the dependence on $\left(\Delta, \Sigma_{n}\right)$ explicit. Define, $\chi_{n}\left(\Delta, \Sigma_{n}\right)$, $a_{n}\left(\Delta, \Sigma_{n}\right)$, and $\bar{b}_{n}\left(\Delta, \Sigma_{n}\right)$ analogously. Let $\Sigma_{n}=\frac{1}{n} \Sigma^{*}$ and $\Delta_{n}=\sqrt{n} \Delta$. Then

1. $v_{n}\left(\Delta_{n}, \Sigma^{*}\right)=v_{n}\left(\Delta, \frac{1}{n} \Sigma_{n}\right)$
2. $a_{n}\left(\Delta_{n}, \Sigma^{*}\right)=\sqrt{n} a_{n}\left(\Delta, \frac{1}{n} \Sigma_{n}\right)$
3. $\chi_{n}\left(\Delta_{n}, \Sigma^{*}\right)=\sqrt{n} \chi_{n}\left(\Delta, \frac{1}{n} \Sigma_{n}\right)$
4. $\bar{b}\left(a_{n}\left(\Delta_{n}, \Sigma^{*}\right), v_{n}\left(\Delta_{n}, \Sigma^{*}\right) ; \Delta_{n}\right)=\sqrt{n} \bar{b}\left(a_{n}\left(\Delta, \Sigma_{n}\right), v_{n}\left(\Delta, \Sigma_{n}\right) ; \Delta\right)$.

Proof. We show in the proof to Lemma B. 19 that $\bar{b}\left(a, v ; \Delta_{n}\right)$ is finite only if $v_{p o s t}=l$, in which case $\bar{b}(a, v ; \Delta)=\max _{\delta \in \Delta}\left|a+v^{\prime} \delta\right|$. Likewise, $\bar{b}\left(\sqrt{n} a, v ; \Delta_{n}\right)$ is finite only if $v_{p o s t}=l$, in which case

$$
\bar{b}(\sqrt{n} a, v ; \Delta)=\max _{\delta_{n} \in \Delta_{n}}\left|\sqrt{n} a+v^{\prime} \delta_{n}\right|=\max _{\delta \in \Delta}\left|\sqrt{n} a+v^{\prime} \sqrt{n} \delta\right|=\sqrt{n} \bar{b}(a, v, \Delta)
$$

Next, observe that using the invariance above and $\Sigma_{n}=\frac{1}{n} \Sigma^{*}$,

$$
\begin{aligned}
\chi\left(\sqrt{n} a, v ; \Sigma^{*}, \Delta_{n}\right) & =\sqrt{v^{\prime} \Sigma^{*} v} \cdot c v_{\alpha}\left(\frac{\bar{b}\left(\sqrt{n} a, v ; \Delta_{n}\right.}{\sqrt{v^{\prime} \Sigma^{*} v}}\right) \\
& =\sqrt{n} \cdot \sqrt{v^{\prime} \Sigma_{n} v} \cdot c v_{\alpha}\left(\frac{\bar{b}(a, v ; \Delta)}{\sqrt{v^{\prime} \Sigma_{n} v}}\right)=\sqrt{n} \chi\left(a, v ; \Sigma^{*}, \Delta\right) .
\end{aligned}
$$

It is then immediate that if $\left(a^{*}, v^{*}\right)=\arg \min _{(a, v)} \chi\left(a, v ; \Delta, \Sigma_{n}\right)$, then $\left(\sqrt{n} a^{*}, v^{*}\right)=\arg \min _{(a, v)}$ $\chi\left(a, v ; \Delta_{n}, \Sigma^{*}\right)$, from which the first two results follow. The second two results then follow from the two invariances derived above.

Lemma B.4. For any $n>0$ and $(\hat{\beta} ; A, d, \bar{\theta}, \Sigma)$,

$$
\psi_{\kappa, \alpha}^{C-F L C I}(\hat{\beta} ; A, d, \bar{\theta}, \Sigma)=\psi_{\kappa, \alpha}^{C-F L C I}(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, n \Sigma) .
$$

Proof. From Lemma B.3, if $\mathcal{C}_{\kappa}^{F L C I}(\hat{\beta} ; A, d, \bar{\theta}, \Sigma)=a_{1}+v_{1}^{\prime} \hat{\beta} \pm \chi_{1}$, then $\mathcal{C}_{\kappa}^{F L C I}(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, \sqrt{n} \Sigma)=$ $\sqrt{n}\left(a_{1}+v_{1}^{\prime} \hat{\beta} \pm \chi_{1}\right)$. Thus, $\bar{\theta} \in \mathcal{C}_{\kappa}^{F L C I}(\hat{\beta} ; A, d, \bar{\theta}, \Sigma) \mathrm{iff} \sqrt{n} \bar{\theta} \in \mathcal{C}_{\kappa}^{F L C I}(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, \sqrt{n} \Sigma)$, so the first stage tests are equivalent. The second stage test is almost identical to $\psi_{\tilde{\alpha}}^{C}$, which is invariant to scale by Lemma B.2, except it replaces $v^{l o}$ with $\max \left\{v^{l o}, v_{F L C I}^{l o}\right\}$ and $v^{u p}$ with
$\min \left\{v^{u p}, v_{F L C I}^{u p}\right\}$. It thus suffices to show that $v_{F L C I}^{l o}$ and $v_{F L C I}^{u p}$ are invariant to scale. We show in the proof to Lemma B. 2 that $S_{n}=\sqrt{n} S_{1}$, and if $\gamma_{n} \in \hat{V}_{n}$ then $\gamma_{1}=\sqrt{n} \gamma_{n} \in \hat{V}_{n}$; where objects subscripted by 1 indicate values based on $(\hat{\beta} ; A, d, \bar{\theta}, \Sigma)$ and values subscripted by $n$ indicate those based on $(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, \sqrt{n} \Sigma)$. Additionally, Lemma B. 3 implies that $\tilde{V}_{1}=\tilde{V}_{n}$, and $\bar{d}_{n}=\sqrt{n} \bar{d}_{n}$. The desired invariance is then immediate from the formulas in Lemma A. 3 .

Lemma B.5. Suppose $\hat{\beta} \sim \mathcal{N}(\beta, \Sigma)$ for $\Sigma$ known. Let $B_{0}$ be a closed, convex set. Then the most-powerful size $\alpha$ test of $H_{0}: \beta \in B_{0}$ against the point alternative $H_{A}: \beta=\beta_{A}$ is equivalent to the most powerful test of $H_{0}: \beta=\tilde{\beta}$ against $H_{A}: \beta=\beta_{A}$, where $\tilde{\beta}=$ $\arg \min _{\beta}\left\|\beta-\beta_{A}\right\|_{\Sigma}$ and $\|\cdot\|_{\Sigma}$ is the Mahalanobis norm in $\Sigma,\|x\|_{\Sigma}=\sqrt{x^{\prime} \Sigma^{-1} x}$. The most powerful test rejects for values of $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1} \hat{\beta}$ greater than $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1} \tilde{\beta}+z_{1-\alpha}\left\|\beta_{A}-\tilde{\beta}\right\|_{\Sigma}$, and has power against the alternative of $\Phi\left(\left\|\beta_{A}-\tilde{\beta}\right\|_{\Sigma}-z_{1-\alpha}\right)$, for $z_{1-\alpha}$ the $1-\alpha$ quantile of the standard normal.

Proof. Define $<\cdot, \cdot>_{\Sigma}$ by $<x, y>_{\Sigma}=x^{\prime} \Sigma^{-1} y$, and observe that $<\cdot, \cdot>_{\Sigma}$ is an inner product. The result then follows immediately from the discussion in Section 2.4.3 of Ingster and Suslina (2003), replacing all instances of the usual euclidean inner product with $<\cdot, \cdot>_{\Sigma}$.

Lemma B.6. Suppose $\Delta=\{\delta: A \delta \leqslant d\}$. As in the proof to Proposition 4.2, let $\psi_{\alpha}^{M P}\left(\hat{\beta} ; A, d, \bar{\theta}, \Sigma, \delta_{A}, \tau_{A}\right)$ be an indicator for whether the most powerful (Neyman-Pearson) test between the null hypothesis $H_{0}: \delta \in \Delta, \theta=\bar{\theta}$ and the alternative $H_{A}:(\delta, \tau)=\left(\delta_{A}, \tau_{A}\right)$ rejects the null, given the realization $\hat{\beta}$ which is assumed to come from a normal distribution with variance $\Sigma$. Then for any $n>0$,

$$
\psi_{\alpha}^{M P}\left(\hat{\beta} ; A, d, \bar{\theta}, \Sigma, \delta_{A}, \tau_{A}\right)=\psi_{\alpha}^{M P}\left(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, n \Sigma, \sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}\right)
$$

Proof. As argued in the proof to Proposition 4.2, the null $H_{0}: \delta \in \Delta, \theta=\bar{\theta}$ is equivalent to the null $H_{0}: \beta \in \mathcal{B}_{0}(\bar{\theta}, d):=\left\{\beta: \exists \tau_{\text {post }}\right.$ s.t. $\left.l^{\prime} \tau_{\text {post }}=\bar{\theta}, A \beta-d-A M_{\text {post }} \tau_{\text {post }} \leqslant 0\right\}$. Likewise, the alternative that $(\delta, \tau)=\left(\delta_{A}, \tau_{A}\right)$ is equivalent to $H_{A}: \beta=\delta_{A}+\tau_{A}=$ : $\beta_{A}$. It is clear from the definition that $\mathcal{B}_{0}$ is convex. Thus, by Lemma B.5, the most powerful test of $H_{0}$ against $H_{A}$ when the covariance of $\hat{\beta}$ is $\Sigma$ is a t-test that rejects for large values of $\left(\beta_{A}-\tilde{\beta}_{1}\right)^{\prime} \Sigma^{-1} \hat{\beta}$, where $\tilde{\beta}_{1}=\arg \min _{\beta \in \mathcal{B}_{0}(\bar{\theta}, d)}\left\|\beta_{A}-\beta\right\|_{\Sigma}$. Its critical value is $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1} \tilde{\beta}_{1}+z_{1-\alpha}\left\|\beta_{A}-\tilde{\beta}_{1}\right\|_{\Sigma}$, for $z_{1-\alpha}$ the $1-\alpha$ quantile of the standard normal distribution.

Similarly, the null hypothesis $\delta \in\{\delta: A \delta \leqslant \sqrt{n} d\}, \theta=\sqrt{n} \bar{\theta}$ is equivalent to $H_{0}: \beta \in$ $\mathcal{B}_{0}(\sqrt{n} \bar{\theta}, \sqrt{n} d)=\left\{\beta: \exists \tau_{\text {post }}\right.$ s.t. $\left.l^{\prime} \tau_{\text {post }}=\sqrt{n} \bar{\theta}, A \beta-\sqrt{n} d-A M_{\text {post }} \tau_{\text {post }} \leqslant 0\right\}$. Likewise, the alternative that $(\delta, \tau)=\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}\right)$ is equivalent to $H_{A}: \beta=\sqrt{n} \delta_{A}+\sqrt{n} \tau_{A}=\sqrt{n} \beta_{A}$. It is clear from the definition that $\mathcal{B}_{0}(\sqrt{n} \bar{\theta}, \sqrt{n} d)$ is convex. Thus, by Lemma B.5, the most
powerful test of $H_{0}$ against $H_{A}$ when the covariance of $\hat{\beta}$ is $n \Sigma$ is a t-test that rejects for large values of $\left(\sqrt{n} \beta_{A}-\tilde{\beta}_{2}\right)^{\prime}(n \Sigma)^{-1} \hat{\beta}$, where $\tilde{\beta}_{2}=\arg \min _{\beta \in \mathcal{B}_{0}(\sqrt{n} \bar{\theta}, \sqrt{n} d)}\left\|\sqrt{n} \beta_{A}-\beta\right\|_{(n \Sigma)}$. Its critical value is $\left(\sqrt{n} \beta_{A}-\tilde{\beta}_{2}\right)^{\prime}(n \Sigma)^{-1} \tilde{\beta}_{2}+z_{1-\alpha}\left\|\beta_{A}-\tilde{\beta}_{2}\right\|_{(n \Sigma)}$.

Now, define

$$
\begin{equation*}
\eta(\hat{\beta}, A, d, \bar{\theta}, \Sigma):=\min _{\eta, \tilde{\tau}} \eta \text { s.t. } A \hat{\beta}-d-\tilde{A}_{(\cdot, 1)} \bar{\theta}-\tilde{A}_{(\cdot,-1)} \tilde{\tau} \leqslant \eta \tilde{\sigma} \tag{38}
\end{equation*}
$$

where $\tilde{\sigma}$ is the square root of the diagonal elements of $A \Sigma A^{\prime}$. It follows immediately from the definition of $\mathcal{B}_{0}$ and the function $\eta$ that we can write

$$
\begin{aligned}
& \mathcal{B}_{0}(\bar{\theta}, d)=\{\beta: \eta(\beta, A, d, \bar{\theta}, \Sigma) \leqslant 0\} \\
& \mathcal{B}_{0}(\sqrt{n} \bar{\theta}, \sqrt{n} d)=\{\beta: \eta(\beta, A, \sqrt{n} d, \sqrt{n} \bar{\theta}, n \Sigma) \leqslant 0\}
\end{aligned}
$$

As argued in the proof to Lemma B. 2 above, for any $n>0, \eta(\beta, A, d, \bar{\theta}, \Sigma)=\eta(\sqrt{n} \beta, A, \sqrt{n} d, \sqrt{n} \bar{\theta}, n \Sigma)$, from which it follows that $\sqrt{n} \mathcal{B}_{0}(\bar{\theta}, d)=\mathcal{B}_{0}(\sqrt{n} \bar{\theta}, \sqrt{n} d)$. Thus,

$$
\begin{aligned}
\tilde{\beta}_{2} & =\sqrt{n} \underset{\beta \in \mathcal{B}_{0}(\bar{\theta}, d)}{\arg \min }\left\|\sqrt{n} \beta_{A}-\sqrt{n} \beta\right\|_{(n \Sigma)} \\
& =\sqrt{n} \underset{\beta \in \mathcal{B}_{0}(\bar{\theta}, d)}{\arg \min }\left\|\beta_{A}-\beta\right\|_{\Sigma}=\sqrt{n} \tilde{\beta}_{1},
\end{aligned}
$$

where the second equality uses the fact that $\|\sqrt{n} x\|_{(n \Sigma)}=\|x\|_{\Sigma}$. Thus, the test statistic used for $\psi_{\alpha}^{M P}\left(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, \sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}\right)$ is

$$
\left(\sqrt{n} \beta_{A}-\tilde{\beta}_{2}\right)^{\prime}(n \Sigma)^{-1}(\sqrt{n} \hat{\beta})=\left(\sqrt{n} \beta_{A}-\sqrt{n} \tilde{\beta}_{1}\right)^{\prime}(n \Sigma)^{-1}(\sqrt{n} \hat{\beta})=\left(\beta_{A}-\tilde{\beta}_{1}\right)^{\prime} \Sigma^{-1} \hat{\beta}
$$

which is the test statistic used for $\psi_{\alpha}^{M P}\left(\hat{\beta} ; A, d, \bar{\theta}, \delta_{A}, \tau_{A}\right)$.
Likewise, the critical value used for $\psi_{\alpha}^{M P}\left(\sqrt{n} \hat{\beta} ; A, \sqrt{n} d, \sqrt{n} \bar{\theta}, \sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}\right)$ is

$$
\begin{aligned}
& \left(\sqrt{n} \beta_{A}-\tilde{\beta}_{2}\right)^{\prime}(n \Sigma)^{-1} \tilde{\beta}_{2}+z_{1-\alpha}\left\|\sqrt{n} \beta_{A}-\tilde{\beta}_{2}\right\|_{(n \Sigma)}= \\
& \left(\sqrt{n} \beta_{A}-\sqrt{n} \tilde{\beta}_{1}\right)^{\prime}(n \Sigma)^{-1} \sqrt{n} \tilde{\beta}_{1}+z_{1-\alpha}\left\|\sqrt{n} \beta_{A}-\sqrt{n} \tilde{\beta}_{1}\right\|_{(n \Sigma)}= \\
& \left(\beta_{A}-\tilde{\beta}_{1}\right)^{\prime} \Sigma^{-1} \tilde{\beta}_{1}+z_{1-\alpha}\left\|\beta_{A}-\tilde{\beta}_{1}\right\|_{\Sigma},
\end{aligned}
$$

which is the critical value used for $\psi_{\alpha}^{M P}\left(\hat{\beta} ; A, d, \bar{\theta}, \delta_{A}, \tau_{A}\right)$. We have thus shown that the test statistics and critical values for the two tests align, which gives the desired result.

Lemma B.7. Suppose Assumption 5 holds. Let $\theta^{u b}:=\sup _{\theta} \mathcal{S}\left(\Delta, \delta_{A}+\tau_{A}\right)$ and $\beta_{A}=\delta_{A}+\tau_{A}$.

Then there exists a vector $\tilde{\tau}^{u b} \in \mathbb{R}^{\bar{T}-1}$ such that for $B=B\left(\delta^{* *}\right)$ as defined in Assumption 5,

$$
\begin{aligned}
& A_{(B,)} \beta_{A}-d_{B}-\tilde{A}_{(B, 1)} \theta^{u b}-\tilde{A}_{(B,-1)} \tilde{\tau}^{u b}=0 \\
& A_{(-B, \cdot)} \beta_{A}-d_{-B}-\tilde{A}_{(-B, 1)} \theta^{u b}-\tilde{A}_{(-B, 1)} \tilde{\tau}^{u b}=-\epsilon<0,
\end{aligned}
$$

for $\epsilon$ a vector with strictly positive entries. Additionally, the matrix $\tilde{A}_{(B,-1)}$ has rank equal to $|B|-1$, and $\left\{\gamma_{B}: \gamma_{B}^{\prime} \tilde{A}_{(B,-1)}=0\right\}=\left\{c \bar{\gamma}_{B}: c \in \mathbb{R}\right\}$ for a non-zero vector $\bar{\gamma}_{B} \geqslant 0$.

Proof. From (6), we have that $\theta^{u b}=l^{\prime} \beta_{A, p o s t}-l^{\prime} \delta_{\text {post }}^{* *}$, for $\delta^{* *}$ a solution to

$$
\begin{equation*}
\min _{\delta} l^{\prime} \delta_{p o s t} \text { s.t. } A \delta \leqslant d, \delta_{p r e}=\delta_{A, p r e} \tag{39}
\end{equation*}
$$

Let $B=B\left(\delta^{* *}\right)$ index the binding inequalities of the optimization above at $\delta^{* *}$, so that

$$
\begin{align*}
& A_{(B, \cdot)} \delta^{* *}-d_{B}=0  \tag{40}\\
& A_{(-B, \cdot)} \delta^{* *}-d_{-B}=-\epsilon<0 \tag{41}
\end{align*}
$$

By Assumption 5, $A_{(B, p o s t)}$ has rank $|B|$.
Now, let $\tau^{* *}=\left(\delta_{A, p o s t}+\tau_{A, p o s t}\right)-\delta_{\text {post }}^{* *}$. Since by construction $\theta^{u b} \in \mathcal{S}_{\theta}\left(\Delta, \beta_{A}\right)$, we have

$$
\binom{\delta_{p r e}^{* *}}{\delta_{\text {post }}^{* *}+\tau^{* *}}=\binom{\delta_{A, p r e}}{\delta_{A, \text { post }}+\tau_{A, \text { post }}}=\beta_{A} .
$$

It follows that

$$
\begin{aligned}
A \delta^{* *} & =A \beta_{A}-A M_{p o s t} \tau^{* *} \\
& =A \beta_{A}-A M_{p o s t} \Gamma^{-1} \Gamma \tau^{* *} \\
& =A \beta_{A}-\tilde{A}_{(\cdot, 1)}\left(l^{\prime} \tau^{* *}\right)-\tilde{A}_{(\cdot,-1)} \Gamma_{(-1, \cdot)} \tau^{* *} \\
& =A \beta_{A}-\tilde{A}_{(\cdot, 1)}\left(\theta^{u b}\right)-\tilde{A}_{(\cdot,-1)} \tilde{\tau}^{u b},
\end{aligned}
$$

where the third equality uses the definition of $\tilde{A}$ and the fact that the first row of $\Gamma$ is $l^{\prime}$; and the fourth equality uses the fact that $\theta^{u b}=l^{\prime}\left(\left(\delta_{A, \text { post }}+\tau_{A, p o s t}\right)-\delta_{\text {post }}^{* *}\right)=l^{\prime} \tau^{* *}$ and defines $\tilde{\tau}^{u b}:=-\Gamma_{(-1, \cdot)} \tau^{* *}$. The first result then follows immediately from the previous display along with (40) and (41).

To show the second set of results, note that $\tilde{A}_{(B, \cdot)}=A_{(B, p o s t)} \Gamma^{-1}$. Since $A_{(B, p o s t)}$ has rank $|B|$ by assumption and $\Gamma^{-1}$ is full rank, $\tilde{A}_{(B, \cdot)}$ also has rank $|B|$. This implies that $\tilde{A}_{(B,-1)}$ has rank of either $|B|-1$ or $|B|$. To show that the rank must be $|B|-1$, note that the
optimization (39) can be re-written as

$$
\begin{equation*}
\min _{\delta_{\text {post }}} l^{\prime} \delta_{\text {post }} \quad \text { s.t. } \quad A_{(,, p o s t)} \delta_{\text {post }} \leqslant d-A_{(,, p r e)} \delta_{A, \text { pre }} . \tag{42}
\end{equation*}
$$

Since the optimization is assumed to have a finite solution, it is equivalent to its dual formulation,

$$
\max _{\gamma} \gamma^{\prime}\left(A_{(\cdot, p r e)} \delta_{A, p r e}-d\right) \text { s.t. }-\gamma^{\prime} A_{(\cdot, p o s t)}=l^{\prime}, \gamma \geqslant 0
$$

Let $\bar{\gamma}$ be a solution to the dual problem. Since $\bar{\gamma}$ is feasible in the dual, $-\bar{\gamma}^{\prime} A_{(\cdot, p o s t)}=$ $l^{\prime}$ and $\bar{\gamma} \geqslant 0$. Additionally, by the complementary slackness conditions, it must be that $\bar{\gamma}_{-B}=0$. Hence, we have $-\bar{\gamma}_{B}^{\prime} A_{(B, p o s t)}=l^{\prime}$. Multiplying on the right by $\Gamma^{-1}$, we obtain $-\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, \cdot)}=l^{\prime} \Gamma^{-1}$. Recall that by construction the first row of $\Gamma$ is $l^{\prime}$, so $l^{\prime}=e_{1}^{\prime} \Gamma$, and thus $-\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, \cdot)}=l^{\prime} \Gamma^{-1}=e_{1}^{\prime}$. This shows, however, that $\bar{\gamma}_{B}$ is in the nullspace of $\tilde{A}_{(B,-1)}^{\prime}$ but not in the null space of $\tilde{A}_{(B, \cdot)}^{\prime}$. It follows that the rank of $\tilde{A}_{(B,-1)}$ is strictly less than that of $\tilde{A}_{(B, \cdot)}$, and thus must be equal to $|B|-1$. Since $\tilde{A}_{(B,-1)}$ has $|B|$ rows and rank $|B|-1$, by the rank nullity theorem the set $\left\{\gamma_{B}: \gamma_{B}^{\prime} \tilde{A}_{(B,-1)}=0\right\}$ must be one dimensional. We've shown that $\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B,-1)}=0$, and $\bar{\gamma}_{B} \neq 0$ since $\bar{\gamma}_{B}^{\prime} A_{(B, p o s t)}=-l^{\prime} \neq 0$, which implies that $\left\{\gamma_{B}: \gamma_{B}^{\prime} \tilde{A}_{(B,-1)}=0\right\}=\left\{c \bar{\gamma}_{B}: c \in \mathbb{R}\right\}$, as needed.

Lemma B.8. Let $\Delta=\{\delta: A \delta \leqslant d\}$, and fix $\delta_{A} \in \Delta, \tau_{A}$, and $\Sigma^{*}$ positive definite. If Assumption 5 holds, then for any $x>0$,

$$
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)\right] \rightarrow 1-\Phi\left(z_{1-\alpha}-c^{*} x\right),
$$

where $\theta_{n}^{u b}:=\sup \mathcal{S}\left(\Delta_{n}, \sqrt{n} \delta_{A}+\sqrt{n} \tau_{A}\right), \Delta_{n}=\{\delta: A \delta \leqslant \sqrt{n} d\}$, and $c^{*}$ is a positive constant (not depending on $x$ or $\alpha$ ). In particular, $c^{*}=-\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)} / \sigma_{B}$, where $\sigma_{B}=$ $\sqrt{\bar{\gamma}_{B}^{\prime} A_{(B, \cdot)} \Sigma^{*} A_{(B,)}^{\prime} \bar{\gamma}_{B}}$ and $\bar{\gamma}_{B}$ is the unique vector such that $\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B,-1)}=0, \bar{\gamma}_{B} \geqslant 0,\left\|\bar{\gamma}_{B}\right\|=1$. Proof. From Lemma B.7, there exists a vector $\tilde{\tau}_{1}^{u b}$ and a set of indices $B$ such that

$$
\begin{align*}
& A_{(B,)} \beta_{A}-d_{B}-\tilde{A}_{(B, 1)} \theta_{1}^{u b}-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{u b}=0  \tag{43}\\
& A_{(-B, \cdot)} \beta_{A}-d_{-B}-\tilde{A}_{(-B, 1)} \theta_{1}^{u b}-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{u b}=-\epsilon<0, \tag{44}
\end{align*}
$$

and the set $\left\{\gamma_{B} \in \mathbb{R}^{|B|}: \gamma_{B}^{\prime} \tilde{A}_{(B,-1)}=0\right\}=\left\{c \bar{\gamma}_{B}: c \in \mathbb{R}\right\}$ for some non-zero vector $\bar{\gamma}_{B} \geqslant 0$, which without loss of generality we can normalize so that $\left\|\bar{\gamma}_{B}\right\|=1$. Let $\tilde{\sigma}$ be the vector containing the square roots of the diagonal elements of $A \Sigma^{*} A^{\prime}$. It follows that the set $\left\{\gamma_{B} \in \mathbb{R}^{|B|}: \gamma_{B}^{\prime} \tilde{A}_{(B,-1)}=0, \gamma_{B}^{\prime} \tilde{\sigma}_{B}=1, \gamma_{B} \geqslant 0\right\}$ is a singleton. In particular, its lone element is $\gamma_{B}^{*}:=\left(\tilde{\sigma}_{B}^{\prime} \bar{\gamma}_{B}\right)^{-1} \bar{\gamma}_{B}$. Note that $\left(\tilde{\sigma}_{B}^{\prime} \bar{\gamma}_{B}\right)^{-1}$ is well-defined since $\gamma_{B} \geqslant 0$ and has at least one
strictly positive element, and $\tilde{\sigma}>0$ since by assumption $A$ has no all-zero rows and $\Sigma^{*}$ is positive definite.

Now, consider $\psi_{\alpha}^{C}\left(\hat{\beta}_{n}, A_{(B, \cdot)}, \sqrt{n} d_{B}, \theta_{n}^{u b}+x, \Sigma^{*}\right)$, the conditional test that uses only the moments in $B$. The test statistic for the conditional test that uses only the moments in $B$ is

$$
\begin{aligned}
\eta\left(\hat{\beta}_{n}, A_{(B, \cdot)}, \sqrt{n} d_{B}, \theta_{n}^{u b}+x, \Sigma^{*}\right) & =\min _{\eta, \tilde{\tau}} \eta \\
& \text { s.t. } A_{(B, \cdot)} \hat{\beta}_{n}-\sqrt{n} d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{n}^{u b}+x\right)-\tilde{A}_{(B,-1)} \tilde{\tau} \leqslant \eta \tilde{\sigma}_{B} .
\end{aligned}
$$

The equivalent dual problem is

$$
\max _{\gamma_{B}} \gamma_{B}^{\prime} \tilde{Y}_{B, n} \text { s.t. } \gamma_{B}^{\prime} \tilde{A}_{(B,-1)}=0, \gamma_{B}^{\prime} \tilde{\sigma}_{B}=1, \gamma_{B} \geqslant 0
$$

where $\tilde{Y}_{B, n}=A_{(B, \cdot)} \hat{\beta}_{n}-\sqrt{n} d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{n}^{u b}+x\right)$. We have shown, however, that there is a single value, $\gamma_{B}^{*}$, that satisfies the constraints of the dual problem, and so the solution to the problem in the previous display is $\gamma_{B}^{*} \tilde{Y}_{B, n}$. Additionally, since the set of dual vertices is a singleton, the conditioning event that $\gamma_{B}^{*}$ is optimal is trivial, so $v^{l o}=-\infty$ and $v^{u p}=$ $\infty$. It follows that the conditional test using only the moments $B$ is a one-sided t-test that rejects for large values of $\gamma_{B}^{* *} \tilde{Y}_{B, n}$. Specifically, the critical value is $z_{1-\alpha} \sigma_{B}^{*}$, for $\sigma_{B}^{*}=$ $\sqrt{\gamma_{B}^{* \prime} A_{(B, \cdot)} \Sigma^{*} A_{(B, \cdot)}^{\prime} \gamma_{B}^{*}}$ the standard deviation of the test statistic $\gamma_{B}^{* \prime} \tilde{Y}_{B, n}$. We claim that $\sigma_{B}^{*}>0$. To see why this is the case, observe that Assumption 5 implies that $A_{(B, \cdot)}$ has full row rank, and by construction $\gamma_{B}^{*} \neq 0$, so $\gamma_{B}^{* \prime} A_{(B, \cdot)} \neq 0$. That $\sigma_{B}^{*}>0$ then follows from the fact that $\Sigma^{*}$ is positive definite.

Additionally, observe that

$$
\begin{aligned}
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\gamma_{B}^{* \prime} \tilde{Y}_{B, n}\right] & =\gamma_{B}^{* \prime}\left[A_{(B, \cdot)} \sqrt{n} \beta_{A}-\sqrt{n} d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{n}^{u b}+x\right)\right] \\
& =\gamma_{B}^{* \prime} \sqrt{n}\left[A_{(B, \cdot)} \beta_{A}-d_{B}-\tilde{A}_{(B, 1)} \theta_{1}^{u b}\right]-\gamma_{B}^{* \prime} \tilde{A}_{(B, 1)} x \\
& =\gamma_{B}^{* \prime}\left[\sqrt{n} \tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{u b}\right]-\gamma_{B}^{* \prime} \tilde{A}_{(B, 1)} x=-\gamma_{B}^{* \prime} \tilde{A}_{(B, 1)} x
\end{aligned}
$$

where the second equality uses $\theta_{n}^{u b}=\sqrt{n} \theta_{1}^{u b}$ from Lemma B.1, the third equality uses (43) to substitute for the term in brackets, and the final equality follows from the fact that $\gamma_{B}^{* \prime} \tilde{A}_{(B,-1)}=0$ by construction. Thus, regardless of $n$, the conditional test using only the moments in $B$ rejects with probability

$$
\begin{equation*}
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\alpha}^{C}\left(\hat{\beta}_{n}, A_{(B, \cdot)}, \sqrt{n} d_{B}, \theta_{n}^{u b}+x, \Sigma^{*}\right)\right]=1-\Phi\left(z_{1-\alpha}-\left(-\gamma_{B}^{* \prime} \tilde{A}_{(B, 1)} / \sigma_{B}^{*}\right) \cdot x\right) . \tag{45}
\end{equation*}
$$

Note also that we showed in the proof of Lemma B. 7 that $-\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, \cdot)}=e_{1}^{\prime}$, which implies
that $-\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)}=1$, and hence $c^{*}:=-\bar{\gamma}_{B}^{*} \tilde{A}_{(B, 1)} / \sigma_{B}^{*}>0$ since $\gamma_{B}^{*}$ is a positive multiple of $\bar{\gamma}_{B}$. Moreover, observe that if we define $\sigma_{B}=\sqrt{\bar{\gamma}_{B}^{\prime} A_{(B, \cdot)} \Sigma^{*} A_{(B,)}^{\prime} \bar{\gamma}_{B}}$, then $\bar{\gamma}_{B}^{*} / \sigma_{B}^{*}=\bar{\gamma}_{B} / \sigma_{B}$, so $c^{*}=-\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)} / \sigma_{B}$.

Recall that $\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)=\psi_{\alpha}^{C}\left(\tilde{Y}_{n}, A \Sigma^{*} A^{\prime}\right)$ for $\tilde{Y}_{n}=A \hat{\beta}_{n}-\sqrt{n} d-\tilde{A}_{(\cdot, 1)}\left(\theta_{n}^{u b}+\right.$ $x)$. Since the conditional test optimizes over $\tilde{\tau}$, and $\tilde{\tau}$ appears in this optimization only in the term $\tilde{A}_{(\cdot,-1)} \tilde{\tau}$, the result of the conditional test using $\tilde{Y}_{n}$ is equivalent to the result of the conditional test that replaces $\tilde{Y}_{n}$ with $\breve{Y}_{n}=\tilde{Y}_{n}-\tilde{A}_{(\cdot,-1)}\left(\sqrt{n} \tilde{\tau}_{1}^{u b}\right)$ (see Lemma 16 in ARP for a formal justification). That is, $\psi_{\alpha}^{C}\left(\tilde{Y}_{n}, A \Sigma^{*} A^{\prime}\right)=\psi_{\alpha}^{C}\left(\breve{Y}_{n}, A \Sigma^{*} A^{\prime}\right)$. The expectation of the elements of $\breve{Y}_{n}$ corresponding with the rows $B$ is

$$
\begin{aligned}
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\breve{Y}_{n, B}\right] & =A_{(B, \cdot)} \sqrt{n} \beta_{A}-\sqrt{n} d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{n}^{u b}+x\right)-\tilde{A}_{(B,-1)}\left(\sqrt{n} \tilde{\tau}_{1}^{u b}\right) \\
& =\sqrt{n}\left(A_{(B, \cdot)} \beta_{A}-d_{B}-\tilde{A}_{(B, 1)} \theta_{1}^{u b}-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{u b}\right)-\tilde{A}_{(B, 1)} x \\
& =-\tilde{A}_{(B, 1)} x,
\end{aligned}
$$

where the second line uses the fact that $\theta_{n}^{u b}=\sqrt{n} \theta_{1}^{u b}$ from Lemma B.1, and the third uses (43). Similarly, the expectation of the elements of $\breve{Y}_{n}$ corresponding to the rows other than $B$ is

$$
\begin{aligned}
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\breve{Y}_{n,-B}\right] & =A_{(-B,)} \sqrt{n} \beta_{A}-\sqrt{n} d_{-B}-\tilde{A}_{(-B, 1)}\left(\theta_{n}^{u b}+x\right)-\tilde{A}_{(-B, 1)}\left(\sqrt{n} \tilde{\tau}_{1}^{u b}\right) \\
& =\sqrt{n}\left(A_{(-B,))} \beta_{A}-d_{-B}-\tilde{A}_{(-B, 1)} \theta_{1}^{u b}-\tilde{A}_{(-B, 1)} \tilde{\tau}_{1}^{u b}\right)-\tilde{A}_{(-B, 1)} x \\
& =\sqrt{n}(-\epsilon)-\tilde{A}_{(-B, 1)} x,
\end{aligned}
$$

where the last line uses (44). Since $-\epsilon<0$, all of the elements of $\mathbb{E}\left[\breve{Y}_{n,-B}\right]$ converge to $-\infty$ as $n \rightarrow \infty$, whereas $\mathbb{E}\left[\breve{Y}_{n, B}\right]$ does not depend on $n$. It follows from Proposition 3 in ARP that the conditional test based on the full set of moments is equal to the conditional test that only uses the moments $B$ with probability approaching one,

$$
\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left(\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)=\psi_{\alpha}^{C}\left(\hat{\beta}_{n}, A_{(B, \cdot)}, \sqrt{n} d_{B}, \theta_{n}^{u b}+x, \Sigma^{*}\right)\right)=1
$$

This, combined with (45), gives the desired result.
Lemma B.9. Let $\mathcal{B}$ be a closed, convex subset of $\mathbb{R}^{K}$, and $\beta_{A} \notin \mathcal{B}$. Let $\tilde{\beta}=\arg \min _{\beta \in \mathcal{B}} \| \beta-$ $\beta_{A} \|_{\Sigma}$, where $\|x\|_{\Sigma}^{2}=x^{\prime} \Sigma^{-1} x$ for some positive definite matrix $\Sigma$. Then for any $\beta \in \mathcal{B}$, $\left(\tilde{\beta}-\beta_{A}\right)^{\prime} \Sigma^{-1}(\beta-\tilde{\beta}) \geqslant 0$.

Proof. Consider any $\beta \in \mathcal{B}$. Define $\beta_{\theta}=\theta(\beta-\tilde{\beta})+\tilde{\beta}$, and note that since $\mathcal{B}$ is convex $\beta_{\theta} \in \mathcal{B}$ for any $\theta \in[0,1]$. Further,

$$
\left\|\beta_{\theta}-\beta_{A}\right\|_{\Sigma}^{2}=\theta^{2}\|\beta-\tilde{\beta}\|_{\Sigma}^{2}+2 \theta\left(\tilde{\beta}-\beta_{A}\right)^{\prime} \Sigma^{-1}(\beta-\tilde{\beta})+\left\|\tilde{\beta}-\beta_{A}\right\|_{\Sigma}^{2} .
$$

Differentiating with respect to $\theta$, we have

$$
\frac{\partial}{\partial \theta}\left\|\beta_{\theta}-\beta_{A}\right\|_{\Sigma}^{2}=2 \theta\|\beta-\tilde{\beta}\|_{\Sigma}^{2}+2\left(\tilde{\beta}-\beta_{A}\right)^{\prime} \Sigma^{-1}(\beta-\tilde{\beta})
$$

from which we see that the derivative evaluated at $\theta=0$ is $2\left(\tilde{\beta}-\beta_{A}\right)^{\prime} \Sigma^{-1}\left(\beta_{A}-\tilde{\beta}\right)$. Since $\tilde{\beta}$ minimizes the norm, it follows that we must have $2\left(\tilde{\beta}-\beta_{A}\right)^{\prime} \Sigma^{-1}\left(\beta_{A}-\tilde{\beta}\right) \geqslant 0$, else we could achieve a lower value of the norm at $\beta_{\theta}$ by choosing $\theta$ sufficiently small.

Lemma B.10. Let $\mathcal{B}=\left\{\beta \in \mathbb{R}^{K}: v^{\prime} \beta \leqslant d\right\}$ for some $v \in \mathbb{R}^{K} \backslash\{0\}$ and $d \in \mathbb{R}$. Let $\tilde{\beta}=\arg \min _{\beta \in \mathcal{B}}\left\|\beta-\beta_{A}\right\|_{\Sigma}$ for some $\beta_{A} \notin \mathcal{B}$, where $\|x\|_{\Sigma}^{2}=x^{\prime} \Sigma^{-1} x$ and $\Sigma$ is positive definite. Then $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1}=c \cdot v^{\prime}$ for the positive constant $c=\frac{v^{\prime} \beta_{A}-d}{\sqrt{v^{\prime} \Sigma v}}$.

Proof. Note that we can form a basis $v, \tilde{v}_{2}, \ldots, \tilde{v}_{K}$ such that $v^{\prime} \tilde{v}_{j}=0$ for $j=2, \ldots, K$. It follows by construction that for any $j=2, . ., K$ and any $t \in \mathbb{R}, \tilde{\beta}+t \cdot \tilde{v}_{j} \in \mathcal{B}$. Hence, from Lemma B.9, $-\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1}\left(t \tilde{v}_{j}\right) \geqslant 0$. Since we can choose $t$ both positive and negative, it follows that $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1} \tilde{v}_{j}=0$ for all $j$. Since $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1}$ is orthogonal to $\left\{\tilde{v}_{2}, \ldots, \tilde{v}_{K}\right\}$, and $\left\{v, \tilde{v}_{2}, \ldots, \tilde{v}_{K}\right\}$ form a basis, we have that $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1}=c \cdot v^{\prime}$, for some $c \in \mathbb{R}$. Multiplying both sides of the equation on the right by $\Sigma v$, we obtain that $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} v=c \cdot v^{\prime} \Sigma v$. However, since $\tilde{\beta}$ is the closest point to $\beta_{A}$ in Mahalanobis distance, it must be on the boundary of $\mathcal{B}$, and so $v^{\prime} \tilde{\beta}=d$. It follows that $c=\left(v^{\prime} \beta_{A}-d\right) /\left(v^{\prime} \Sigma v\right)$, which is clearly positive since $\beta_{A} \notin \mathcal{B}$ and thus $v^{\prime} \beta_{A}>d$.

Lemma B.11. Let $\mathcal{B}=\left\{\beta \in \mathbb{R}^{K}: v^{\prime} \beta \leqslant d\right\}$ for some $v \in \mathbb{R}^{K} \backslash\{0\}$ and $d \in \mathbb{R}$. Suppose $\hat{\beta} \sim \mathcal{N}(\beta, \Sigma)$ for $\Sigma$ positive definite known, and consider the problem of testing $H_{0}: \beta \in$ $\mathcal{B}$ against $H_{A}: \beta=\beta_{A}$ for some $\beta_{A} \notin \mathcal{B}$. Then the most powerful size- $\alpha$ test of $H_{0}$ against $H_{A}$ is a one-sided t-test that rejects for large values of $v^{\prime} \hat{\beta}$, and has power equal to $\Phi\left(\left(v^{\prime} \beta_{A}-d\right) / \sqrt{v^{\prime} \Sigma v}-z_{1-\alpha}\right)$.

Proof. From Lemma B.5, the most powerful test rejects for large values of $\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1} \hat{\beta}$, where $\tilde{\beta}=\arg \min _{\beta \in \mathcal{B}}\left\|\beta-\beta_{A}\right\|_{\Sigma}$, and has power $\Phi\left(\left\|\beta_{A}-\tilde{\beta}\right\|_{\Sigma}-z_{1-\alpha}\right)$. By Lemma B.10,
$\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1}=c v^{\prime}$, for $c=\left(v^{\prime} \beta_{A}-d\right) /\left(v^{\prime} \Sigma v\right)$. It follows that

$$
\begin{aligned}
\left\|\beta_{A}-\tilde{\beta}\right\|_{\Sigma}^{2} & =\left(\beta_{A}-\tilde{\beta}\right)^{\prime} \Sigma^{-1}\left(\beta_{A}-\tilde{\beta}\right) \\
& =c v^{\prime}\left(\beta_{A}-\tilde{\beta}\right) \\
& =c\left(v^{\prime} \beta_{A}-d\right)=\left(v^{\prime} \beta_{A}-d\right)^{2} /\left(v^{\prime} \Sigma v\right),
\end{aligned}
$$

where we use the fact that $v^{\prime} \tilde{\beta}=d$, since $\tilde{\beta}$ must be on the boundary of $\mathcal{B}$, as argued in the proof to Lemma B.10. The result then follows immediately.

Lemma B.12. Let $\Delta=\{\delta: A \delta \leqslant d\}$, and fix $\delta_{A} \in \Delta$, $\tau_{A}$, and $\Sigma^{*}$ positive definite. If Assumption 5 holds, then for any $x>0$,

$$
\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\psi_{\alpha}^{M P}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)\right] \rightarrow 1-\Phi\left(z_{1-\alpha}-c^{*} x\right),
$$

where $\psi_{\alpha}^{M P}$ is as defined in the proof to Proposition 4.2, $\theta_{n}^{u b}:=\sup \mathcal{S}\left(\Delta_{n}, \sqrt{n} \delta_{A}+\sqrt{n} \tau_{A}\right)$, $\Delta_{n}=\{\delta: A \delta \leqslant \sqrt{n} d\}$, and $c^{*}$ is the same positive constant as in Lemma B.8.

Proof. As argued in the proof to Lemma B.6, the null hypothesis $H_{0}: \theta=\bar{\theta}, \delta \in\{A \delta \leqslant d\}$ is equivalent to the null $H_{0}: \beta \in \mathcal{B}_{0}(\bar{\theta}, d)=\left\{\beta: \exists \tau_{\text {post }}\right.$ s.t. $\left.l^{\prime} \tau_{\text {post }}=\bar{\theta}, A \beta-d-A M_{\text {post }} \tau_{\text {post }} \leqslant 0\right\}$, which we showed in Lemma B. 6 to be equivalent to $\mathcal{B}_{0}(\bar{\theta}, d)=\left\{\beta: \eta\left(\beta, A, d, \bar{\theta}, \Sigma^{*}\right) \leqslant 0\right\}$ for the function $\eta$ as defined in (38). Thus, the null hypothesis for the test associated with $\psi_{\alpha}^{M P}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)$ can be written as $H_{0}: \beta_{n} \in \mathcal{B}_{n, 0}:=\left\{\beta: \eta\left(\beta, A, \sqrt{n} d, \theta_{n}^{u b}+\right.\right.$ $\left.\left.x, \Sigma^{*}\right) \leqslant 0\right\}$. Under the alternative for this test, $\beta_{n}=\sqrt{n} \beta_{A}$, so by Lemma B. 5 the most powerful test uses the test statistic $\left(\sqrt{n} \beta_{A}-\tilde{\beta}_{n}\right)^{\prime} \Sigma^{*-1} \hat{\beta}_{n}$, where $\tilde{\beta}_{n}=\arg \min _{\beta \in \mathcal{B}_{n, 0}} \| \beta-$ $\sqrt{n} \beta_{A} \|_{\Sigma^{*}}$.

Now, from Lemma B.7, there exists a vector $\tilde{\tau}_{1}^{u b}$ and a set of indices $B$ such that

$$
\begin{align*}
& A_{(B,)} \beta_{A}-d_{B}-\tilde{A}_{(B, 1)} \theta_{1}^{u b}-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{u b}=0  \tag{46}\\
& A_{(-B, \cdot)} \beta_{A}-d_{-B}-\tilde{A}_{(-B, 1)} \theta_{1}^{u b}-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{u b}=-\epsilon<0, \tag{47}
\end{align*}
$$

where $\left\{\gamma_{B} \in \mathbb{R}^{|B|}: \gamma_{B}^{\prime} \tilde{A}_{(B,-1)}=0\right\}=\left\{c \bar{\gamma}_{B}: c \in \mathbb{R}\right\}$ for some non-zero vector $\bar{\gamma}_{B} \geqslant 0$. Define $\mathcal{B}_{n}^{B}:=\left\{\beta: \eta\left(\beta, A_{(B, \cdot)}, \sqrt{n} d_{B}, \theta_{n}^{u b}+x, \Sigma^{*}\right) \leqslant 0\right\}$, the analog to $\mathcal{B}_{n, 0}$ that restricts attention only to the set of moments $B$. By an argument analogous to that in the proof to Lemma B. 8 (replacing $\hat{Y}$ with $\mu$ ), we can show that $\eta\left(\beta, A_{(B, \cdot)}, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right)=\gamma_{B}^{* \prime} \mu_{B, n}(\beta)$, where $\mu_{B, n}(\beta)=A_{(B, \cdot)} \beta-\sqrt{n} d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{n}^{u b}+x\right)$ and $\gamma_{B}^{*}=\left(\bar{\gamma}_{B}^{\prime} \tilde{\sigma}\right)^{-1} \bar{\gamma}_{B}$. Note also that (46) implies that $\tilde{A}_{(B, 1)} \theta_{1}^{u b}=A_{(B, \cdot)} \beta_{A}-d_{B}-\tilde{A}_{(B,-1)} \tilde{\tau}^{u b}$. Substituting into the expression for $\mu_{B, n}(\beta)$ and using the fact that $\theta_{n}^{u b}=\sqrt{n} \theta_{1}^{u b}$ by Lemma B.1, we obtain $\mu_{B, n}(\beta)=$ $A_{(B,)}\left(\beta-\sqrt{n} \beta_{A}\right)-\tilde{A}_{(B, 1)} x+\sqrt{n} \tilde{A}_{(B,-1)} \tilde{\tau}^{u b}$. Since $\gamma_{B}^{* \prime} \tilde{A}_{(B,-1)}=0$ by construction, this
implies that $\gamma_{B}^{* \prime} \mu_{B, n}(\beta)=\gamma_{B}^{* \prime}\left(A_{(B, \cdot)}\left(\beta-\sqrt{n} \beta_{A}\right)-\tilde{A}_{(B, 1)} x\right)$. Hence,

$$
\begin{aligned}
\mathcal{B}_{n}^{B} & =\left\{\beta: \eta\left(\beta, A_{(B, \cdot)}, \sqrt{n} d, \theta_{n}^{u b}+x, \Sigma^{*}\right) \leqslant 0\right\} \\
& =\left\{\beta: \gamma_{B}^{* \prime}\left(A_{(B, \cdot)}\left(\beta-\sqrt{n} \beta_{A}\right)-\tilde{A}_{(B, 1)} x\right) \leqslant 0\right\} \\
& =\left\{\beta: \gamma_{B}^{* \prime}\left(A_{(B, \cdot)}\left(\left(\beta-(\sqrt{n}-1) \beta_{A}\right)-\beta_{A}\right)-\tilde{A}_{(B, 1)} x\right) \leqslant 0\right\} \\
& =\left\{\beta:\left(\beta-(\sqrt{n}-1) \beta_{A}\right) \in \mathcal{B}_{1}^{B}\right\}=(\sqrt{n}-1) \beta_{A}+\mathcal{B}_{1}^{B} .
\end{aligned}
$$

Now, define $\beta_{n}^{*}=\arg \min _{\beta \in \mathcal{B}_{n}^{B}}\left\|\beta-\sqrt{n} \beta_{A}\right\|_{\Sigma^{*}}$. The results above imply that

$$
\begin{aligned}
\beta_{n}^{*} & =\underset{\beta \in \mathcal{B}_{n}^{B}}{\arg \min }\left\|\beta-\sqrt{n} \beta_{A}\right\|_{\Sigma^{*}} \\
& =\underset{\beta \in(\sqrt{n}-1) \beta_{A}+\mathcal{B}_{1}^{B}}{\arg \min }\left\|\beta-\sqrt{n} \beta_{A}\right\|_{\Sigma^{*}} \\
& =(\sqrt{n}-1) \beta_{A}+\underset{\beta \in \mathcal{B}_{1}^{B}}{\arg \min }\|\underbrace{\beta+(\sqrt{n}-1) \beta_{A}-\sqrt{n} \beta_{A}}_{=\left(\beta-\beta_{A}\right)}\|_{\Sigma^{*}} \\
& =(\sqrt{n}-1) \beta_{A}+\beta_{1}^{*} .
\end{aligned}
$$

Observe that $\mathcal{B}_{n}^{B} \supseteq \mathcal{B}_{n, 0}$ since $\mathcal{B}_{n}^{B}$ is the set of values $\beta$ that are consistent with a subset of the moments used in $\mathcal{B}_{n, 0}$ (formally, $\eta\left(\beta, A_{(B, \cdot)}, \sqrt{n} d_{B} \theta_{n}^{u b}+x, \Sigma^{*}\right) \leqslant \eta\left(\beta, A, \sqrt{n} d \theta_{n}^{u b}+x, \Sigma^{*}\right)$ since the RHS minimizes the same objective function subject to additional constraints). Thus, $\beta_{n}^{*}=\tilde{\beta}_{n}$ iff $\beta_{n}^{*} \in \mathcal{B}_{n, 0}$. From the definition of $\mathcal{B}_{n, 0}$, this occurs iff there exists a value $\tilde{\tau}_{n}$ such that

$$
\begin{aligned}
& A_{(B,))} \beta_{n}^{*}-\sqrt{n} d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{n}^{u b}+x\right)-\tilde{A}_{(B,-1)} \tilde{\tau}_{n} \leqslant 0 \\
& A_{(-B, \cdot)} \beta_{n}^{*}-\sqrt{n} d_{-B}-\tilde{A}_{(-B, 1)} \sqrt{n}\left(\theta_{n}^{u b}+x\right)-\tilde{A}_{(B,-1)} \tilde{\tau}_{n} \leqslant 0
\end{aligned}
$$

Now, since $\beta_{1}^{*} \in \mathcal{B}_{1}^{B}$, there exists a value $\tilde{\tau}_{1}^{*}$ such that

$$
A_{(B, \cdot)} \beta_{1}^{*}-d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{1}^{u b}+x\right)-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{*} \leqslant 0 .
$$

It follows that

$$
\begin{aligned}
& A_{(B, \cdot)} \beta_{n}^{*}-\sqrt{n} d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{n}^{u b}+x\right)-\tilde{A}_{(B,-1)}\left(\tilde{\tau}_{1}^{*}+(\sqrt{n}-1) \tilde{\tau}_{1}^{u b}\right) \\
& =A_{(B,)} \beta_{1}^{*}-d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{1}^{u b}+x\right)-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{*}+(\sqrt{n}-1)\left[A_{(B, \cdot)} \beta_{A}-d_{B}-\tilde{A}_{(B, 1)} \theta_{1}^{u b}-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{u b}\right] \\
& =A_{(B, \cdot)} \beta_{1}^{*}-d_{B}-\tilde{A}_{(B, 1)}\left(\theta_{1}^{u b}+x\right)-\tilde{A}_{(B,-1)} \tilde{\tau}_{1}^{*} \leqslant 0,
\end{aligned}
$$

where the first equality uses the fact that $\theta_{n}^{u b}=\sqrt{n} \theta_{1}^{u b}$ by Lemma B. 1 and $\beta_{n}^{*}=\beta_{1}^{*}+(\sqrt{n}-$

1) $\beta_{A}$ as shown above, and the second equality uses (46).

Similarly, we have

$$
\begin{aligned}
& A_{(-B,)} \beta_{n}^{*}-\sqrt{n} d_{-B}-\tilde{A}_{(-B, 1)} \sqrt{n}\left(\theta_{n}^{u b}+x\right)-\tilde{A}_{(B,-1)}\left(\tilde{\tau}_{1}^{*}+(\sqrt{n}-1) \tilde{\tau}_{1}^{u b}\right)= \\
& =A_{(-B, \cdot)} \beta_{1}^{*}-d_{-B}-\tilde{A}_{(-B, 1)}\left(\theta_{1}^{u b}+x\right)-\tilde{A}_{(-B, 1)} \tilde{\tau}_{1}^{*}+ \\
& (\sqrt{n}-1)\left[A_{(-B, \cdot)} \beta_{A}-d_{-B}-\tilde{A}_{(-B, 1)} \theta_{1}^{u b}-\tilde{A}_{(-B, 1)} \tilde{\tau}_{1}^{u b}\right] \\
& =\left[A_{(-B, \cdot)} \beta_{1}^{*}-d_{-B}-\tilde{A}_{(-B, 1)}\left(\theta_{1}^{u b}+x\right)-\tilde{A}_{(-B, 1)} \tilde{\tau}_{1}^{*}\right]-(\sqrt{n}-1) \epsilon
\end{aligned}
$$

for $\epsilon$ a vector with strictly positive elements, where the first equality again uses that $\theta_{n}^{u b}=$ $\sqrt{n} \theta_{1}^{u b}$ and $\beta_{n}^{*}=\beta_{1}^{*}+(\sqrt{n}-1) \beta_{A}$, and the second equality uses (47). Since the term in brackets in the final expression in the previous display does not depend on $n$ and all elements of the final term go to $-\infty$, for $n$ sufficiently large the expression in the previous display will be less than or equal to 0 . Thus, for $n$ sufficiently large, $\beta_{n}^{*}=\tilde{\beta}_{n}$, and hence the MP test of $H_{0}: \beta \in \mathcal{B}_{n, 0}$ against $H_{A}: \beta=\sqrt{n} \beta_{A}$ is equivalent to the most powerful test of $H_{0}: \beta \in \mathcal{B}_{n}^{B}$ against $H_{A}: \beta=\sqrt{n} \beta_{A}$.

We showed earlier in the proof that $\mathcal{B}_{n}^{B}=\left\{\beta: v^{\prime} \beta \leqslant \bar{d}_{n}\right\}$, for $v=\gamma_{B}^{* \prime} A_{(B, \cdot)}$ and $\bar{d}_{n}=$ $\gamma_{B}^{* \prime} \tilde{A}_{(B, 1)} x+v^{\prime} \sqrt{n} \beta_{A}$. From Lemma B.11, the MP test of $H_{0}: \beta \in \mathcal{B}_{n}^{B}$ against $H_{A}: \beta=\beta_{A}$ has power equal to $\Phi\left(\left(v^{\prime} \sqrt{n} \beta_{A}-\bar{d}_{n}\right) /\left(v^{\prime} \Sigma^{*} v\right)-z_{1-\alpha}\right)$. Plugging in the definitions of $v$ and $\bar{d}$ and cancelling like terms, we obtain that the power of the test is $\Phi\left(-\gamma_{B}^{* \prime} \tilde{A}_{(B, 1)} x / \sigma_{B}^{*}-z_{1-\alpha}\right)$, for $\sigma_{B}^{*}=\sqrt{\gamma_{B}^{*} A_{(B, \cdot)} \Sigma^{*} A_{(B, \cdot)}^{\prime} \gamma_{B}^{*}}$, which coincides with the expression for the limiting power of the conditional test in Lemma B.8, as needed.

Lemma B.13. Let $\eta(\beta, A, d, \bar{\theta}, \Sigma)$ be as defined in (38). Fix $\Sigma^{*}$ positive definite. For any $\delta_{A}, \tau_{A}$, and d, let $\beta_{A}\left(\delta_{A}, \tau_{A}\right)=\delta_{A}+\tau_{A}$ and $\theta^{u b}\left(\delta_{A}, \tau_{A}, d\right)=\sup \mathcal{S}\left(\Delta, \delta_{A}+\tau_{A}\right)$ for $\Delta=\{\delta:$ $A \delta \leqslant d\}$. Let $\eta^{*}\left(x ; \delta_{A}, \tau_{A}, d\right):=\eta\left(\beta_{A}\left(\delta_{A}, \tau_{A}\right), A, d, \theta^{u b}\left(\delta_{A}, \tau_{A}, d\right)+x, \Sigma^{*}\right)$. Then there exists a scalar $c\left(\Sigma^{*}, A\right)>0$ such that $\eta^{*}\left(x ; \delta_{A}, \tau_{A}, d\right) \geqslant c\left(\Sigma^{*}, A\right) \cdot x$ for all $\delta_{A}, \tau_{A}$, and $d$.

Proof. Observe that $\eta\left(\beta_{A}, A, d, \bar{\theta}, x\right)$ is equivalent to the linear program

$$
\min _{\eta, \tau} \eta \text { s.t. } A \beta_{A}-d-A \tau \leqslant \eta \tilde{\sigma}, l^{\prime} \tau=\bar{\theta}
$$

The dual formulation for this problem is

$$
\max _{\gamma}\binom{\gamma_{A}}{\gamma_{\theta}}^{\prime}\binom{A \beta_{A}-d}{\bar{\theta}} \text { s.t. } \gamma_{A}^{\prime} A+\gamma_{\theta} l^{\prime}=0, \gamma_{A}^{\prime} \tilde{\sigma}=1, \gamma_{A} \geqslant 0
$$

where $\gamma_{A}$ is a vector with length equal to the number of rows of $A$, and $\gamma_{\theta}$ is a scalar. Note that the feasible set for the dual depends on $A$ and $\Sigma^{*}$ but not on $d, \delta_{A}$, or $\tau_{A}$. Let $V_{D}$ denote
the set of vertices of the dual, which is finite, and recall that maximizing over the feasible set is equivalent to maximizing over the set of vertices.

Now, we first claim that $\eta\left(\beta_{A}, A, d, \theta^{u b}, \Sigma^{*}\right)=0$. Note that since $\theta^{u b}$ is in the identified set, it must be that $\eta\left(\beta_{A}, A, d, \theta^{u b}, \Sigma^{*}\right) \leqslant 0$. Towards contradiction, suppose that $\eta\left(\beta_{A}, A, d, \theta^{u b}, \Sigma^{*}\right)=-\epsilon_{1}<0$. Then for all $\gamma=\binom{\gamma_{A}}{\gamma_{\theta}} \in V_{D}$,

$$
\binom{\gamma_{A}}{\gamma_{\theta}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}} \leqslant-\epsilon_{1} .
$$

Since $V_{D}$ is finite, $\bar{\gamma}_{\theta}:=\max _{\gamma \in V_{D}} \gamma_{\theta}$ is finite. But then for $\epsilon_{2}>0$,

$$
\binom{\gamma_{A}}{\gamma_{\theta}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}+\epsilon_{2}} \leqslant-\epsilon_{1}+\bar{\gamma}_{\theta} \epsilon_{2} .
$$

By choosing $\epsilon_{2}$ sufficiently small, we can make the upper bound in the previous display less than or equal to 0 . However, this implies that $\eta\left(\beta_{A}, A, d, \theta^{u b}+\epsilon_{2}, \Sigma^{*}\right) \leqslant 0$. But this in turn implies $\theta^{u b}+\epsilon_{2}$ is in the identified set, which contradicts $\theta^{u b}$ being maximal. Therefore, $\eta\left(\beta_{A}, A, d, \theta^{u b}, \Sigma^{*}\right)=0$.

Additionally, we claim that for $\bar{\theta}=\theta^{u b}$, there must be an optimal dual vertex with $\gamma_{\theta}>0$. Towards contradiction, suppose not. Then there exists $\epsilon_{3}>0$ such that for all $\gamma=\binom{\gamma_{A}}{\gamma_{\theta}} \in V_{D,+}:=\left\{\gamma \in V_{D}: \gamma_{\theta}>0\right\},\binom{\gamma_{A}}{\gamma_{\theta}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}}<-\epsilon_{3}$. Letting $\epsilon_{4}=$ $\epsilon_{3} / \max _{\gamma \in V_{D,+}} \gamma_{\theta}$, it follows that for all $\gamma \in V_{D,+},\binom{\gamma_{A}}{\gamma_{\theta}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}+\epsilon_{4}}<0$. Additionally, for $\gamma=\binom{\gamma_{A}}{\gamma_{\theta}} \in V_{D} \backslash V_{D,+}$, we have $\gamma_{\theta} \leqslant 0$, and so

$$
\binom{\gamma_{A}}{\gamma_{\theta}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}+\epsilon_{4}} \leqslant\binom{\gamma_{A}}{\gamma_{\theta}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}} \leqslant 0
$$

Thus, $\binom{\gamma_{A}}{\gamma_{\theta}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}+\epsilon_{4}} \leqslant 0$ for all $\gamma \in V_{D}$, and so $\eta\left(\beta_{A}, A, d, \theta^{u b}+\epsilon_{4}, \Sigma^{*}\right) \leqslant 0$. However, this implies that $\theta^{u b}+\epsilon_{4}$ is in the identified set, which contradicts $\theta^{u b}$ being maximal. Thus, there must be at least one $\gamma^{*} \in V_{D,+}$ such that

$$
\binom{\gamma_{A}^{*}}{\gamma_{\theta}^{*}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}}=0 .
$$

Since $\gamma^{*}$ remains feasible in the dual with $\bar{\theta}=\theta^{u b}+x$, it follows that $\eta\left(\beta_{A}, A, d, \theta^{u b}+x, \Sigma^{*}\right)$
is lower bounded by

$$
\binom{\gamma_{A}^{*}}{\gamma_{\theta}^{*}}^{\prime}\binom{A \beta_{A}-d}{\theta^{u b}+x}=\gamma_{\theta}^{*} \cdot x .
$$

Note that the choice of $\gamma^{*} \in V_{D,+}$ depended on $d, \delta_{A}$, and $\tau_{A}$. However, as noted earlier in the proof, the set $V_{D,+}$ depends on $A$ and $\Sigma^{*}$ but does not on $d, \delta_{A}, \tau_{A}$. Since $V_{D,+}$ is finite and $\gamma_{\theta}>0$ for all $\gamma \in V_{D,+}$, there is a value $c>0$ such that $\gamma_{\theta} \geqslant c$ for all $\gamma \in V_{D,+}$. Hence, $\eta^{*}\left(x ; \delta_{A}, \tau_{A}, d\right) \geqslant c \cdot x$ for all $\delta_{A}, \tau_{A}, d$, as needed.

Lemma B.14. Let $\alpha \in(0,1)$ and $c>z_{1-\alpha}$. Then there exists a unique constant $\zeta(c)>0$ such that

$$
\frac{\Phi(c)-\Phi(c-\zeta(c))}{1-\Phi(c-\zeta(c))}=1-\alpha
$$

Additionally, for any values $z_{l o}<z_{u p}$, with $z_{l o}$ and $z_{u p}$ potentially infinite-valued, and $\eta>$ $\max \left\{c, z_{l o}+\zeta(c)\right\}$,

$$
F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}(\eta)>1-\alpha,
$$

where $F_{\xi \mid \xi \in\left[z^{l o}, z^{u p}\right)}(\cdot)$ is the $C D F$ of $\xi \sim \mathcal{N}(0,1)$ truncated to $\left[z^{l o}, z^{u p}\right)$.
Proof. First, we show that $F_{\xi \mid \xi \in\left[z^{l o}, z^{u p}\right)}(t)$ is increasing in $t$ and decreasing in $z_{l o}$ and $z_{u p}$, and these comparative statics are strict for $t \in\left(z_{l o}, z_{u p}\right)$. To see this, note that

$$
F_{\xi \mid \xi \in\left[z^{l o}, z^{u p}\right)}(t)= \begin{cases}0 & \text { for } t \leqslant z_{l o} \\ \frac{\Phi(t)-\Phi\left(z_{l o}\right)}{\Phi\left(z_{u p}\right)-\Phi\left(z_{l o}\right)} & \text { for } t \in\left(z_{l o}, z_{u p}\right) \\ 1 & \text { for } t \geqslant z_{u p}\end{cases}
$$

It is immediate that $F_{\xi \mid \xi \in\left[z^{l o}, z^{u p}\right)}(t)$ is increasing in $t$ and decreasing in $z_{u p}$, and strictly so when $t \in\left(z_{l o}, z_{u p}\right)$. Additionally, we have

$$
\frac{\partial}{\partial z_{l o}} \frac{\Phi(t)-\Phi\left(z_{l o}\right)}{\Phi\left(z_{u p}\right)-\Phi\left(z_{l o}\right)}=\frac{-\phi\left(z_{l o}\right)\left(\Phi\left(z_{u p}\right)-\Phi(t)\right)}{\left(\Phi\left(z_{u p}\right)-\Phi\left(z_{l o}\right)\right)^{2}}
$$

which is clearly negative for $t \in\left(z_{l o}, z_{u p}\right)$, which gives the desired result for $z_{l o}$.
Next, consider the function

$$
f(\zeta)=\frac{\Phi(c)-\Phi(c-\zeta)}{1-\Phi(c-\zeta)}
$$

Observe that $f(0)=0$ and $\lim _{\zeta \rightarrow \infty} f(\zeta)=\Phi(c)>1-\alpha$. Additionally, the derivative in the
previous paragraph (with $z_{u p}=\infty$ ) implies that $\frac{d}{d \zeta} f(\zeta)>0$ for $\zeta>0$. It follows that there is a unique value $\zeta(c)>0$ such that

$$
f(c, \zeta(c))=\frac{\Phi(c)-\Phi(c-\zeta(c))}{1-\Phi(c-\zeta(c))}=1-\alpha
$$

which gives the first result.
Next, we claim that for $z_{l o} \in(-\infty, \infty)$ and $\zeta>0, F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}\left(z_{l o}+\zeta\right)$ is increasing in $z_{l o}$. To see why this is the case, note that

$$
F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}\left(z_{l o}+\zeta\right)=\frac{\Phi\left(z_{l o}+\zeta\right)-\Phi\left(z_{l o}\right)}{1-\Phi\left(z_{l o}\right)} .
$$

Differentiating with respect to $z_{l o}$, we obtain

$$
\frac{\phi\left(z_{l o}+\zeta\right)\left(1-\Phi\left(z_{l o}\right)\right)-\phi\left(z_{l o}\right)\left(1-\Phi\left(z_{l o}+\zeta\right)\right)}{\left[1-\Phi\left(z_{l o}\right)\right]^{2}}
$$

which is greater than zero iff

$$
\frac{\phi\left(z_{l o}+\zeta\right)}{1-\Phi\left(z_{l o}+\zeta\right)}>\frac{\phi\left(z_{l o}\right)}{1-\Phi\left(z_{l o}\right)}
$$

which holds since the normal hazard function is strictly increasing.
Now, suppose that $\eta>\max \left\{c, z_{l o}+\zeta(c)\right\}$. Then

$$
\begin{align*}
F_{\xi \mid \xi \in\left[z^{l o}, z^{u p}\right)}(\eta) & \geqslant F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}(\eta) \\
& >F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}\left(\max \left\{c, z_{l o}+\zeta(c)\right\}\right) \\
& =\max \left\{F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}(c), F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}\left(z_{l o}+\zeta(c)\right)\right\} \tag{48}
\end{align*}
$$

where the first inequality uses the fact that $F_{\xi \mid \xi \in\left[z^{l o}, z^{u p}\right)}(t)$ is decreasing in $z_{u p}$ and the second inequality uses the fact that $F_{\xi \mid \xi \in\left[z^{l o}, z^{u p}\right)}(t)$ is strictly increasing in $t$ when $t \in\left(z_{l o}, \infty\right)$, and that $\max \left\{c, z_{l o}+\zeta(c)\right\}>z_{l o}$ since $\zeta(c)>0$. The final equality again uses the fact that $F_{\xi \mid \xi \in\left[z^{l o}, z^{u p}\right)}(t)$ is increasing in $t$.

However, if $z_{l o} \leqslant c-\zeta(c)$, then

$$
F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}(c) \geqslant F_{\xi \mid \xi \in[c-\zeta(c), \infty)}(c)=1-\alpha,
$$

since we've shown that the expression on the left hand side is decreasing in $z_{l o}$. On the other hand, if $z_{l o} \geqslant c-\zeta(c)$, then

$$
F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}\left(z_{l o}+\zeta(c)\right) \geqslant F_{\xi \mid \xi \in[c-\zeta(c), \infty)}(c)=1-\alpha,
$$

since we've shown that $F_{\xi \mid \xi \in\left[z^{l o}, \infty\right)}\left(z_{l o}+\zeta\right)$ is increasing in $z_{l o}$. We have thus shown that the max on the right-hand side of (48) is at least $1-\alpha$, which gives the desired result.
Lemma B.15. For any $t \in \mathbb{R}, \int_{-\infty}^{t} \Phi(x) d x$ is finite. In particular, $\int_{-\infty}^{t} \Phi(x) d x=t \Phi(t)+\phi(t)$.
Proof. We have

$$
\begin{aligned}
\int_{-\infty}^{t} \Phi(x) d x & =\int_{-\infty}^{\infty} 1[x \leqslant t] \int_{-\infty}^{\infty} 1[s \leqslant x] \phi(s) d s d x \\
& =\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} 1[s \leqslant x \leqslant t] \phi(s) d s d x \\
& =\int_{-\infty}^{\infty}(t-s) 1[s \leqslant t] \phi(s) d s \\
& =t \int_{-\infty}^{\infty} 1[s \leqslant t] \phi(s) d s-\int_{-\infty}^{\infty} s 1[s \leqslant t] \phi(s) d s \\
& =t \Phi(t)-\Phi(t) \mathbb{E}[\xi \mid \xi \leqslant t, \xi \sim \mathcal{N}(0,1)]=t \Phi(t)-\Phi(t) \frac{-\phi(t)}{\Phi(t)}
\end{aligned}
$$

where the last line uses the formula for the mean of a truncated normal distribution. Note that we exchange the order of integration via Fubini's theorem, which is valid since the integrand is weakly positive everywhere and thus equal to its absolute value, and we've shown that the integral after switching the order is finite.
Lemma B.16. Suppose $\tilde{Y}(x) \sim \mathcal{N}(\tilde{\mu}(x), \tilde{\Sigma})$ for some $\tilde{\mu}(x)$ such that $\max _{\gamma \in V(\tilde{\Sigma})} \gamma^{\prime} \tilde{\mu}(x) \geqslant$ $x>0$, where $V(\tilde{\Sigma})$ is the set of vertices of the dual feasible set, $F=\left\{\gamma: \gamma \geqslant 0, \gamma^{\prime} \tilde{A}_{(,,-1)}=\right.$ $\left.0, \gamma^{\prime} \tilde{\sigma}=1\right\}$, and $\tilde{\sigma}$ contains the square root of the diagonal elements of $\tilde{\Sigma}$. Then there exists a function $\underline{\rho}(x, \tilde{\Sigma})$, not depending on $\tilde{\mu}(x)$, such that $\mathbb{E}\left[\psi_{\alpha}^{C}(\tilde{Y}(x), \tilde{\Sigma})\right] \geqslant \underline{\rho}(x, \tilde{\Sigma})$ and $\lim _{n \rightarrow \infty} \underline{\rho}(x, \tilde{\Sigma})=1$.
Proof. Recall that $\psi_{\alpha}^{C}$ is based on the solution to the dual problem, $\hat{\eta}=\max _{\gamma \in V(\tilde{\Sigma})} \gamma^{\prime} \tilde{Y}$. Specifically, $\psi_{\alpha}^{C}(\tilde{Y}, \tilde{\Sigma})=1$ iff

$$
\left.F_{\xi \mid \xi \in\left[v_{\gamma_{*}}^{l o}, v_{*}^{u p}\right]}\left(\hat{\eta} ; \gamma_{*}^{\prime} \tilde{\Sigma} \gamma_{*}\right)\right)>1-\alpha
$$

where $\gamma_{*}$ is an optimal solution to the dual $\left(\gamma_{*} \in \hat{V}\right)$, and $v^{l o}, v^{u p}$ are functions of $\gamma_{*}, \tilde{\Sigma}$, and a sufficient statistic $S_{\gamma_{*}}(\tilde{Y})$ that by construction is independent of $\gamma_{*}^{\prime} \tilde{Y}$. (In this proof only, we make the dependence of $v^{l o}$ and $v^{u p}$ on $\gamma_{*}$ explicit in the notation.) If $\gamma_{*}^{\prime} \Sigma \gamma_{*} \neq 0$, then using the standard formula for the CDF of a truncated normal distribution, we have that the conditional test rejects iff

$$
\begin{equation*}
\frac{\Phi\left(\hat{\eta} / \sigma_{\gamma_{*}}\right)-\Phi\left(z_{\gamma_{*}}^{l o}\right)}{\Phi\left(z_{\gamma_{*}}^{u p}\right)-\Phi\left(z_{\gamma_{*}}^{l o}\right)}>1-\alpha \tag{49}
\end{equation*}
$$

where $\sigma_{\gamma_{*}}=\sqrt{\gamma_{*}^{\prime} \tilde{\Sigma} \gamma_{*}}$ and $z_{\gamma_{*}}^{l o}=\hat{v}_{\gamma_{*}}^{l o} / \sigma_{\gamma_{*}}, z_{\gamma_{*}}^{u p}=\hat{v}_{\gamma_{*}}^{u p} / \sigma_{\gamma_{*}}$. By Lemma B.14, for any $c>z_{1-\alpha}$, (49) holds whenever $\hat{\eta} / \sigma_{\gamma_{*}}>\max \left\{c, z_{\gamma_{*}}^{l o}+\zeta(c)\right\}$, where $\zeta(c)$ is the unique value that solves

$$
\frac{\Phi(c)-\Phi(c-\zeta(c))}{1-\Phi(c-\zeta(c))}=1-\alpha
$$

Thus, when $\sigma_{\gamma_{*}} \neq 0, \psi_{\alpha}^{C}=1$ whenever $\eta / \sigma_{\gamma_{*}}>\max \left\{c, z_{\gamma_{*}}^{l o}+\zeta(c)\right\}$, or equivalently, whenever $\hat{\eta}>\sigma_{\gamma_{*}} c$ and $\hat{\eta} / \sigma_{\gamma_{*}}-z_{\gamma_{*}}^{l o}>\zeta(c)$. Additionally, if $\sigma_{\gamma_{*}}=0$, then $\psi_{\alpha}^{C}=1$ whenever $\hat{\eta}>0$.

Let $\bar{\sigma}=\max _{\gamma \in V(\tilde{\Sigma})} \sigma_{\gamma}$, which is finite since $V(\tilde{\Sigma})$ is finite. Then the preceding discussion implies that for any $c>\max \left\{z_{1-\alpha}, 0\right\}, \psi_{\alpha}^{C}=1$ whenever

1) $\hat{\eta}>\bar{\sigma} c, \mathrm{AND}$
2) $\exists \gamma_{*} \in \hat{V}$ such that either i) $\sigma_{\gamma_{*}}=0$, OR ii) $\sigma_{\gamma_{*}}>0$ and $\gamma_{*}^{\prime} \tilde{Y} / \sigma_{\gamma_{*}}-z_{\gamma_{*}}^{l o}>\zeta(c)$,
where for the second part of condition 2) we use the fact that $\hat{\eta}=\gamma_{*}^{\prime} \tilde{Y}$ when $\gamma_{*} \in \hat{V}$. Hence, $\psi_{\alpha}^{C}=0$ only if either
A) $\hat{\eta} \leqslant \bar{\sigma} c$, OR
B) $\exists \gamma_{*} \in \hat{V}$ such that $\sigma_{\gamma_{*}}>0$ and $\gamma_{*}^{\prime} \tilde{Y} / \sigma_{\gamma_{*}}-z_{\gamma_{*}}^{l o} \leqslant \zeta(c)$.

Now, by assumption there exists some $\bar{\gamma} \in V(\tilde{\Sigma})$ such that $\bar{\gamma}^{\prime} \tilde{\mu}(x) \geqslant x$. Since $\bar{\gamma}$ is feasible in the dual problem for $\hat{\eta}$, we see that $\hat{\eta}$ is lower bounded by $\bar{\gamma}^{\prime} \tilde{Y}$, which is distributed $\mathcal{N}\left(\bar{\gamma}^{\prime} \tilde{\mu}(x), \sigma_{\tilde{\gamma}}^{2}\right)$. Thus, the probability that condition A) holds is bounded above by the probability that $\bar{\gamma}^{\prime} \tilde{Y} \leqslant \bar{\sigma} c$. If $\sigma_{\bar{\gamma}}=0$, then the probability condition A) holds is 0 so long as $c<\frac{x}{\bar{\sigma}}$. If $\sigma_{\bar{\gamma}}>0$, then $\mathbb{P}\left(\bar{\gamma}^{\prime} \tilde{Y} \leqslant \bar{\sigma} c\right)=\Phi\left(\frac{\bar{\sigma} c-\bar{\gamma}^{\prime} \tilde{\mu}(x)}{\sigma_{\bar{\gamma}}}\right)$. If $\sigma_{\bar{\gamma}}>0$, then the set $V^{+}(\tilde{\Sigma}):=\left\{\gamma \in V(\tilde{\Sigma}) ; \sigma_{\gamma}>0\right\}$ is non-empty. In this case, let $\underline{\sigma}=\min _{\gamma \in V^{+}} \sigma_{\gamma}$ and note that $\underline{\sigma}>0$ since $V^{+}$is finite. Then

$$
\Phi\left(\frac{\bar{\sigma} c-\bar{\gamma}^{\prime} \tilde{\mu}(x)}{\sigma_{\bar{\gamma}}}\right) \leqslant \Phi\left(\frac{\bar{\sigma} c-x}{\sigma_{\bar{\gamma}}}\right) \leqslant \Phi\left(\frac{\bar{\sigma}}{\underline{\sigma}} c-\frac{x}{\bar{\sigma}}\right)
$$

where we use the fact that $\Phi(\cdot)$ is increasing, $c \geqslant 0$ and $\bar{\gamma}^{\prime} \tilde{\mu}(x) \geqslant x>0$. Thus, if $c<\frac{x}{\bar{\sigma}}$, we have that condition A) holds with probability bounded above by $\Phi\left(\frac{\bar{\sigma}}{\underline{\sigma}} c-\frac{x}{\bar{\sigma}}\right)$.

Now, the probability that condition B) holds is equal to

$$
\begin{aligned}
& \mathbb{P}\left(\exists \gamma_{*} \in \hat{V} \text { s.t. } \sigma_{\gamma_{*}}>0 \text { and } \gamma_{*}^{\prime} \tilde{Y} / \sigma_{\gamma_{*}}-z_{\gamma_{*}}^{l o} \leqslant \zeta(c)\right)= \\
& \mathbb{P}\left(\exists \gamma_{*} \in \hat{V} \text { s.t. } \sigma_{\gamma_{*}}>0 \text { and }\left|\gamma_{*}^{\prime} \tilde{Y} / \sigma_{\gamma_{*}}-z_{\gamma_{*}}^{l o}\right| \leqslant \zeta(c)\right) \leqslant \\
& \mathbb{P}\left(\exists \gamma_{+} \in V^{+} \text {s.t. }\left|\gamma_{+}^{\prime} \tilde{Y} / \sigma_{\gamma_{+}}-z_{\gamma_{+}}^{l o}\right| \leqslant \zeta(c)\right) \leqslant \\
& \quad \sum_{\gamma_{+} \in V^{+}} \mathbb{P}\left(\left|\gamma_{+}^{\prime} \tilde{Y} / \sigma_{\gamma_{+}}-z_{\gamma_{+}}^{l o}\right| \leqslant \zeta(c)\right) .
\end{aligned}
$$

The equality above uses the fact that $\gamma_{*} \in \hat{V}$ implies that $\gamma_{*}^{\prime} \tilde{Y} / \sigma_{\gamma_{*}}-z_{\gamma_{*}}^{l o} \geqslant 0$ since $\hat{\eta} \geqslant v^{l o}$ by construction; and the remaining inequalities follow from standard properties of probability. Next, observe that $\gamma_{+}^{\prime} \tilde{Y} / \sigma_{\gamma_{+}}$is normally distributed with variance 1 for every $\gamma_{+} \in V^{+}(\tilde{\Sigma})$. Additionally, the random variable $z_{\gamma_{+}}^{l o}$ is by construction independent of $\gamma_{+}^{\prime} \tilde{Y} / \sigma_{\gamma_{+}}$. However, for any variable $\xi$ that is normally distributed with variance 1 and any variable $Z$ independent of $\xi$,

$$
\begin{aligned}
\mathbb{P}_{(\xi, Z)}(|\xi-Z| \leqslant \zeta) & =\mathbb{E}_{Z}\left[\mathbb{P}_{\xi \mid Z}(\xi \in[z-\zeta, z+\zeta] \mid Z=z)\right] \\
& \leqslant \max _{v \in \mathbb{R}} \mathbb{P}_{\xi}(\xi \in[v-\zeta, v+\zeta])=\Phi(\zeta)-\Phi(-\zeta)
\end{aligned}
$$

where the first equality follows from iterated expectations, the inequality uses the fact that the distribution of $\xi$ is independent of $Z$, and the final equality uses the fact that the normal distribution is single-peaked at its mean, so the maximal probability that a normal distribution with variance 1 falls in an interval of length $2 \zeta$ is $\Phi(\zeta)-\Phi(-\zeta)$. Additionally, observe that $\Phi(\zeta)-\Phi(-\zeta)=\int_{-\zeta}^{\zeta} \phi(t) d t \leqslant 2 \phi(0) \zeta$. It follows that for any constant $c>$ $\max \left\{z_{1-\alpha}, 0\right\}$, the probability condition B) holds is bounded above by $\kappa \zeta(c)$, where we define the constant $\kappa=2\left|V^{+}\right| \phi(0)$.

Since $\psi_{\alpha}^{C}=0$ only if either condition A) or condition B) holds, the probability that $\psi_{\alpha}^{C}=0$ is bounded above by $\Phi\left(\frac{\bar{\sigma}}{\underline{\sigma}} c-\frac{x}{\bar{\sigma}}\right)+\kappa \zeta(c)$, for any $c \in\left[\max \left\{z_{1-\alpha}, 0\right\}, \frac{x}{\bar{\sigma}}\right)$. Let $c(x)=c_{0} \cdot x$ for $c_{0}=\frac{1}{2} \frac{\underline{\sigma}}{\bar{\sigma}^{2}}$. Note that $c(x)>\max \left\{z_{1-\alpha}, 0\right\}$ for $x>\max \left\{z_{1-\alpha} / c_{0}, 0\right\}=: x_{\min }$. Note also that $c_{0}=\frac{1}{2} \frac{\sigma}{\bar{\sigma}} \frac{1}{\bar{\sigma}}<\frac{1}{\bar{\sigma}}$, so $c(x)<\frac{1}{\bar{\sigma}} x$. For $x>x_{\text {min }}$, we then have that the probability $\psi_{\alpha}^{C}=0$ is bounded above by $\Phi\left(-\frac{1}{2 \bar{\sigma}} x\right)+\kappa \zeta\left(c_{0} x\right)$.

Define $\underline{\rho}(x, \tilde{\Sigma})=1-\Phi\left(-\frac{1}{2 \bar{\sigma}} x\right)-\kappa \zeta\left(c_{0} x\right)$ for $x>x_{\text {min }}$ and $\underline{\rho}(x, \tilde{\Sigma})=0$ otherwise. By construction, $\mathbb{E}\left[\psi_{\alpha}^{C}(\tilde{Y}, \tilde{\Sigma})\right] \geqslant \underline{\rho}(x, \tilde{\Sigma})$. Note that as $x \rightarrow \infty, \Phi\left(-\frac{1}{2 \bar{\sigma}} x\right) \rightarrow 0$. To complete the proof that $\underline{\rho} \rightarrow 1$, we show that $\kappa \zeta(c) \rightarrow 0$ as $c \rightarrow \infty$. To show this, observe that for any
$\epsilon>0$, by L'Hospitale's rule,

$$
\begin{aligned}
\lim _{c \rightarrow \infty} \frac{\Phi(c)-\Phi(c-\epsilon)}{1-\Phi(c-\epsilon)} & =\lim _{c \rightarrow \infty} \frac{\phi(c)-\phi(c-\epsilon)}{-\phi(c-\epsilon)} \\
& =1-\lim _{c \rightarrow \infty} \frac{\phi(c)}{\phi(c-\epsilon)} \\
& =1-\lim _{c \rightarrow \infty} \exp \left(-\frac{1}{2}\left(2 c \epsilon-\epsilon^{2}\right)\right)=1 .
\end{aligned}
$$

Additionally, as shown in the proof to Lemma B.14, $\frac{\Phi(c)-\Phi(c-\zeta)}{1-\Phi(c-\zeta)}$ is increasing in $\zeta$. It is then immediate that $\limsup _{c \rightarrow \infty} \zeta(c)<\epsilon$ for all $\epsilon>0$, and hence $\lim _{c \rightarrow \infty} \zeta(c)=0$.

Lemma B.17. Suppose $\tilde{Y}(x) \sim \mathcal{N}(\tilde{\mu}, \tilde{\Sigma})$ for some $\tilde{\mu}(x)$ such that $\max _{\gamma \in V(\tilde{\Sigma})} \gamma^{\prime} \tilde{\mu}(x) \geqslant x>$ 0 , where $V(\tilde{\Sigma})$ is the set of vertices of the dual feasible set, $F=\left\{\gamma: \gamma \geqslant 0, \gamma^{\prime} \tilde{A}_{(\cdot,-1)}=\right.$ $\left.0, \gamma^{\prime} \tilde{\sigma}=1\right\}$, and $\tilde{\sigma}$ contains the square root of the diagonal elements of $\tilde{\Sigma}$. Then there exists a function $\underline{\rho}(x, \tilde{\Sigma})$, not depending on $\tilde{\mu}(x)$, such that $\mathbb{E}\left[\psi_{\kappa, \alpha}^{C-F L C I}(\tilde{Y}(x), \tilde{\Sigma})\right] \geqslant \underline{\rho}(x, \tilde{\Sigma})$ and $\lim _{n \rightarrow \infty} \underline{\rho}(x, \tilde{\Sigma})=1$.

Proof. The proof is nearly identical to that of Lemma B.16. In particular, by analogous argument we can show that the test $\psi_{\kappa, \alpha}^{C-F L C I}=0$ only if A) $\hat{\eta} \leqslant \bar{\sigma} c_{\tilde{\alpha}}$, or B) $\exists \gamma_{*} \in \hat{V}$ such that $\sigma_{\gamma_{*}}>0$ and $0 \leqslant \gamma_{*}^{\prime} \tilde{Y} / \sigma_{\gamma_{*}}-z_{C-F L C I, \gamma_{*}}^{l o} \leqslant \zeta\left(c_{\tilde{\alpha}}\right)$, where $z_{C-F L C I, \gamma_{*}}^{l o}=v_{C-F L C I, \gamma_{*}}^{l o} / \sigma_{\gamma_{*}}$, and $c_{\tilde{\alpha}}$ solves $\frac{\Phi\left(c_{\tilde{\alpha}}\right)-\Phi\left(c_{\tilde{\alpha}}-\zeta\left(c_{\tilde{\alpha}}\right)\right)}{1-\Phi\left(c_{\tilde{\alpha}}-\zeta\left(c_{\tilde{\alpha}}\right)\right)}=1-\tilde{\alpha}$. Noting that $z_{C-F L C I, \gamma_{*}}^{l o}$ is independent of $\gamma_{*}^{\prime} \tilde{Y}$, we can then obtain upper bounds on the probability that conditions A) or B) hold by an analogous argument to that in the proof to Lemma B.16.

Lemma B.18. Let $\Delta=\{\delta: A \delta \leqslant d\}$, and let $\theta^{u b}(\Delta, \beta):=\sup \mathcal{S}(\Delta, \beta)$. Then there exists a function $\rho_{L B}(\cdot, \cdot)$ such that for any $\delta \in \Delta, \tau, \Sigma^{*}$, and $x>0$,

$$
\mathbb{E}_{\left(\delta, \tau, \Sigma^{*}\right)}\left[\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, d, \theta^{u b}(\Delta, \delta+\tau)+x, \Sigma^{*}\right)\right] \geqslant \rho_{L B}\left(x, \Sigma^{*}\right),
$$

and for any $\Sigma^{*}$ fixed, $\rho_{L B}\left(x, \Sigma^{*}\right) \rightarrow 1$ as $x \rightarrow \infty$. Analogously, there exists a function $\tilde{\rho}_{L B}(\cdot, \cdot)$ such that for any $\delta \in \Delta, \tau, \Sigma^{*}$, and $x>0$,

$$
\mathbb{E}_{\left(\delta, \tau, \Sigma^{*}\right)}\left[\psi_{\kappa, \alpha}^{C-F L C I}\left(\hat{\beta}_{n} ; A, d, \theta^{u b}(\Delta, \delta+\tau)+x, \Sigma^{*}\right)\right] \geqslant \tilde{\rho}_{L B}\left(x, \Sigma^{*}\right),
$$

and for any $\Sigma^{*}$ fixed, $\tilde{\rho}_{L B}\left(x, \Sigma^{*}\right) \rightarrow 1$ as $x \rightarrow \infty$.

Proof. Lemma B. 13 implies that there exists a scalar $c\left(\Sigma^{*}, A\right)>0$ such that

$$
c\left(\Sigma^{*}, A\right) \cdot x \leqslant \eta^{*}\left(x ; \delta, \tau, \Sigma^{*}\right):=\min _{\eta, \tilde{\tau}} \eta \text { s.t. } \underbrace{A \beta-d-\tilde{A}_{(\cdot, 1)}\left(\theta^{u b}+x\right)}_{:=\tilde{\mu}}-\tilde{A}_{(\cdot,-1)} \tilde{\tau} \leqslant \eta \tilde{\sigma},
$$

where $\beta=\delta+\tau$. Reformulating the minimization above in terms of its dual, we have that $c\left(\Sigma^{*}, A\right) \cdot x \leqslant \max _{\gamma \in V\left(\tilde{\Sigma}^{*}\right)} \gamma^{\prime} \tilde{\mu}$, where $V\left(\tilde{\Sigma}^{*}\right)$ is the set of vertices of $F=\left\{\gamma^{\prime} \tilde{A}_{(\cdot,-1)}=0, \gamma^{\prime} \tilde{\sigma}=\right.$ $0, \gamma \geqslant 0\}$. Next, recall that by definition, $\psi_{\alpha}^{C}\left(\hat{\beta} ; A, d, \bar{\theta}, \Sigma^{*}\right)=\psi_{\alpha}^{C}\left(\tilde{Y}(\hat{\beta}, A, d, \bar{\theta}), A \Sigma^{*} A^{\prime}\right)$, where $\tilde{Y}(\hat{\beta}, A, d, \bar{\theta})=A \hat{\beta}-d-\tilde{A}_{(\cdot,-1)} \bar{\theta}$. Observe that $\mathbb{E}_{\left(\delta, \tau, \Sigma^{*}\right)}[\tilde{Y}(\hat{\beta}, A, d, \bar{\theta})]=\tilde{\mu}$. Lemma B. 16 then implies that there exists a function $\underline{\rho}(\cdot, \cdot)$ such that

$$
\mathbb{E}_{\left(\delta, \tau, \Sigma^{*}\right)}\left[\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, d, \theta^{u b}(\Delta, \delta+\tau)+x, \Sigma^{*}\right)\right] \geqslant \underline{\rho}\left(c\left(\Sigma^{*}, A\right) \cdot x, A \Sigma^{*} A^{\prime}\right)
$$

and $\underline{\rho}\left(\tilde{x}, A \Sigma^{*} A^{\prime}\right) \rightarrow 1$ as $\tilde{x} \rightarrow \infty$. The first desired result then follows by defining $\rho_{L B}\left(x, \Sigma^{*}\right):=$ $\underline{\rho}\left(c\left(\Sigma^{*}, A\right) \cdot x, A \Sigma^{*} A^{\prime}\right)$. The second desired result follows from an analogous argument, appealing to Lemma B. 17 instead of Lemma B.16.

Lemma B.19. For any $(a, v), \bar{b}(a, v) \geqslant \frac{1}{2} \sup _{\delta_{p r e} \in \Delta_{p r e}} L I D\left(\Delta, \delta_{\text {pre }}\right)$.
Proof. Since $\beta=\delta+\tau$, we can write the bias of the affine estimator $a+v^{\prime} \hat{\beta}$ as $b=a+$ $v^{\prime} \delta+\left(v_{\text {post }}-l\right)^{\prime} \tau_{\text {post }}$. Since $\tau_{\text {post }}$ is unrestricted in the maximization in (11), we see that the worst-case bias will be infinite if $v_{\text {post }} \neq l$ and the lemma holds trivially. We can thus restrict attention to affine estimators with $v_{\text {post }}=l$, in which case the worst-case bias reduces to

$$
\begin{equation*}
\bar{b}(a, v)=\sup _{\delta \in \Delta}\left|a+v^{\prime} \delta\right|=\sup _{\delta \in \Delta}\left|a+v_{p r e}^{\prime} \delta_{p r e}+l^{\prime} \delta_{p o s t}\right| . \tag{50}
\end{equation*}
$$

Now, pick any $\delta_{p r e}^{*} \in \Delta_{\text {pre }}$. First, suppose that the minimum $\left(\min _{\delta} l^{\prime} \delta_{\text {post }}\right.$, s.t. $\left.\delta \in \Delta, \delta_{\text {pre }}=\delta_{p r e}^{*}\right)$ and the equivalent maximum $\left(\max _{\delta} l^{\prime} \delta_{p o s t}\right.$, s.t. $\left.\delta \in \Delta, \delta_{p r e}=\delta_{p r e}^{*}\right)$ are finite. Let $\delta^{\min }$ and $\delta^{\text {max }}$ be the associated solutions. By construction, $\delta_{p r e}^{\max }=\delta_{p r e}^{\text {min }}=\delta_{p r e}^{*}$. For any $v_{p r e}$, we apply the triangle inequality to show that

$$
\begin{aligned}
\left|a+v_{\text {pre }}^{\prime} \delta_{\text {pre }}^{m a x}+l^{\prime} \delta_{\text {post }}^{\max }\right|+\left|a+v_{\text {pre }}^{\prime} \delta_{\text {pre }}^{\min }+l^{\prime} \delta_{\text {post }}^{\min }\right| & \geqslant\left|\left(a+v_{\text {pre }}^{\prime} \delta_{\text {pre }}^{\max }+l^{\prime} \delta_{\text {post }}^{\max }\right)-\left(a+v_{\text {pre }}^{\prime} \delta_{\text {pre }}^{\min }+l^{\prime} \delta_{\text {post }}^{\min }\right)\right| \\
& =\left|l^{\prime} \delta_{\text {post }}^{\max }-l^{\prime} \delta_{\text {post }}^{\min }\right|=L I D\left(\Delta, \delta_{\text {pre }}^{*}\right) .
\end{aligned}
$$

Note that for any $x_{1}, x_{2} \geqslant 0, \max \left\{x_{1}, x_{2}\right\} \geqslant \frac{1}{2}\left(x_{1}+x_{2}\right)$. It then follows from the previous display that

$$
\max \left\{\left|a+v_{\text {pre }}^{\prime} \delta_{\text {pre }}^{\max }+l^{\prime} \delta_{\text {post }}^{\max }\right|,\left|a+v_{\text {pre }}^{\prime} \delta_{\text {pre }}^{\min }+l^{\prime} \delta_{\text {post }}^{\min }\right|\right\} \geqslant \frac{1}{2} L I D\left(\Delta, \delta_{\text {pre }}^{*}\right) .
$$

Since $\delta_{p r e}^{\max }$ and $\delta_{p r e}^{\min }$ are feasible in the maximization (50), we see that $\bar{b} \geqslant \frac{1}{2} L I D\left(\Delta, \delta_{p r e}^{*}\right)$, as needed. To complete the proof, now suppose without loss of generality that $\left(\max _{\delta} l^{\prime} \delta_{\text {post }}\right.$, s.t. $\delta \in \Delta, \delta_{\text {pre }}=\delta$ $\infty$. Then, we can replay the argument above replacing $\delta^{\max }$ with a sequence of values $\left\{\delta_{j}\right\}$ such that $l^{\prime} \delta_{j}$ diverges, which gives that $\bar{b}$ is infinite and the result follows.

Lemma B.20. Suppose $\Delta$ is convex. Suppose there exists $\delta \in \Delta$ such that LID $\left(\Delta, \delta_{\text {pre }}\right)=$ $\sup _{\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}} \operatorname{LID}\left(\Delta, \tilde{\delta}_{\text {pre }}\right)<\infty$. Then there exists $(a, v)$ such that $\bar{b}(a, v)=\frac{1}{2} \sup _{\tilde{\delta}_{p r e} \in \Delta_{\text {pre }}} L I D\left(\Delta, \tilde{\delta}_{\text {pre }}\right)$. Additionally, for any $\tau$ and $\Sigma_{n}, \mathbb{E}_{\left(\delta, \tau, \Sigma_{n}\right)}\left[a+v^{\prime} \hat{\beta}_{n}\right]=\frac{1}{2}\left(\theta^{u b}+\theta^{l b}\right)$, where $\theta^{\text {ub }}$ and $\theta^{\text {lb }}$ are the upper and lower bounds of the identified set $\mathcal{S}(\Delta, \delta+\tau)$.

Proof. Let $b^{\max }\left(\delta_{p r e}^{*}\right):=\left(\max _{\delta} l^{\prime} \delta_{\text {post }}\right.$, s.t. $\left.\delta \in \Delta, \delta_{\text {pre }}=\delta_{\text {pre }}^{*}\right)$, where we define $b^{\max }=-\infty$ if $\delta_{p r e}^{*} \notin \Delta_{\text {pre }}$. Likewise, define $b^{\min }\left(\delta_{p r e}^{*}\right):=\left(\min _{\delta} l^{\prime} \delta_{p o s t}\right.$, s.t. $\left.\delta \in \Delta, \delta_{p r e}=\delta_{p r e}^{*}\right)$, where we define $b^{\text {min }}=\infty$ if $\delta_{\text {pre }}^{*} \notin \Delta_{\text {pre }}$. Note that $\Delta$ convex implies that $b^{\text {max }}$ is concave and $b^{\text {min }}$ is convex. Thus, $-L I D\left(\delta_{p r e}^{*}\right)=b^{\min }\left(\delta_{p r e}^{*}\right)-b^{\max }\left(\delta_{p r e}^{*}\right)$ is convex (where we define $\operatorname{LID}\left(\delta_{p r e}^{*}\right)=-\infty$ if $\left.\delta_{p r e}^{*} \notin \Delta_{p r e}\right)$. The domain of $-\operatorname{LID}\left(\delta_{p r e}^{*}\right)$ (i.e. the set of values for which it is finite) is $\Delta_{p r e}$, since it is infinite for $\delta_{p r e}^{*} \notin \Delta_{\text {pre }}$ by construction, and by assumption, $\operatorname{LID}\left(\delta_{p r e}^{*}\right)$ is finite for all $\delta_{\text {pre }}^{*} \in \Delta_{\text {pre }}$. Since $\Delta$ is assumed to be convex, it is easy to verify that $\Delta_{p r e}$ is a non-empty convex set, and thus has non-empty relative interior, so the relative interior of the domain of $-L I D$ is non-empty. ${ }^{43}$ It follows from Theorem 8.2 in Mau Nam (2019) that $\partial(-L I D)=\partial\left(-b^{\max }\right)+\partial\left(b^{\text {min }}\right)$ where for a convex function $f, \partial f$ is the subdifferential $\partial f(\bar{x}):=\left\{v: f(\bar{x})+v^{\prime}(x-\bar{x}) \leqslant f(x), \forall x\right\}$ and $\partial\left(-b^{\text {max }}\right)+\partial\left(b^{\text {min }}\right)$ is the Minkowski sum of the two subdifferentials.

Additionally, if $L I D\left(\delta_{\text {pre }}\right)=\sup _{\tilde{\delta}_{p r e} \in \Delta_{\text {pre }}} L I D\left(\tilde{\delta}_{\text {pre }}\right)$, then $-L I D\left(\delta_{\text {pre }}\right)=\inf _{\tilde{\delta}_{p r e} \in \Delta_{\text {pre }}}-L I D\left(\tilde{\delta}_{\text {pre }}\right)$. Thus, standard results in convex analysis (see, e.g., Theorem 16.2 in Mau Nam (2019)) give that $0 \in \partial(-L I D)\left(\delta_{\text {pre }}\right)+N\left(\Delta ; \delta_{\text {pre }}\right)$, where $N\left(\Delta ; \delta_{\text {pre }}\right)=\left\{v_{\text {pre }}: v_{\text {pre }}^{\prime}\left(\tilde{\delta}_{\text {pre }}-\delta_{\text {pre }}\right) \leqslant 0, \forall \tilde{\delta}_{\text {pre }} \in\right.$ $\left.\Delta_{\text {pre }}\right\}$ is the normal cone to $\Delta_{\text {pre }}$ at $\delta_{\text {pre }}$. Hence, there exist vectors $\bar{v}_{\text {min }}, \bar{v}_{\text {max }}$ such that for all $\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}$,

$$
\begin{align*}
& b^{\text {min }}\left(\delta_{\text {pre }}\right)+\bar{v}_{\text {min }}^{\prime}\left(\tilde{\delta}_{\text {pre }}-\delta_{\text {pre }}\right) \leqslant b^{\text {min }}\left(\tilde{\delta}_{\text {pre }}\right)  \tag{51}\\
& -b^{\text {max }}\left(\delta_{\text {pre }}\right)+\bar{v}_{\text {max }}^{\prime}\left(\tilde{\delta}_{\text {pre }}-\delta_{\text {pre }}\right) \leqslant-b^{\text {max }}\left(\tilde{\delta}_{\text {pre }}\right)  \tag{52}\\
& -\left(\bar{v}_{\text {min }}+\bar{v}_{\text {max }}\right)^{\prime}\left(\tilde{\delta}_{\text {pre }}-\delta_{\text {pre }}\right) \leqslant 0 . \tag{53}
\end{align*}
$$

The inequalities (52) and (53) together imply that for all $\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}$,

$$
\begin{equation*}
b^{\max }\left(\delta_{p r e}\right)+\bar{v}_{\text {min }}^{\prime}\left(\tilde{\delta}_{p r e}-\delta_{p r e}\right) \geqslant b^{\max }\left(\tilde{\delta}_{p r e}\right) . \tag{54}
\end{equation*}
$$

[^28]Now, let $v$ be the vector such that $v_{\text {post }}=l$ and $v_{\text {pre }}=-\bar{v}_{\text {min }}$. Observe that

$$
\begin{align*}
\max _{\tilde{\delta} \in \Delta} a+v_{p r e}^{\prime} \tilde{\delta}_{p r e}+l^{\prime} \tilde{\delta}_{p o s t} & =\max _{\tilde{\delta}_{p r e} \in \Delta_{\text {pre }}}\left(a+v_{\text {pre }}^{\prime} \tilde{\delta}_{p r e}+\max _{\bar{\delta} \in \Delta, \bar{\delta}_{p r e}=\tilde{\delta}_{p r e}} l^{\prime} \bar{\delta}_{\text {post }}\right) \\
& =\max _{\tilde{\delta}_{p r e} \in \Delta_{p r e}} a+v_{p r e}^{\prime} \tilde{\delta}_{\text {pre }}+b^{\text {max }}\left(\tilde{\delta}_{\text {pre }}\right) \\
& \leqslant a+v_{p r e}^{\prime} \delta_{\text {pre }}+b^{\text {max }}\left(\delta_{\text {pre }}\right), \tag{55}
\end{align*}
$$

where the first equality nests the maximization, the second equality uses the definition of $b^{\max }$, and the inequality follows from (54). An analogous argument using (51) yields that

$$
\begin{align*}
\min _{\tilde{\delta} \in \Delta} a+v_{p r e}^{\prime} \tilde{\delta}_{\text {pre }}+l^{\prime} \tilde{\delta}_{\text {post }} & =\min _{\tilde{\delta}_{p r e} \in \Delta_{p r e}} a+v_{p r e}^{\prime} \tilde{\delta}_{\text {pre }}+b^{\min }\left(\tilde{\delta}_{p r e}\right) \\
& \geqslant a+v_{p r e}^{\prime} \delta_{\text {pre }}+b^{\text {min }}\left(\delta_{\text {pre }}\right) . \tag{56}
\end{align*}
$$

Now, it is apparent from equation (50) that

$$
\begin{equation*}
\bar{b}(a, v)=\max \left\{\left|\max _{\tilde{\delta} \in \Delta} a+v_{p r e}^{\prime} \tilde{\delta}_{\text {pre }}+l^{\prime} \tilde{\delta}_{\text {post }}\right|,\left|\min _{\tilde{\delta} \in \Delta} a+v_{p r e}^{\prime} \tilde{\delta}_{\text {pre }}+l^{\prime} \tilde{\delta}_{\text {post }}\right|\right\}, \tag{57}
\end{equation*}
$$

which is bounded above by $\max \left\{\left|a+v_{\text {pre }}^{\prime} \delta_{\text {pre }}+b^{\max }\left(\delta_{\text {pre }}\right)\right|,\left|a+v_{p r e}^{\prime} \delta_{\text {pre }}+b^{\text {min }}\left(\delta_{p r e}\right)\right|\right\}$ from the results above. Setting $a=-v_{\text {pre }}^{\prime} \delta_{\text {pre }}-\frac{1}{2}\left(b^{\text {max }}\left(\delta_{\text {pre }}\right)+b^{\text {min }}\left(\delta_{\text {pre }}\right)\right)$, the upper bound in the previous display reduces to $\frac{1}{2}\left(b^{\max }\left(\delta_{\text {pre }}\right)-b^{\min }\left(\delta_{\text {pre }}\right)\right)$. Since $\operatorname{LID}\left(\Delta, \delta_{\text {pre }}\right)=b^{\text {max }}\left(\delta_{\text {pre }}\right)-$ $b^{\text {min }}\left(\delta_{\text {pre }}\right)$ and $\operatorname{LID}\left(\Delta, \delta_{\text {pre }}\right)=\sup _{\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}} \operatorname{LID}\left(\Delta, \tilde{\delta}_{\text {pre }}\right)$ by assumption, it is then immediate that $\bar{b} \leqslant \frac{1}{2} \sup _{\tilde{\delta}_{p r e} \in \Delta_{\text {pre }}} \operatorname{LID}\left(\Delta, \tilde{\delta}_{\text {pre }}\right)$. The inequality in the opposite direction follows from Lemma B.19.

Finally, substituting in the definition of $a$ and $v$ above and simplifying, we see that $\mathbb{E}_{\left(\delta, \tau, \Sigma_{n}\right)}\left[a+v^{\prime} \hat{\beta}_{n}\right]=l^{\prime} \beta_{\text {post }}-\frac{1}{2}\left(b^{\max }\left(\delta_{p r e}\right)+b^{\text {min }}\left(\delta_{\text {pre }}\right)\right)$, which from (5) and (6) we see is the midpoint of the identified set.

Lemma B.21. Let $\chi_{\alpha}$ be the $1-\alpha$ quantile of the $\left|\mathcal{N}\left(b, \sigma^{2}\right)\right|$ distribution for $b \geqslant 0$. Then $b+\sigma z_{1-\alpha} \leqslant \chi_{\alpha} \leqslant b+\sigma z_{1-\alpha / 2}$.

Proof. Since $|\xi| \geqslant \xi$, we have that $q_{1-\alpha}\left(|\xi| \mid \xi \sim \mathcal{N}\left(b, \sigma^{2}\right)\right) \geqslant q_{1-\alpha}\left(\xi \mid \xi \sim \mathcal{N}\left(b, \sigma^{2}\right)\right)=$ $b+\sigma z_{1-\alpha}$, which yields the first inequality. For the second inequality, observe that

$$
\begin{aligned}
q_{1-\alpha}\left(|\xi| \mid \xi \sim \mathcal{N}\left(b, \sigma^{2}\right)\right) & =q_{1-\alpha}\left(|\xi+b| \mid \xi \sim \mathcal{N}\left(0, \sigma^{2}\right)\right) \\
& \leqslant b+q_{1-\alpha}\left(|\xi| \mid \xi \sim \mathcal{N}\left(0, \sigma^{2}\right)\right)=b+\sigma z_{1-\alpha / 2}
\end{aligned}
$$

where the first inequality uses the triangle inequality, and the final equality uses the fact
that a mean-zero normal distribution is symmetric about 0 .
Lemma B.22. Suppose the conditions of Proposition A.1 hold. Then there is a unique pair $(\bar{a}, \bar{v})$ such that $\bar{b}(\bar{a}, \bar{v})=\frac{1}{2} \sup _{\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}} \operatorname{LID}\left(\Delta, \tilde{\delta}_{\text {pre }}\right)=: \bar{b}_{\text {min }}$. Additionally, $\sqrt{\bar{v}^{\prime} A \Sigma^{*} A^{\prime} \bar{v}}=$ $1 / c^{*}$, for $c^{*}$ defined in Proposition 4.2.

Proof. Existence of an $(\bar{a}, \bar{v})$ satisfying $\bar{b}(\bar{a}, \bar{v})=\bar{b}_{\text {min }}$ follows from Lemma B.20, so to establish the existence of a unique solution it suffices to establish uniqueness. In the proof to Lemma B.7, we showed that $b^{\min }\left(\delta_{A, p r e}\right)$ is equivalent to the problem (42). Assumption 5 implies that there is a solution $\delta_{\text {post }}^{* *}$ to the optimization (42) such that $A_{(B, p o s t)}$ has rank $|B|$, where $B$ indexes the binding moments. The solution $\delta_{p o s t}^{* *}$ to the problem (42) is thus non-degenerate. It follows that in a neighborhood of $\delta_{p r e, A}, b^{\min }\left(\delta_{p r e}\right)=$ $b^{\text {min }}\left(\delta_{A, p r e}\right)+\bar{\gamma}^{\prime} A_{(\cdot, p r e)}\left(\delta_{p r e}-\delta_{A, p r e}\right)$, where $\bar{\gamma}$ is a solution to the dual problem (see, e.g., Section 10.4 of Schrijver (1986)). By the complementary slackness conditions, $\bar{\gamma}_{-B}=0$. Moreover, we showed in the proof to Lemma B. 7 that $\bar{\gamma}_{B}$ is the unique vector that satisfies $\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B,-1)}=0, \bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)}=1$.

Next, combining the expression for $\bar{b}$ in (57) along with the equalities in (55) and (56) in the proof to Lemma B.20, we see that for any $(a, v)$,

$$
\begin{equation*}
\bar{b}(a, v)=\max \left\{\left|\max _{\tilde{\delta}_{p r e} \in \Delta_{p r e}} a+v_{p r e}^{\prime} \tilde{\delta}_{p r e}+b^{\max }\left(\tilde{\delta}_{p r e}\right)\right|,\left|\min _{\tilde{\delta}_{p r e} \in \Delta_{\text {pre }}} a+v_{p r e}^{\prime} \tilde{\delta}_{p r e}+b^{\min }\left(\tilde{\delta}_{p r e}\right)\right|\right\} . \tag{58}
\end{equation*}
$$

This implies that if $(\bar{a}, \bar{v})$ are such that $\bar{b}(\bar{a}, \bar{v})=\bar{b}_{\text {min }}$, then for all $\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}$,

$$
\begin{equation*}
\bar{b}_{\text {min }} \geqslant \max \left\{\left|\bar{a}+\bar{v}_{p r e}^{\prime} \tilde{\delta}_{p r e}+b^{\max }\left(\tilde{\delta}_{p r e}\right)\right|,\left|\bar{a}+\bar{v}_{p r e}^{\prime} \tilde{\delta}_{p r e}+b^{\min }\left(\tilde{\delta}_{p r e}\right)\right|\right\} . \tag{59}
\end{equation*}
$$

Now, note that by the triangle inequality, for any scalars $x_{1}, x_{2}, x_{3}$ with $x_{2} \geqslant x_{3}$, max $\left\{\mid x_{1}+\right.$ $x_{2}\left|,\left|x_{1}+x_{3}\right|\right\} \geqslant \frac{1}{2}\left|x_{2}-x_{3}\right|$, with equality if and only if $x_{1}+x_{3}=-\left(x_{1}+x_{2}\right)$. Further, recall that $b^{\text {max }}\left(\delta_{A, p r e}\right)-b^{\text {min }}\left(\delta_{A, p r e}\right)=\operatorname{LID}\left(\Delta, \delta_{A, p r e}\right)=2 \bar{b}_{\text {min }}$. It follows from these two facts along with the expression in the previous display that

$$
\begin{equation*}
\bar{b}_{\text {min }}=\bar{a}+\bar{v}_{p r e}^{\prime} \delta_{A, p r e}+b^{\max }\left(\delta_{A, p r e}\right)=-\left(\bar{a}+\bar{v}_{p r e}^{\prime} \delta_{A, \text { pre }}+b^{\min }\left(\delta_{A, p r e}\right)\right) . \tag{60}
\end{equation*}
$$

Displays (59) and (60) imply that for all $\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}$,

$$
\bar{v}_{p r e}^{\prime}\left(\tilde{\delta}_{p r e}-\tilde{\delta}_{A, p r e}\right)+b^{\min }\left(\tilde{\delta}_{p r e}\right)-b^{\text {min }}\left(\delta_{A, p r e}\right) \geqslant 0
$$

which using the local linearization derived above implies that

$$
\left.\left(\bar{v}_{p r e}^{\prime}+\bar{\gamma}^{\prime} A_{(\cdot, p r e)}\right)\right)\left(\tilde{\delta}_{p r e}-\delta_{A, p r e}\right) \geqslant 0
$$

for all $\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}$ in a sufficiently small neighborhood of $\delta_{A, p r e}$. However, Assumption 5 implies that $\delta_{A, p r e}$ is in the interior of $\Delta_{\text {pre }}$, and so the equality in the previous display can hold for all such $\tilde{\delta}_{\text {pre }}$ only if $\bar{v}_{\text {pre }}^{\prime}=-\bar{\gamma}^{\prime} A_{(, \text {pre })}$. We argued in the proof to Lemma B. 19 that $\bar{v}_{\text {post }}$ must equal $l$, so we have shown that there is a unique value of $\bar{v}$. Further, (60) uniquely pins downs $\bar{a}$ in terms of $\bar{v}$, and so the pair $(\bar{a}, \bar{v})$ is unique, as claimed.

Finally, recall from the proof to Lemma B. 7 that $-\bar{\gamma}^{\prime} A_{(\cdot, p o s t)}=l^{\prime}$. Hence $\bar{v}^{\prime}=\left(-\bar{\gamma}^{\prime} A_{(\cdot, p r e)},-\bar{\gamma}^{\prime} A_{(\cdot, p o s t)}\right)=$ $-\bar{\gamma}^{\prime} A$ and thus $\bar{v}^{\prime} \Sigma^{*} \bar{v}=\bar{\gamma}^{\prime} A \Sigma^{*} A^{\prime} \bar{\gamma}$. Since $\bar{\gamma}_{-B}=0$ and $\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)}=1$, we see that $1 / \sqrt{\bar{v}^{\prime} \Sigma^{*} \bar{v}}$ corresponds with the formula for $c^{*}$ given in the footnote to Proposition 4.2.

Lemma B.23. Suppose the conditions of Proposition A.1 hold. Then $\frac{\sigma_{v_{n}, n}}{\sigma_{\bar{v}, n}} \rightarrow 1$, where the optimal FLCI is based on the affine estimator $a_{n}+v_{n}^{\prime} \hat{\beta}_{n}$ and $\bar{v}$ is the unique value such that $\bar{b}(\bar{a}, \bar{v})=\bar{b}_{\text {min }}$.
Proof. It suffices to show that $\frac{\sqrt{n} \sigma_{v_{n}, n}}{\sqrt{n} \sigma_{\bar{v}, n}} \rightarrow 1$. Note that $\sqrt{n} \sigma_{\bar{v}, n}=\sigma_{\bar{v}, 1}=\sqrt{\bar{v}^{\prime} \Sigma^{*} \bar{v}}$. By assumption, $\Sigma^{*}$ is positive definite, and we showed in the proof to Lemma B. 19 that $\bar{v}_{\text {post }}=l$, so $\bar{v} \neq 0$. Hence $\sigma_{\bar{v}, 1}>0$. Next, observe that $\sqrt{n} \sigma_{v_{n}, n}=\sqrt{v_{n}^{\prime} \Sigma^{*} v_{n}}$. It thus suffices to show that $v_{n} \rightarrow \bar{v}$, since then both the numerator and denominator converge to the same non-zero limit. To do this, we will show that every subsequence of $v_{n}$ has a convergent subsequence. Consider a subsequence $v_{n_{m}}$. We argued in the proof to Proposition 3.2 that $\sigma_{v_{n}, n} \leqslant \sigma_{\bar{v}, n}$, which implies that $\sqrt{v_{n}^{\prime} \Sigma^{*} v_{n}} \leqslant \sqrt{\bar{v}^{\prime} \Sigma^{*} \bar{v}}$. Thus, $v_{n}$ is bounded in the Mahalanobis norm using $\Sigma^{*}$, which implies that $v_{n}$ is bounded in the standard euclidean norm since $\Sigma^{*}$ positive definite. It follows that $v_{n_{m}}$ has a convergent subsequence, $v_{n_{m}, 1} \rightarrow v^{*}$. We argued in the proof to Proposition 3.2 that $\bar{b}\left(a_{n}, v_{n}\right) \rightarrow \bar{b}_{\text {min }}$. This implies, however, that $a_{n_{m}, 1}$ is bounded. To see why this is the case, note that if there is a divergent subsequence $a_{n_{m}, 2}$, then for any fixed $\tilde{\delta}_{\text {pre }} \in \Delta_{\text {pre }}$, $\left|a_{n_{m}, 2}+v_{n_{m}, 2, \text { pre }}^{\prime} \tilde{\delta}_{\text {pre }}+b^{\text {max }}\left(\tilde{\delta}_{\text {pre }}\right)\right|$ diverges since $v_{n_{m}, 2, p r e} \rightarrow v_{\text {pre }}^{*}$. Equation (58) then implies that $\bar{b}\left(a_{n_{m}, 2}, v_{n_{m}, 2}\right)$ diverges, which is a contradiction. Thus $a_{n_{m}, 1}$ is bounded, and so we can extract a further subsequence such that $\left(a_{n_{m}, 2}, v_{n_{m}, 2}\right) \rightarrow\left(a^{*}, v^{*}\right)$. For ease of notation, suppose without loss of generality that these convergences hold for the original subsequence $n_{m}$. To complete the proof, we will show that $\bar{b}\left(a^{*}, v^{*}\right)=\bar{b}_{\text {min }}$, which then implies that $v^{*}=\bar{v}$ by Lemma B.22. To show this, note that (50) together with the identity $|x|=\max \{x,-x\}$ imply that $\bar{b}(a, v)=\max \left\{\left(\max _{\delta} a+v^{\prime} \delta\right.\right.$ s.t. $\left.A \delta \leqslant d\right),\left(\max _{\delta}-a-v^{\prime} \delta\right.$ s.t. $\left.\left.A \delta \leqslant d\right)\right\}$. Consider the first inner maximization, and let $\delta_{n_{m}}$ denote the optimal value using $v=v_{n_{m}}$, and $\delta^{*}$
the optimal value using $v=v^{*}$. Since $\delta^{*}$ is feasible in the optimization using $v_{n_{m}}$, we have $a_{n_{m}}+v_{n_{m}}^{\prime} \delta^{*} \leqslant a_{n_{m}}+v_{n_{m}}^{\prime} \delta_{n_{m}}$. Taking limits on both sides of this inequality implies that

$$
a^{*}+\left(v^{*}\right)^{\prime} \delta^{*}=\left(\max _{\delta} a^{*}+\left(v^{*}\right)^{\prime} \delta \text { s.t. } A \delta \leqslant d\right) \leqslant \liminf _{m \rightarrow \infty}\left(\max _{\delta} a_{n_{m}}+v_{n_{m}}^{\prime} \delta \text { s.t. } A \delta \leqslant d\right)
$$

Applying a similar argument to the second inner maximization, it follows that

$$
\bar{b}\left(a^{*}, v^{*}\right) \leqslant \lim _{m \rightarrow \infty} \bar{b}\left(a_{n_{m}}, v_{n_{m}}\right)=\bar{b}_{m i n}
$$

But $\bar{b}\left(a^{*}, v^{*}\right) \geqslant \bar{b}_{\text {min }}$ by Lemma B.19, which gives the desired equality.
Lemma B.24. $\lim _{x \rightarrow \infty}\left(c v_{\alpha}(x)-\left(z_{1-\alpha}+x\right)\right)=0$.
Proof. $c v_{\alpha}(x)$ solves $\Phi\left(c v_{\alpha}(x)-x\right)-\Phi\left(-c v_{\alpha}(x)-x\right)=1-\alpha$. By Lemma B.21, $c v_{\alpha}(x) \geqslant x+$ $z_{1-\alpha}$, which diverges as $x \rightarrow \infty$. Thus, $\Phi\left(-c v_{\alpha}(x)-x\right)$ converges to 0 and $\Phi\left(c v_{\alpha}(x)-x\right) \rightarrow$ $1-\alpha$, together implying $c v_{\alpha}(x)-x \rightarrow z_{1-\alpha}$.

Lemma B.25. Suppose that Assumption 5 holds at $\delta_{A, p r e}$. Then $\operatorname{LID}\left(\Delta, \delta_{A, p r e}\right)>0$.
Proof. From (5) and (6), we see that that $\operatorname{LID}\left(\Delta, \delta_{A, p r e}\right)=0$ if and only if $b^{\max }\left(\delta_{A, p r e}\right)=$ $b^{\text {min }}\left(\delta_{A, p r e}\right)$, where $b^{\text {min }}\left(\delta_{\text {pre }, A}\right):=\left(\min _{\delta} l^{\prime} \delta_{\text {post }}\right.$, s.t. $\left.\delta \in \Delta, \delta_{\text {pre }}=\delta_{\text {pre }, A}\right)$, and $b^{\text {max }}$ is defined analogously. In the proof to Lemma B.7, we showed that $b^{\min }$ is equivalent to the problem (42). Assumption 5 implies that there is a solution $\delta_{\text {post }}^{* *}$ such that

$$
A_{(B, \text { post })} \delta_{\text {post }}^{* *}=d_{B}-A_{(B, p r e)} \delta_{A, \text { pre }} \text { and } A_{(-B, p o s t)} \delta_{\text {post }}^{* *}<d_{-B}-A_{(-B, p r e)} \delta_{A, p r e},
$$

where $A_{B, \text { post }}$ has rank $|B|$. Observe that if $b^{\min }\left(\delta_{A, p r e}\right)=b^{\max }\left(\delta_{A, p r e}\right)$, then it must be that $l^{\prime} \delta_{p r e}^{* *}=l^{\prime} \tilde{\delta}_{\text {pre }}$ for any $\tilde{\delta}_{\text {pre }}$ that is feasible in the problem (42). It thus suffices to construct a feasible value $\tilde{\delta}_{\text {pre }}$ such that $l^{\prime} \tilde{\delta}_{\text {pre }} \neq l^{\prime} \delta_{p r e}^{* *}$. Since $A_{(B, p o s t)}$ has rank $|B|$, its image is $\mathbb{R}^{|B|}$, so there exists $\bar{\delta}_{\text {post }}$ such that $A_{(B, p o s t)} \bar{\delta}_{\text {post }}=-\iota$, for $\iota$ the vector of ones. Thus, for any $\epsilon_{1}>0$, we have that $A_{(B, p o s t)}\left(\delta_{\text {post }}^{* *}+\epsilon_{1} \bar{\delta}_{\text {post }}\right)<d_{B}-A_{(B, p r e)} \delta_{A, p r e}$. However, since the moments $-B$ are slack at $\delta_{A, p r e}$, for $\epsilon_{1}$ sufficiently small, we also have $A_{(-B, p o s t)}\left(\delta_{\text {post }}^{* *}+\epsilon_{1} \bar{\delta}_{\text {post }}\right)<$ $d_{-B}-A_{(-B, p r e)} \delta_{A, p r e}$. If $l^{\prime} \bar{\delta}_{\text {post }} \neq 0$, then we are done. If $l^{\prime} \bar{\delta}_{\text {post }}=0$, then since all of the moments are slack at $\delta_{\text {post }}^{* *}+\epsilon_{1} \bar{\delta}_{\text {post }}$, for $\epsilon_{2}>0$ sufficiently small, $\tilde{\delta}_{\text {post }}=\delta_{\text {post }}^{* *}+\epsilon_{1} \bar{\delta}_{\text {post }}+\epsilon_{2} l$ is also feasible, and by construction $l^{\prime}\left(\tilde{\delta}_{\text {post }}-\delta_{\text {post }}^{* *}\right)=\epsilon_{2} l^{\prime} l>0$.

Lemma B.26. Suppose $\Delta$ is convex and centrosymmetric, and $\delta_{A}$ is such that $\delta \in \Delta$ implies $\delta-\delta_{A} \in \Delta$. Then $\delta_{A}$ satisfies Assumption 4.

Proof. Recall from the proof to Lemma B. 20 that for any $\delta_{\text {pre }}^{*} \in \Delta_{\text {pre }}, \operatorname{LID}\left(\Delta, \delta_{\text {pre }}^{*}\right)=$ $b^{\max }\left(\delta_{\text {pre }}^{*}\right)-b^{\min }\left(\delta_{p r e}^{*}\right)$, where the functions $b^{\min }$ and $-b^{\max }$ are convex. Observe that

$$
\begin{aligned}
b^{\min }\left(\delta_{\text {pre }}^{*}\right) & =\left(\min _{\delta} l^{\prime} \delta_{p o s t}, \text { s.t. } \delta \in \Delta, \delta_{p r e}=\delta_{p r e}^{*}\right) \\
& =-\left(\max _{\delta} l^{\prime}\left(-\delta_{\text {post }}\right), \text { s.t. } \delta \in \Delta, \delta_{\text {pre }}=\delta_{p r e}^{*}\right) \\
& =-\left(\max _{\delta} l^{\prime} \delta_{p o s t}, \text { s.t. } \delta \in \Delta, \delta_{\text {pre }}=-\delta_{p r e}^{*}\right)=-b^{\max }\left(-\delta_{p r e}^{*}\right),
\end{aligned}
$$

where the third equality uses the fact that $\Delta$ is centrosymmetric. Hence, $-\operatorname{LID}\left(\Delta, \delta_{\text {pre }}^{*}\right)=$ $-b^{\max }\left(\delta_{p r e}^{*}\right)-b^{\max }\left(-\delta_{p r e}^{*}\right)$. It follows from the subdifferential sum and chain rules for convex functions (e.g., Theorems 8.2 and 9.3 in Mau $\operatorname{Nam}(2019))$ that $\partial-\operatorname{LID}\left(\Delta, \delta_{p r e}^{*}\right)=$ $\partial\left(-b^{\max }\right)\left(\delta_{p r e}^{*}\right)+\left(-\partial\left(-b^{\max }\right)\left(-\delta_{p r e}^{*}\right)\right)$, for + the Minkowski sum. It is then immediate that $0 \in \partial(-L I D(\Delta, 0))$, and hence $0 \in \arg \min _{\tilde{\delta}_{p r e} \in \Delta_{\text {pre }}}-L I D\left(\Delta, \tilde{\delta}_{\text {pre }}\right)$. This implies that $\operatorname{LID}(\Delta, 0)=\sup _{\tilde{d}_{\text {pre }} \in \Delta_{\text {pre }}} \operatorname{LID}\left(\Delta, \tilde{\delta}_{\text {pre }}\right)$.

To complete the proof, we show that $\operatorname{LID}\left(\Delta, \delta_{A, \text { pre }}\right) \geqslant \operatorname{LID}(\Delta, 0)$. We first claim that for any $\delta \in \Delta$, we also have $\delta+\delta_{A} \in \Delta$. Indeed, by centrosymmetry, $-\delta \in \Delta$. By assumption, this implies that $-\delta-\delta_{A} \in \Delta$. Applying centrosymmetry again, we see that $\delta+\delta_{A} \in \Delta$, as desired. Next, suppose that $\delta^{\max }$ is optimal in the maximization $b^{\max }(0)=\left(\max _{\delta} l^{\prime} \delta_{\text {post }}\right.$, s.t. $\left.\delta \in \Delta, \delta_{\text {pre }}=0\right)$. Then $\delta^{\max }+\delta_{A}$ is feasible in the optimization $\left(\max _{\delta} l^{\prime} \delta_{p o s t}\right.$, s.t. $\left.\delta \in \Delta, \delta_{\text {pre }}=\delta_{A, p r e}\right)$, and thus $b^{\max }\left(\delta_{A, p r e}\right) \geqslant b^{\max }(0)+l^{\prime} \delta_{A, p o s t}$. By analogous argument, we can obtain that $b^{\min }\left(\delta_{A, p r e}\right) \leqslant b^{\min }(0)+l^{\prime} \delta_{A, p o s t}$. It follows that $\operatorname{LID}\left(\Delta, \delta_{A, p r e}\right)=b^{\max }\left(\delta_{A, p r e}\right)-b^{\min }\left(\delta_{A, p r e}\right) \geqslant b^{\max }(0)-b^{\min }(0)=\operatorname{LID}(\Delta, 0)$, as needed.

Lemma B.27. Fix $\Sigma^{*}$ positive definite, $\delta_{A} \in \Delta$, and $\tau_{A}$. Suppose Assumption 5 holds at $\delta_{A}$, and let $B=B\left(\delta^{* *}\right)$. Let $\hat{V}_{n}$ denote the set of optimal vertices used in $\psi_{\alpha}^{C}\left(\hat{\beta}_{n} ; A, \sqrt{n} d, \theta_{n}^{u b}+\right.$ $\left.x, \Sigma^{*}\right)$, where $\theta_{n}^{u b}=\sup S\left(\Delta_{n}, \sqrt{n}\left(\delta_{A}+\tau_{A}\right)\right), \Delta_{n}=\sqrt{n} \Delta$. Then

$$
\lim _{n \rightarrow \infty} \mathbb{P}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left(\hat{V}_{n}=\{c \bar{\gamma}\}\right)=1,
$$

where $c>0$ and $\bar{\gamma}$ is the vector such that $\bar{\gamma}_{-B}=0$ and $\bar{\gamma}_{B}$ is the unique vector such that $\bar{\gamma}^{\prime} \tilde{A}_{(\cdot,-1)}=0, \bar{\gamma} \geqslant 0,\|\bar{\gamma}\|=1$.

Proof. Observe that $\hat{V}_{n}=\arg \min _{\gamma \in V\left(\Sigma^{*}\right)} \gamma^{\prime} \tilde{Y}_{n}$, where $\tilde{Y}_{n}=A \hat{\beta}_{n}-\sqrt{n} d-\tilde{A}_{(\cdot, 1)}\left(\theta_{n}^{u b}+x\right)$. Since all vertices $\gamma \in V\left(\Sigma^{*}\right)$ satisfy $\gamma^{\prime} \tilde{A}_{(\cdot,-1)}=0$ by definition, we have that $\hat{V}_{n}=\arg \min _{\gamma \in V\left(\Sigma^{*}\right)} \gamma^{\prime} \breve{Y}_{n}$, for $\breve{Y}_{n}=\tilde{Y}_{n}-\tilde{A}_{(\cdot,-1)}\left(\sqrt{n} \tilde{\tau}_{1}^{u b}\right)$ and $\tilde{\tau}_{1}^{u b}$ the vector constructed in the proof to Lemma B.8. However, we showed in the proof to Lemma B. 8 that $\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\breve{Y}_{n, B}\right]=-\tilde{A}_{(B, 1)} x$ and $\mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\breve{Y}_{n,-B}\right] \rightarrow-\infty$ as $n \rightarrow \infty$.

Lemmas C. 1 and D. 7 in the supplementary material together imply that there is a unique
vector $\gamma^{*} \in V\left(\Sigma^{*}\right)$ such that $\gamma_{-B}^{*}=0$, which satisfies $\gamma_{B}^{*}=c \bar{\gamma}$ for $c>0$. By definition, $\gamma \geqslant 0$ for all $\gamma \in V\left(\Sigma^{*}\right)$, and thus $\gamma_{-B}$ has at least one strictly positive element for all $\gamma \in V\left(\Sigma^{*}\right) \backslash\left\{\gamma^{*}\right\}$. It follows that
$\lim _{n \rightarrow \infty} \mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\gamma^{* \prime} \breve{Y}_{n}\right]=-\gamma_{B}^{* \prime} \tilde{A}_{(B, 1)} x$ and $\lim _{n \rightarrow \infty} \mathbb{E}_{\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)}\left[\gamma^{\prime} \breve{Y}_{n}\right]=-\infty, \forall \gamma \in V\left(\Sigma^{*}\right) \backslash\left\{\gamma^{*}\right\}$.
Let $P_{n}$ denote the sequence of data-generating processes characterized by $\left(\sqrt{n} \delta_{A}, \sqrt{n} \tau_{A}, \Sigma^{*}\right)$. Note that that for all $n,\left(\gamma^{*}-\gamma\right)^{\prime} \tilde{Y}_{n}$ is normally distributed with variance $\left(\gamma^{*}-\gamma\right)^{\prime} \Sigma^{*}\left(\gamma^{*}-\gamma\right)$ under $P_{n}$. This combined with the results in the previous display imply that $\gamma^{* \prime} \breve{Y}_{n}-\gamma^{\prime} \breve{Y}_{n} \xrightarrow{P_{n}}{ }_{p}$ $\infty$ for all $\gamma \in V\left(\Sigma^{*}\right) \backslash\left\{\gamma^{*}\right\}$. Since $V\left(\Sigma^{*}\right) \backslash\left\{\gamma^{*}\right\}$ is finite, this implies that $\min _{\gamma \in V\left(\Sigma^{*}\right) \backslash\left\{\gamma^{*}\right\}}\left(\gamma^{* \prime} \breve{Y}_{n}-\right.$ $\left.\gamma^{\prime} \breve{Y}_{n}\right) \xrightarrow{P_{n}} \infty$, from which we see that $\gamma^{* \prime} \breve{Y}_{n}=\max _{\gamma \in V\left(\Sigma^{*}\right)} \gamma^{\prime} \breve{Y}_{n}$ with probability approaching 1 under $P_{n}$, which gives the desired result.

## Appendix References

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[^0]:    *We are grateful to Isaiah Andrews, Elie Tamer, and Larry Katz for their invaluable advice and encouragement. We also thank Gary Chamberlain, Raj Chetty, Peter Ganong, Ed Glaeser, Nathan Hendren, Ryan Hill, Ariella Kahn-Lang, Jens Ludwig, Sendhil Mullainathan, Claudia Noack, Frank Pinter, Adrienne Sabety, Pedro Sant'Anna, Jesse Shapiro, Neil Shephard, Jann Spiess, Jim Stock, and seminar participants at Brown, Chicago Booth, Dartmouth, Harvard, Michigan, Microsoft, Princeton, Rochester, UCL, and Yale for helpful comments, and Dorian Carloni for sharing data. We gratefully acknowledge financial support from the NSF Graduate Research Fellowship under Grant DGE1745303 (Rambachan) and Grant DGE1144152 (Roth).
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[^1]:    ${ }^{1}$ Throughout the paper, we use the phrase "event-study" to refer to a large class of specifications that estimate dynamic treatment effects along with placebo pre-treatment effects. This includes, but is not limited to, settings with staggered treatment timing; see Related Literature and Section 7 below.

[^2]:    ${ }^{2}$ This condition is implied by the linear independence constraint qualification (LICQ), which has been used recently in the moment inequality settings studied in Gafarov (2019); Cho and Russell (2019); Flynn (2019); Kaido and Santos (2014). In contrast to many previous uses of LICQ, however, we do not require this condition to obtain uniform asymptotic size control. See Section 4.3 for further discussion.

[^3]:    ${ }^{3}$ Similar "breakdown" concepts have been proposed in other settings with partial identification (Horowitz and Manski, 1995; Kline and Santos, 2013; Masten and Poirier, 2020).
    ${ }^{4}$ The latest version of may be downloaded here.

[^4]:    ${ }^{5}$ Examples of estimators that yield asymptotically normal event-study estimates include canonical twoway fixed effects estimators, the GMM procedure proposed by Freyaldenhoven et al. (2019), instrumental variables event-studies (Hudson, Hull and Liebersohn, 2017), the estimation strategies of Sun and Abraham (2020) and Callaway and Sant'Anna (2020) to address issues with non-convex weights on cohort-specific effects in staggered treatment designs, as well as a range of procedures that flexibly control for differences in covariates between treated and untreated groups (e.g., Heckman, Ichimura, Smith and Todd, 1998; Abadie, 2005; Sant'Anna and Zhao, 2020).

[^5]:    ${ }^{6}$ For the purposes of this example, we think of the observed sample as consisting of $N_{1}$ independent draws from the treated $(D=1)$ population and $N_{0}$ independent draws from the control population $(D=0)$ with $N=N_{0}+N_{1}$, as in Abadie and Imbens (2006).

[^6]:    ${ }^{7}$ That is, researchers may augment specification (3) with group-specific linear trends, an approach Dobkin et al. (2018) refer to as a "parametric event-study." An analogous approach is to estimate a linear trend using only observations prior to treatment, and then subtract out the estimated linear trend from the observations after treatment (Bhuller et al., 2013; Goodman-Bacon, 2018a,b).
    ${ }^{8}$ Setting $\delta=0$ corresponds with the common practice of normalizing $\beta_{0}=0$, as in specification (3).
    ${ }^{9} \Delta^{S D}(M)$ bounds the discrete analog of the second derivative of $\delta$, and is thus similar to restrictions on the second derivative of the conditional expectation function or density in regression discontinuity settings (Kolesar and Rothe, 2018; Frandsen, 2016; Noack and Rothe, 2020). Smoothness restrictions are also used to obtain partial identification in Kim, Kwon, Kwon and Lee (2018).

[^7]:    ${ }^{10}$ Monotone violations of parallel trends are often discussed in applied work. For example, Lovenheim and Willen (2019) argue that violations of parallel trends cannot explain their results because "pre-[treatment] trends are either zero or in the wrong direction (i.e., opposite to the direction of the treatment effect)." Greenstone and Hanna (2014) estimate upward-sloping pre-existing trends and argue that "if the pre-trends had continued" their estimates would be upward biased.

[^8]:    ${ }^{11}$ In the case with one pre-period and one post-period, $\Delta^{S D}(M)=\left\{\delta: A^{S D} \delta \leqslant d^{S D}\right\}$ for $A^{S D}=$ $\left(\begin{array}{cc}-1 & 1 \\ 1 & -1\end{array}\right)$ and $d^{S D}=\binom{M}{M}$. This generalizes naturally when there are multiple pre-periods and multiple post-periods.

[^9]:    ${ }^{12}$ After augmenting the vector for the event-study coefficients, equation (2) needs to be re-written to replace $\left(0, \tau_{\text {post }}^{\prime}\right)^{\prime}$ with $M \tau_{\text {post }}$, where $M$ is a matrix that accounts for the fact that elements of $\tau$ enter both the event-study coefficients and the augmented terms. Our proposed methods and results do not rely on the structure that $M=(0, I)^{\prime}$ and thus easily accommodate this modification.

[^10]:    ${ }^{13}$ If $t=\infty$, we define $c v_{\alpha}=\infty$.

[^11]:    ${ }^{14}$ We use $\delta_{A}$ for the null value of $\delta$, rather than $\delta_{0}$, since we use the notation $\delta_{t}$ to refer to the component of $\delta$ corresponding with period $t$.

[^12]:    ${ }^{15}$ Additionally, as noted in Armstrong and Kolesar (2020), the results in Joshi (1969) imply that if $\Delta$ is a linear subspace satisfying part i) of Assumption 3, the FLCI achieves minimax expected length, so any procedure that outperforms it somewhere must also be inferior at some other point in the parameter space.
    ${ }^{16}$ To see why, suppose that the vector $\delta$ maximizes the bias for an affine estimator $(a, v)$ over $\Delta^{S D}(M)$. The vector that adds a constant slope to $\delta$, say $\tilde{\delta}_{c}=\delta+c \cdot(-\underline{T}, \ldots, \bar{T})^{\prime}$, also lies in $\Delta^{S D}(M)$, and for $c$ sufficiently large, $\tilde{\delta}_{c}$ will lie in $\Delta^{S D P B}(M)$. Moreover, the worse-case bias will be the same for $\delta$ and $\tilde{\delta}_{c}$, since if $(a, v)$ has finite worst-case bias it must subtract out a weighted average of the pre-treatment slopes.

[^13]:    ${ }^{17}$ This follows immediately from Lemma B. 19 below, which shows that the worst-case bias must be at least half the maximum length of the identified set, which is infinite for $\Delta^{R M I}(\bar{M})$.
    ${ }^{18}$ See, e.g., Kadane (1971) and Moreira and Ridder (2019) for other uses of small- $\Sigma$ asymptotics.

[^14]:    ${ }^{19}$ Specifically, let $\Gamma$ be a square matrix with the vector $l^{\prime}$ in the first row and remaining rows chosen so that $\Gamma$ has full rank. Define $\tilde{A}:=A M_{p o s t} \Gamma^{-1}$. Then $A M_{p o s t} \tau=\tilde{A} \Gamma \tau_{p o s t}=\tilde{A}(\underbrace{\Gamma_{(-1, \cdot)} \tau_{p o s t}}_{:=\tilde{\tau}})$. If $\bar{T}=1$, then $\tilde{\tau}$ is 0 -dimensional and should be interpreted as 0 .

[^15]:    ${ }^{20}$ Other moment inequality methods have been proposed for subvector inference, but typically do not exploit the linear structure of our setting - see, e.g, Chen, Christensen and Tamer (2018); Bugni, Canay and Shi (2017); Kaido, Molinari and Stoye (2019); Chernozhukov, Newey and Santos (2015); Romano and Shaikh (2008). Gafarov (2019), Cho and Russell (2019), and Flynn (2019) also provide methods for subvector inference with linear moment inequalities, but in contrast to our approach require a linear independence constraint qualification (LICQ) assumption for size control.

[^16]:    ${ }^{21}$ Technically, the duality results require that $\hat{\eta}$ be finite. However, one can show that $\hat{\eta}$ is finite with probability 1 , unless the span of $\tilde{X}$ contains a vector with all negative entries, in which case the identified set for $\theta$ is the real line. We therefore trivially define our test never to reject if $\hat{\eta}=-\infty$.
    ${ }^{22}$ In general, there may not be a unique solution to the dual program. However, Lemma 11 of ARP shows that conditional on any one vertex of the dual program's feasible set being optimal, every other vertex is optimal with either probability 0 or 1 . It thus suffices to condition on the event that a vector $\gamma_{*} \in \hat{V}$.
    ${ }^{23}$ The cutoffs $v^{l o}$ and $v^{u p}$ are the maximum and minimum of the set $\left\{x: x=\max _{\gamma \in F_{n}} \gamma^{\prime}\left(s+\frac{\tilde{\Sigma}_{n} \gamma_{*}}{\gamma_{*}^{\prime} \tilde{\Sigma}_{n} \gamma_{*}} x\right)\right\}$ when $\gamma_{*}^{\prime} \tilde{\Sigma}_{n} \gamma_{*} \neq 0$, where $F_{n}$ is the feasible set of the dual program (18). When $\gamma_{*}^{\prime} \tilde{\Sigma}_{n} \gamma_{*}=0$, we define $v^{l o}=-\infty$ and $v^{u p}=\infty$, so the conditional test rejects if and only if $\hat{\eta}>0$.
    ${ }^{24}$ This follows from the fact that the truncated normal distribution $\xi \mid \xi \in\left[v^{l o}, v^{u p}\right]$ has the monotone likelihood ratio property in it is mean (see, e.g. Lemma A. 1 in Lee, Sun, Sun and Taylor (2016)).

[^17]:    ${ }^{25}$ In particular, letting $B=B\left(\delta^{* *}\right)$ as defined in Assumption $5, c^{*}=-\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B, 1)} / \sigma_{B}$, where $\sigma_{B}=$ $\sqrt{\bar{\gamma}_{B}^{\prime} A_{(B, \cdot)} \Sigma^{*} A_{(B, \cdot)}^{\prime} \bar{\gamma}_{B}}$ and $\bar{\gamma}_{B}$ is a non-zero vector such that $\bar{\gamma}_{B}^{\prime} \tilde{A}_{(B,-1)}=0, \bar{\gamma}_{B} \geqslant 0$. The vector $\bar{\gamma}_{B}$ is unique up to scale.

[^18]:    ${ }^{26}$ The fact that the conditioning event becomes trivial asymptotically under Assumption 5 explains how the conditional test is able to approach the power envelope for all valid tests, not just conditional tests.

[^19]:    ${ }^{27}$ In concurrent work, Cox and Shi (2020) propose a new method for testing moment inequalities with nuisance paramaters, which like the ARP test is strongly insensitive to slack moments. It is thus possible that similar results could be obtained for their test as well.
    ${ }^{28}$ Indeed, in the supplementary material we prove a uniform version of the optimality result in Proposition 4.2 under a modified version of Assumption 5 that requires the non-binding moments to be uniformly bounded away from zero.

[^20]:    ${ }^{29}$ In practice, we set $\kappa=\alpha / 10$ following Romano et al. (2014) and ARP, although the optimal choice of $\kappa$ is an interesting question for future research.

[^21]:    ${ }^{30}$ Roth (2019) systematically reviewed the set of papers containing an event-study plot published in the American Economic Review, AEJ: Applied Economics and AEJ: Economic Policy between 2014 and mid2018. Section 4.1 of Roth (2019) discusses the sample selection criteria for this survey of published event studies.
    ${ }^{31}$ We focus on the normal simulations in the main text since it allows for a tractable computation of the optimal excess length of procedures that control size. In the supplementary material, we show that our procedures perform similarly in simulations based on the empirical distribution in the original paper.
    ${ }^{32}$ In the supplementary material, we provide simulation results in which the parameter of interest is the average causal effect in the post-periods $\left(\theta=\bar{\tau}_{\text {post }}\right)$, and find the results are qualitatively unchanged.
    ${ }^{33} \mathrm{~A}$ formula for this optimal bound is provided in the supplementary materials, and follows as a corollary from results in Armstrong and Kolesar (2018) on the optimal expected length of a confidence set satisfying the uniform coverage requirement.

[^22]:    ${ }^{34}$ The literature on staggered treatment timing considers generalizations of the parallel trends assumption that impose that untreated potential outcomes for each treated cohort move in parallel to those for some control group; possibilities for the control group include never-treated units, not-yet-treated units, or the last cohort to be treated. See, e.g., Assumption 2 of Callaway and Sant'Anna (2020) or Section 4.2 in Sun and Abraham (2020).

[^23]:    ${ }^{35}$ Formally, one can show that if $\mathcal{C}(M)$ satisfies (9) for $\Delta^{S D}(M)$, then the sample breakdown value, $\hat{M}_{B E}:=\inf \left\{M: \theta_{0} \in \mathcal{C}(M)\right\}$, is a valid $(1-\alpha)$-level lower bound for the population breakdown value, $M_{B E}:=\inf \left\{M: \theta_{0} \in \mathcal{S}\left(\Delta^{S D}(M), \beta\right)\right\}$. That is, $\mathbb{P}\left(\hat{M}_{B E} \leqslant M_{B E}\right) \geqslant 1-\alpha$.

[^24]:    ${ }^{36}$ Such an interval may be formed as follows: Let $\hat{\beta}$ placebo be the vector of estimated event-study coefficients for the placebo groups, and $\delta^{\text {placebo }}$ its expectation. We form a lower one-sided CI for $M^{\text {placebo }}:=\max _{j}\left(A^{S D} \delta^{\text {placebo }}\right)_{j}$, where $A^{S D}$ is the matrix that creates second differences. Letting $u b_{j}=\left(A^{S D} \hat{\beta}^{\text {placebo }}\right)_{j}+\sigma_{j} z_{1-\alpha}$ where $\sigma_{j}$ is the standard deviation of $\left(A^{S D} \hat{\beta}^{\text {placebo }}\right)_{j}$, define $u b:=\max _{j} u b_{j}$. Then $(-\infty, u b]$ is a level $(1-\alpha)$ CI for $M^{p l a c e b o . ~ P r o p e r ~ c o v e r a g e ~ o f ~ t h i s ~ C I ~ f o l l o w s ~ f r o m ~ r e s u l t s ~ b y ~ B e r g e r ~}$ and Hsu (1996) on the "union-intersection" approach.
    ${ }^{37}$ Relatedly, one might define $\Delta$ such that the largest non-linearity in $\delta$ in the post-treatment period is no larger than $M_{p r e}$, the largest non-linearity in $\delta$ in the pre-treatment period. Then, constructing a robust confidence set using $\Delta^{S D}\left(\hat{M}_{\text {pre }}\right)$, where $\hat{M}_{\text {pre }}$ is the upper bound of a $1-\alpha$ confidence interval for $M_{p r e}$, will have correct coverage over the imposed $\Delta$ at the $1-2 \alpha$ level.
    ${ }^{38}$ We can reject a value of $M$ if we reject the null hypothesis $H_{0}: \mathbb{E}\left[A^{S D} \hat{\beta}_{p r e}\right] \leqslant M$, where $A^{S D}$ is the matrix that produces the positive and negative second differences of $\hat{\beta}_{\text {pre }}$. This is a system of linear moment inequalities.

[^25]:    ${ }^{39} D_{s c,-11}$ is set to 1 if state $s$ passed a law 11 years or more after cohort $c$ turned 18. Likewise, $D_{s c, 21}$ is set to 1 if state $s$ passed a law 21 or more years before cohort $c$ turned 18.
    ${ }^{40}$ Treatment timing in LW is staggered, and therefore the results in Sun and Abraham (2020) imply that $\beta_{r}$ can be interpreted as a sensible weighted average of causal effects under parallel trends only if treatment effects are homogeneous across adoption cohorts. For simplicity, we focus on the robustness of the results to violations of parallel trends using the original specification in LW, which is valid under the assumption of homogeneous treatment effects. As discussed in Section 7.1, our sensitivity analysis can also be applied to estimators that are robust to treatment effect heterogeneity.

[^26]:    ${ }^{41}$ LW normalize event time -1 to 0 , but discuss how cohorts at event time -1 may have been partially treated, since LW impute the year that a student starts school with error. Since our robust confidence sets assume that there is no causal effect in the pre-period $\left(\tau_{p r e}=0\right)$, we instead treat event-time -2 as the reference period in our analysis.

[^27]:    ${ }^{42}$ Applying the definitions of $\tilde{A}$ and $\tilde{v}_{n}$, we obtain that $\tilde{v}_{n}^{\prime} \tilde{A}_{(\cdot, 1)}=v_{n, p o s t}^{\prime} \Gamma^{-1} e_{1}$. However, we show in the proof to Lemma B. 19 that $v_{n, p o s t}=l$, so $\tilde{v}_{n}^{\prime} \tilde{A}_{(\cdot, 1)}=l^{\prime} \Gamma^{-1} e_{1}$. The result then follows from the fact that $e_{1}^{\prime} \Gamma=l^{\prime}$ by construction.

[^28]:    ${ }^{43}$ The relative interior of a set is the interior of the set relative to its affine hull. See, e.g., Mau Nam (2019), Chapter 5.

