# Econ 2140, spring 2018, Part IIc Applications of Statistical Decision Theory

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#### Takeaways for this part of class

- In a Normal means model with Normal prior, there are a number of equivalent ways to think about regularization:
  - posterior mean,
  - penalized least squares (penalty corresponds to prior),
  - shrinkage, etc.
- Applied to linear regression: Ridge regression as penalized OLS with quadratic penalty.
- Alternatively, using an absolute value penalty: Lasso regression. (Popular in machine learning.)
- Hierarchical normal models yield the estimators used in the "value added" literature.

#### Roadmap

#### Normal posterior means - equivalent representations

**Ridge regression** 

Lasso regression

Value added models

Normal posterior means – equivalent representations

Normal posterior means – equivalent representations Setup

 $\bullet \ \theta \in \mathbb{R}^k$ 

• 
$$\boldsymbol{X}|\theta \sim N(\theta, I_k)$$

Loss

$$L(\widehat{\theta}, \theta) = \sum_{i} (\widehat{\theta}_{i} - \theta_{i})^{2}$$

Prior

 $heta \sim N(0,C)$ 

- Normal posterior means - equivalent representations

# 6 equivalent representations of the posterior mean

- 1. Minimizer of weighted average risk
- 2. Minimizer of posterior expected loss
- 3. Posterior expectation
- 4. Posterior best linear predictor
- 5. Penalized least squares estimator
- 6. Shrinkage estimator

-Normal posterior means - equivalent representations

# 1) Minimizer of weighted average risk

- Minimize weighted average risk (= Bayes risk),
- averaging loss  $L(\hat{\theta}, \theta) = (\hat{\theta} \theta)^2$  over both
  - 1. the sampling distribution  $f_{\boldsymbol{X}|\theta}$ , and
  - 2. weighting values of  $\theta$  using the decision weights (prior)  $\pi_{\theta}$ .

► Formally,

$$\widehat{\theta}(\cdot) = \operatorname*{argmin}_{t(\cdot)} \int E_{\theta}[L(t(\mathbf{X}), \theta)] d\pi(\theta).$$

-Normal posterior means - equivalent representations

# 2) Minimizer of posterior expected loss

- Minimize posterior expected loss,
- averaging loss  $L(\widehat{\theta}, \theta) = (\widehat{\theta} \theta)^2$  over

1. just the posterior distribution  $\pi_{\theta|\mathbf{X}}$ .

Formally,

$$\widehat{\theta}(x) = \operatorname*{argmin}_{t} \int L(t, \theta) d\pi_{\theta | \mathbf{X}}(\theta | x).$$

- Normal posterior means - equivalent representations

# 3 and 4) Posterior expectation and posterior best linear predictor

Note that

$$\begin{pmatrix} X \\ \theta \end{pmatrix} \sim N\left(0, \begin{pmatrix} C+I & C \\ C & C \end{pmatrix}\right).$$

Posterior expectation:

$$\widehat{\theta} = E[\theta | \mathbf{X}].$$

Posterior best linear predictor:

$$\widehat{\theta} = E^*[\theta | \mathbf{X}] = C \cdot (C+I)^{-1} \cdot \mathbf{X}.$$

Normal posterior means – equivalent representations

# 5) Penalization

Minimize

- 1. the sum of squared residuals,
- 2. plus a quadratic penalty term.

Formally,

$$\widehat{\theta} = \operatorname*{argmin}_{t} \sum_{i=1}^{n} (X_i - t_i)^2 + ||t||^2,$$

where

$$||t||^2 = t'C^{-1}t.$$

- Normal posterior means - equivalent representations

# 6) Shrinkage

- Diagonalize C: Find
  - 1. orthonormal matrix U of eigenvectors, and
  - 2. diagonal matrix D of eigenvalues, so that

C = UDU'.

Change of coordinates, using U:

 $\tilde{\mathbf{X}} = U'\mathbf{X}$  $\tilde{\mathbf{\theta}} = U'\mathbf{ heta}.$ 

Componentwise shrinkage in the new coordinates:

$$\widehat{\widetilde{\theta}}_i = \frac{d_i}{d_i + 1} \widetilde{X}_i. \tag{1}$$

Statistical Decision Theory

Normal posterior means – equivalent representations

Practice problem

Show that these 6 objects are all equivalent to each other.

- Normal posterior means - equivalent representations

# Solution (sketch)

- Minimizer of weighted average risk = minimizer of posterior expected loss: See decision slides.
- 2. Minimizer of posterior expected loss = posterior expectation:
  - First order condition for quadratic loss function,
  - pull derivative inside,
  - and switch order of integration.
- 3. Posterior expectation = posterior best linear predictor:
  - **X** and  $\theta$  are jointly Normal,
  - conditional expectations for multivariate Normals are linear.
- 4. Posterior expectation  $\Rightarrow$  penalized least squares:
  - ► Posterior is symmetric unimodal ⇒ posterior mean is posterior mode.
  - Posterior mode = maximizer of posterior log-likelihood = maximizer of joint log likelihood,
  - since denominator  $f_X$  does not depend on  $\theta$ .

- Normal posterior means - equivalent representations

#### Solution (sketch) continued

- 5. Penalized least squares  $\Rightarrow$  posterior expectation:
  - Any penalty of the form

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for A symmetric positive definite

corresponds to the log of a Normal prior

$$\theta \sim N(0, A^{-1}).$$

- 6. Componentwise shrinkage = posterior best linear predictor:
  - Change of coordinates turns  $\widehat{\theta} = C \cdot (C+I)^{-1} \cdot \mathbf{X}$  into

$$\widehat{\widetilde{\theta}} = D \cdot (D+I)^{-1} \cdot \boldsymbol{X}.$$

Diagonality implies

$$D\cdot (D+I)^{-1} = \operatorname{diag}\left(\frac{d_i}{d_i+1}\right).$$

- Ridge regression

# Normal prior for linear regression

- Normal linear regression model:
- Suppose we observe n i.i.d. draws of (Y<sub>i</sub>, X<sub>i</sub>), where Y<sub>i</sub> is real valued and X<sub>i</sub> is a k vector.
- $\flat \quad Y_i = X_i \cdot \beta + \varepsilon_i$
- $\varepsilon_i | \boldsymbol{X}, \boldsymbol{\beta} \sim N(0, \sigma^2)$
- $\beta | \mathbf{X} \sim N(0, \Omega)$  (prior)
- ► Note: will leave conditioning on **X** implicit in following slides.

Ridge regression

#### Practice problem ("weight space view")

- Find the posterior expectation of β
- Hints:
  - 1. The posterior expectation is the maximum a posteriori.
  - 2. The log likelihood takes a penalized least squares form.
- Find the posterior expectation of x · β for some (non-random) point x.

Ridge regression

## Solution

• Joint log likelihood of  $Y, \beta$ :

$$\log(f_{\boldsymbol{Y}\beta}) = \log(f_{\boldsymbol{Y}|\beta}) + \log(f_{\beta})$$
$$= const. - \frac{1}{2\sigma^2} \sum_{i} (Y_i - X_i\beta)^2 - \frac{1}{2}\beta'\Omega^{-1}\beta.$$

First order condition for maximum a posteriori:

$$0 = \frac{\partial f_{\mathbf{Y}\beta}}{\partial \beta} = \frac{1}{\sigma^2} \sum_{i} (Y_i - X_i \beta) \cdot X_i - \beta' \Omega^{-1}.$$
  
$$\Rightarrow \quad \widehat{\beta} = \left( \sum_{i} X_i' X_i + \sigma^2 \Omega^{-1} \right)^{-1} \cdot \sum X_i' Y_i.$$

Thus

$$E[x \cdot \beta | \mathbf{Y}] = x \cdot \widehat{\beta} = x \cdot (\mathbf{X}' \mathbf{X} + \sigma^2 \Omega^{-1})^{-1} \cdot \mathbf{X}' \mathbf{Y}.$$

- Previous derivation required inverting  $k \times k$  matrix.
- Can instead do prediction inverting an  $n \times n$  matrix.
- n might be smaller than k if there are many "features."
- This will lead to a "function space view" of prediction.

#### Practice problem ("kernel trick")

Find the posterior expectation of

$$f(x) = E[Y|X = x] = x \cdot \beta.$$

- Wait, didn't we just do that?
- Hints:
  - 1. Start by figuring out the variance / covariance matrix of  $(x \cdot \beta, \mathbf{Y})$ .
  - 2. Then deduce the best linear predictor of  $x \cdot \beta$  given **Y**.

# Solution

• The joint distribution of  $(x \cdot \beta, \mathbf{Y})$  is given by

$$\begin{pmatrix} \boldsymbol{x} \cdot \boldsymbol{\beta} \\ \boldsymbol{Y} \end{pmatrix} \sim N \left( \boldsymbol{0}, \begin{pmatrix} \boldsymbol{x} \Omega \boldsymbol{x}' & \boldsymbol{x} \Omega \boldsymbol{X}' \\ \boldsymbol{X} \Omega \boldsymbol{x}' & \boldsymbol{X} \Omega \boldsymbol{X}' + \sigma^2 \boldsymbol{I}_n \end{pmatrix} \right)$$

• Denote 
$$C = X\Omega X'$$
 and  $c(x) = x\Omega X'$ .

Then

$$E[x \cdot \beta | \mathbf{Y}] = c(x) \cdot (C + \sigma^2 I_n)^{-1} \cdot \mathbf{Y}.$$

Contrast with previous representation:

$$E[x \cdot \beta | \mathbf{Y}] = x \cdot (\mathbf{X}' \mathbf{X} + \sigma^2 \Omega^{-1})^{-1} \cdot \mathbf{X}' \mathbf{Y}.$$

-Lasso regression

#### Lasso regression

Ridge regression as penalization: Assume Var(β) = I, denote σ<sup>2</sup> = λ and ||β||<sup>2</sup><sub>2</sub> = β' ⋅ β. Then

$$\widehat{eta} = \mathop{\mathrm{argmin}}_{eta} \sum_i (Y_i - X_ieta)^2 + \lambda \|eta\|_2^2,$$

- Could consider alternative penalties.
- For instance:  $\|\beta\|_1 = \sum_j |\beta_j|$ .
- This yields Lasso regression:

$$\widehat{eta} = \operatorname*{argmin}_{eta} \sum_{i} (Y_i - X_i eta)^2 + \lambda \|eta\|_1.$$

-Lasso regression

# Lasso, simplified setting

- Consider again the normal means setting, as before, where  $X | \theta \sim N(\theta, I_k)$ .
- ► Let  $\widehat{\theta} = \underset{t}{\operatorname{argmin}} \sum_{i=1}^{n} (X_i - t_i)^2 + 2\lambda \|t\|_1.$

#### Practice problem

Derive an explicit formula for  $\widehat{\theta}$ 

- Lasso regression

## Solution

We can treat each component separately:

$$\widehat{ heta}_i = \operatorname*{argmin}_{t_i} \frac{1}{2} (X_i - t_i)^2 + \lambda |t_i|.$$

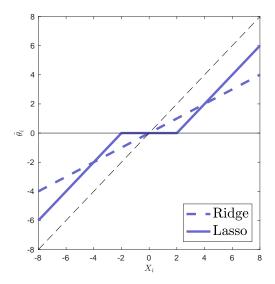
Sub-derivative of objective function:

$$\frac{\partial}{\partial t_i} = -(X_i - t_i) + \begin{cases} -1 & t_i < 0\\ 0 & t_i = 0\\ 1 & t_i < 0. \end{cases}$$

Solution to optimization problem (first order condition):

$$\widehat{ heta}_i = egin{cases} X_i + \lambda & X_i < -\lambda \ 0 & -\lambda < X_i < \lambda \ X_i - \lambda & \lambda < X_i. \end{cases}$$

Lasso regression



# Comparing methods of regularized regression

- Abadie and Kasy (2017): compare the risk of alternative regularization methods.
- No one method that's always optimal!

#### Neighborhood effects:

The effect of location during childhood on adult income (Chetty and Hendren, 2015)

#### Arms trading event study:

Changes in the stock prices of arms manufacturers following changes in the intensity of conflicts in countries under arms trade embargoes (DellaVigna and La Ferrara, 2010)

#### Nonparametric Mincer equation:

A nonparametric regression equation of log wages on education and potential experience (Belloni and Chernozhukov, 2011)

# **Estimated Risk**

- Estimated risk  $\widehat{R}$  at the optimized tuning parameter  $\widehat{\lambda}^*$
- for each application and estimator considered.

	n		Ridge	Lasso	Pre-test
location effects	595	Ŕ	0.29	0.32	0.41
		$\widehat{\lambda}^*$	2.44	1.34	5.00
arms trade	214	R	0.50	0.06	-0.02
		$\widehat{\lambda}^*$	0.98	1.50	2.38
returns to education	65	R	1.00	0.84	0.93
		$\widehat{\lambda}^*$	0.01	0.59	1.14

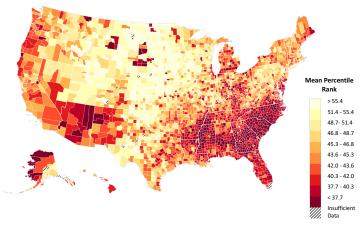
## Value added models

- Chetty, R. and N. Hendren (2015). The impacts of neighborhoods on intergenerational mobility: Childhood exposure effects and county-level estimates. *Working Paper.*
- We are interested in the causal impact θ<sub>i</sub> of cities i on intergenerational mobility.
- Suppose that for each city we have
  - a noisy but unbiased estimate  $Y_i$  of  $\theta_i$ , with known standard error  $\sigma_i$ ,
  - and a biased but less noisy estimate X<sub>i</sub>.
- Suppose that estimates and parameters are jointly normally distributed,

$$egin{aligned} &Y_i| heta_i,\sigma_i,X_i\sim \mathcal{N}( heta_i,\sigma_i^2)\ &( heta_i,X_i)|\sigma_i\sim \mathcal{N}((ar{ heta},ar{X}),\Sigma). \end{aligned}$$

- Value added models

The Geography of Intergenerational Mobility in the United States Predicted Income Rank at Age 30 for Children with Parents at 25<sup>th</sup> Percentile



What is the Average Causal Impact of Growing Up in place with Better Outcomes?

- Value added models

#### Practice problem

- Suppose you know  $\Sigma$  and observe a draw of  $(Y_i, X_i, \sigma_i)$ .
- What is the joint distribution of  $Y_i, X_i$  and  $\theta_i$ ?
- What is the posterior expectation of θ<sub>i</sub>?

## Solution

• Joint distribution of  $Y_i, X_i$  and  $\theta_i$ :

$$(\theta_i, Y_i, X_i) | \sigma_i \sim N\left(\begin{pmatrix} \bar{\theta} \\ \bar{\theta} \\ \bar{X} \end{pmatrix}, \begin{pmatrix} \Sigma_{11} & \Sigma_{11} & \Sigma_{12} \\ \Sigma_{11} & \Sigma_{11} + \sigma_i^2 & \Sigma_{12} \\ \Sigma_{12} & \Sigma_{12} & \Sigma_{22} \end{pmatrix}\right)$$

• Posterior expectation of  $\theta_i$  = best linear predictor,

$$\begin{aligned} \widehat{\theta}_i &= E[\theta_i | Y_i, X_i, \sigma_i] \\ &= E[\theta_i] + \operatorname{Cov}(\theta_i, (Y_i, X_i)) \cdot \operatorname{Var}(Y_i, X_i)^{-1} \cdot ((Y_i, X_i) - E[(Y_i, X_i)]) \\ &= \overline{\theta} + (\Sigma_{11}, \Sigma_{12}) \cdot \begin{pmatrix} \Sigma_{11} + \sigma_i^2 & \Sigma_{12} \\ \Sigma_{12} & \Sigma_{22} \end{pmatrix}^{-1} \cdot ((Y_i, X_i) - (\overline{\theta}, \overline{X})) \end{aligned}$$

- Value added models

#### **Practice problem**

Suppose you observe i.i.d. draws of  $(Y_i, X_i, \sigma_i)$ . What is your estimate of  $(\bar{\theta}, \bar{X})$  and of  $\Sigma$ ?

- Value added models

## Solution

As shown before,

$$E[(Y_i, X_i)] = (\bar{\theta}, \bar{X}),$$
$$Var(Y_i, X_i) | \sigma_i = \begin{pmatrix} \Sigma_{11} + \sigma_i^2 & \Sigma_{12} \\ \Sigma_{12} & \Sigma_{22} \end{pmatrix},$$

$$\widehat{\Sigma} = \frac{1}{n-1} \sum_{i} \begin{pmatrix} (Y_i - \bar{Y})^2 - \sigma_i^2 & (Y_i - \bar{Y})(X_i - \bar{X}) \\ (Y_i - \bar{Y})(X_i - \bar{X}) & (X_i - \bar{X})^2 \end{pmatrix}.$$